1. Determine if each of the following are valid autocorrelation matrices of WSS processes. (Correlation Matrix)

$$\boldsymbol{R}_a = \begin{bmatrix} 4 & 1 & 1 \\ -1 & 4 & 1 \\ -1 & -1 & 4 \end{bmatrix}, \boldsymbol{R}_b = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix}, \boldsymbol{R}_c = \begin{bmatrix} 2j & 0 & j \\ 0 & 2j & 0 \\ -j & 0 & 2j \end{bmatrix}, \boldsymbol{R}_d = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}.$$

2. Consider the random process $y(n) = x(n) + v(n)$, where $x(n) = Ae^{j(\omega n + \phi)}$ and $v(n)$ is zero mean white Gaussian noise with a variance σ_v^2. We also assume the noise and the complex sinusoid are independent. Under the following conditions, determine if $y(n)$ is WSS. Justify your answers. (WSS Process)

(a) ω and A are constants, and ϕ is a uniformly distributed over the interval $[0, 2\pi]$.

(b) ω and ϕ are constants, and A is a Gaussian random variable $\sim \mathcal{N}(0, \sigma_A^2)$.

(c) ϕ and A are constants, and ω is a uniformly distributed over the interval $[\omega_0 - \Delta, \omega_0 + \Delta]$ for some fixed Δ.

3. [Rec.II P2(a) revisited] Determine the PSD of the WSS process $y(n) = Ae^{j(\omega_0 n + \phi)} + v(n)$, where $v(n)$ is zero mean white Gaussian noise with a variance σ_v^2, and ϕ is uniformly distributed over the interval $[0, 2\pi]$. (Power Spectral Density)

4. Assume $v(n)$ is a white Gaussian random process with zero mean and variance 1. The two filters in Fig. RII.4 are $G(z) = \frac{1}{1-0.4z^{-1}}$ and $H(z) = \frac{2}{1-0.5z^{-1}}$. (Auto-Regressive Process)

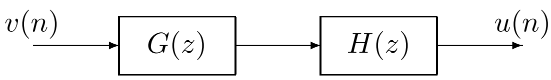

Figure RII.4:

(a) Is $u(n)$ an AR process? If so, find the parameters.

(b) Find the autocorrelation coefficients $r_u(0)$, $r_u(1)$, and $r_u(2)$ of the process $u(n)$.

5. Let a real-valued AR(2) process be described by

$$u(n) = x(n) + a_1 x(n-1) + a_2 x(n-2)$$

where $u(n)$ is a white noise of zero-mean and variance σ^2, and $u(n)$ and past values $x(n-1)$, $x(n-2)$ are uncorrelated. (Yule-Walker Equation)

(a) Determine and solve the Yule-Walker Equations for the AR process.

(b) Find the variance of the process $x(n)$.

6. [Problem 5.3 continued] Assume $v(n)$ and $w(n)$ are white Gaussian random processes with zero mean and variance 1. The two filters in Fig. RII.6 are $G(z) = \frac{1}{1-0.4z^{-1}}$ and $H(z) = \frac{2}{1-0.5z^{-1}}$. (Wiener Filter)

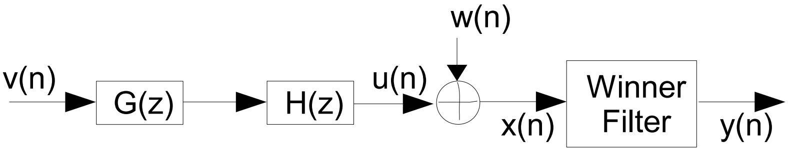

Figure RII.6:

(a) Design a 1-order Wiener filter such that the desired output is $u(n)$. What is the MSE?

(b) Design a 2-order Wiener filter. What is the MSE?

7. The autocorrelation sequence of a given zero-mean real-valued random process $u(n)$ is $r(0) = 1.25$, $r(1) = r(-1) = 0.5$, and $r(k) = 0$ for any $|k| \geq 2$. (Wiener Filter)

(a) What model fits this process best: AR or MA? Find the corresponding parameters.

(b) Design the Wiener filter when using $u(n)$ to predict $u(n+1)$. Can we do better (in terms of MSE) if we use both $u(n)$ and $u(n-1)$ as the input to the Wiener filter? What if using $u(n)$ and $u(n-2)$?

8. Consider the MIMO (multi-input multi-output) wireless communications system shown in Fig. RII.8. There are two antennas at the transmitter and three antennas at the receiver. Assume the channel gain from the i-th transmit antenna to the j-th receive antenna is h_{ji}. Take a snapshot at time slot n, the received signal is $y_j(n) = h_{j1}x_1(n) + h_{j2}x_2(n) + v_j(n)$ where $v_j(n)$ are white Gaussian noise (zero mean, variance N_0) independent of signals. We further assume $x_1(n)$ and $x_2(n)$ are uncorrelated, and their power are P_1 and P_2, respectively. Use $y_1(n), y_2(n)$ and $y_3(n)$ as input, find the optimal Wiener filter to estimate $x_1(n)$ and $x_2(n)$. (Wiener Filter)

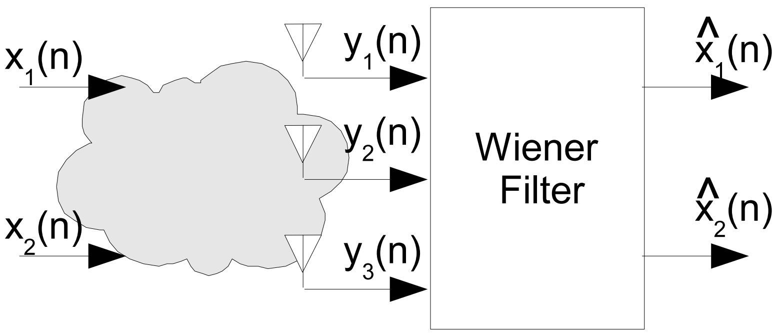

Figure RII.8:

9. Given an real-valued AR(3) model with parameters $\Gamma_1 = -4/5$, $\Gamma_2 = 1/9$, $\Gamma_3 = 1/8$, and $r(0) = 1$. Find $r(1), r(2)$, and $r(3)$. (Levinson-Durbin Recursion)

10. Consider the MA(1) process $x(n) = v(n) + bv(n-1)$ with $v(n)$ being a zero-mean white sequence with variance 1. If we use Γ_k to represent this system, prove that (Levinson-Durbin Recursion)

$$\Gamma_{m+1} = \frac{\Gamma_m^2}{\Gamma_{m-1}(1 - |\Gamma_m|^2)}.$$

11. Given a p-order AR random process $\{x(n)\}$, it can be equivalently represented by any of the three following sets of values: (Levinson-Durbin Recursion)

- $\{r(0), r(1), \ldots, r(p)\}$
- $\{a_1, a_2, \ldots, a_p\}$ and $r(0)$
- $\{\Gamma_1, \Gamma_2, \ldots, \Gamma_p\}$ and $r(0)$

(a) If a new random process is defined as $x'(n) = cx(n)$ where c is a real-valued constant, what will be the new autocorrelation sequence $r'(k)$ in terms of $r(k)$ (for $k = 1, 2, \ldots, p$)? How about a'_k and Γ'_k?

(b) Let a new random process be defined as $x'(n) = (-1)^n x(n)$. Prove that $r'(k) = (-1)^k r(k)$, $a'_k = (-1)^k a_k$ and $\Gamma'_k = (-1)^k \Gamma_k$. (Hint: use induction when proving Γ_k, since Γ_k is calculated recursively.)

12. Given a lattice predictor that simultaneously generate both forward and backward prediction errors $f_m(n)$ and $b_m(n)$ ($m = 1, 2, \ldots, M$). (Lattice Structure)

(a) Find $E(f_m(n) b_i^*(n))$ for both conditions when $i \leq m$ and $i > m$.

(b) Find $E(f_m(n+m) f_i^*(n+i))$ for both conditions when $i = m$ and $i < m$.

(c) Design a joint process estimation scheme using the forward prediction errors.

(d) If for some reason we can only obtain part of forward prediction error (from order 0 to order k) and part of backward prediction error (from oder $k+1$ to order M), i.e., we have $\{f_0(n), f_1(n), \ldots, f_k(n), b_{k+1}(n), b_{k+2}(n), \ldots, b_M(n)\}$. Describe how to use such mixed forward and backward prediction errors to perform joint process estimation.

(Hint: the results from (a) and (b) will be useful for questions (c) and (d).)

13. Consider the backward prediction error sequence $b_0(n), b_1(n), \ldots, b_M(n)$ for the observed sequence $\{u(n)\}$. (Properties of FLP and BLP Errors)

(a) Define $\boldsymbol{b}(n) = [b_0(n), b_1(n), \ldots, b_M(n)]^T$, and $\boldsymbol{u}(n) = [u(n), u(n-1), \ldots, u(n-M)]^T$, find $\boldsymbol{L}$ in terms of the coefficients of the backward prediction-error filter where $\boldsymbol{b}(n) = \boldsymbol{L}\boldsymbol{u}(n)$.

(b) Let the correlation matrix for $\boldsymbol{b}(n)$ be $\boldsymbol{D}$, and that for $\boldsymbol{u}(n)$ be $\boldsymbol{R}$. Is $\boldsymbol{D}$ diagonal? What is relation between $\boldsymbol{R}$ and $\boldsymbol{D}$? Show that a lower triangular matrix $\boldsymbol{A}$ exists such that $\boldsymbol{R}^{-1} = \boldsymbol{A}^H\boldsymbol{A}$.

(c) Now we are to perform joint estimation of a desired sequence $\{d(n)\}$ by using either $\{b_k(n)\}$ or $\{u(n)\}$, and their corresponding optimal weight vectors are $\boldsymbol{k}$ and $\boldsymbol{w}$, respectively. What is relation between $\boldsymbol{k}$ and $\boldsymbol{w}$?