

solutions ETPE 610 final Fall 2018

$$\#1. \quad y(s) = \frac{(s^2+1)(s^2+a)}{s(s^2+2)(s^2+b)} = \frac{k_0}{s} + \frac{k_1 s}{s^2+2} + \frac{k_2 s}{s^2+b} = \frac{a}{2b} + \frac{1}{2} \left(\frac{a-2}{b-2} \right) s + \frac{(b-1) \left(\frac{a-b}{2-b} \right) s}{s^2+b}$$

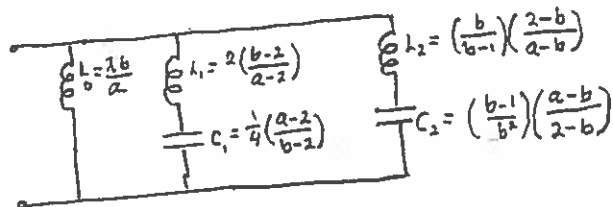
$$k_0 = y(s) \times s \Big|_{s=0} = \frac{(s^2+1)(s^2+a)}{(s^2+2)(s^2+b)} \Big|_{s=0} = \frac{(1)(a)}{(2)(b)} = \frac{a}{2b}$$

$$k_1 = y(s) \times \frac{(s^2+2)}{s} \Big|_{s^2=-2} = \frac{(s^2+1)(s^2+a)}{s^2(s^2+b)} \Big|_{s^2=-2} = \frac{(-1)(a-2)}{(-2)(b-2)} = \frac{1}{2} \left(\frac{a-2}{b-2} \right)$$

$$k_2 = y(s) \times \frac{(s^2+b)}{s} \Big|_{s^2=-b} = \frac{(s^2+1)(s^2+a)}{s^2(s^2+2)} \Big|_{s^2=-b} = \frac{(1-b) \left(\frac{a-b}{2-b} \right)}{(-b)} = \left(\frac{b-1}{b} \right) \left(\frac{a-b}{2-b} \right)$$

This requires poles and zeroes to alternate thus 2 on $j\omega$ axis ($a, b \geq 0$)
 $\therefore 0 \leq a < b < 1, 2 \leq a < b$ or $0 \leq a = b$ real

The generic circuit is



which resolves when $a=2$ or $a=b$ or $b=1$ with $0 \leq a \leq 2$

$\therefore P(s) = E_v P + O_d P = (2s^6 + 9s^4 + 12s^2 + 4) + (s^7 + 6s^5 + 12s^3 + 8s)$

choose: $g(s) = \frac{O_d P}{E_v P} \Rightarrow$ continued fraction about ∞

$$\begin{array}{r} 2s^6 + 9s^4 + 12s^2 + 4 \quad \Big| \quad \frac{1}{2}s \\ \hline 2s^7 + 6s^5 + 12s^3 + 8s \\ \hline \frac{12s^4}{2} = 6s^4 + 6s^2 + 6s \\ \hline 2s^6 + 9s^4 + 12s^2 + 4 \\ \hline 2s^6 + 8s^4 + 8s^2 \\ \hline s^4 + 4s^2 + 4 \\ \hline \frac{3}{2}s \\ \hline \frac{3}{2}s^5 + 6s^3 + 6s \\ \hline 0 \quad 0 \quad 0 \end{array}$$

\therefore there is a common factor in $E_v P$ & $O_d P$

to find

$$\frac{O_d P}{E_v P} = \frac{\frac{1}{2}s + \frac{1}{\frac{4}{3}s + \frac{1}{\frac{3}{2}s}}}{\frac{1}{2}s + \frac{1}{2s^2 + 1}} = \frac{\frac{1}{2}s + \frac{3}{2}s}{2s^2 + 1} = \frac{s^3 + \frac{1}{2}s + \frac{3}{2}s}{2s^2 + 1}$$

$$= \frac{s^3 + 2s}{2s^2 + 1} \Rightarrow P_1 = E_v P_1 + O_d P_1 = (2s^2 + 1) + (s^3 + 2s) = s^3 + 2s^2 + 2s + 1$$

and $P = P_1 \cdot Q$, $Q =$ common factor $\Rightarrow Q = \frac{P}{P_1}$, divide P by P_1

$$\begin{array}{r} s^3 + 2s^2 + 2s + 1 \quad \Big| \quad \frac{s^4 + 4s^2 + 4}{s^7 + 2s^6 + 6s^5 + 9s^4 + 12s^3 + 12s^2 + 8s + 4} \\ \hline s^7 + 2s^6 + 2s^5 + s^4 \\ \hline 4s^5 + 8s^4 + 12s^3 + 12s^2 + 8s + 4 \\ \hline 4s^5 + 8s^4 + 8s^3 + 4s^2 \\ \hline 4s^3 + 8s^2 + 8s + 4 \\ \hline 4s^3 + 8s^2 + 8s + 4 \\ \hline 0 \end{array} \Rightarrow Q = \frac{s^4 + 4s^2 + 4}{(s^2 + 2)^2}$$

$\therefore P(s) = \left(\begin{smallmatrix} \text{Hurwitz} \\ \text{cont. in LFR} \end{smallmatrix} \right) \times \left(\begin{smallmatrix} \text{double zero} \\ \text{on } j\omega \text{ axis} \end{smallmatrix} \right)$

$(s^2 + 2)^2 \Rightarrow$ unstable $\Rightarrow P(s)$ is not Hurwitz (or strictly Hurwitz)

#3. a)
$$\begin{bmatrix} -m_v & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ -m_i & 1 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} \equiv Av = Bi \quad \text{as } \det A = \det B = 0$$

 nor $y = B^{-1}A$ or $Z = A^{-1}B$ exists, all real m_v, m_i

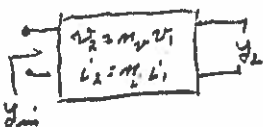
Then $S = (B+A)^{-1}(B-A) = \begin{bmatrix} -m_v & 1 \\ -m_i & 1 \end{bmatrix}^{-1} \begin{bmatrix} m_v & -1 \\ -m_i & 1 \end{bmatrix} = \frac{1}{m_i - m_v} \begin{bmatrix} 1 & -1 \\ m_i & -m_v \end{bmatrix} \begin{bmatrix} m_v - 1 \\ -m_i & 1 \end{bmatrix} = \frac{1}{m_i - m_v} \begin{bmatrix} -(m_v + m_i) - 2 \\ 2m_v m_i & -(m_v + m_i) \end{bmatrix}$

which exists for all m_v & m_i , except when $m_i = m_v$

b) This is measure of $E(t) = \int_{-\infty}^t p(\tau) d\tau \geq 0$ where $p(t) = v^T(t) i(t)$

here $p(t) = v_1 i_1 + v_2 i_2 = v_1 i_1 + m_v m_i v_1 i_1 = (1 + m_v m_i) v_1 i_1$

as v_1 & i_1 are arbitrary they can have sign $(v_1 i_1) = -\text{sign}(1 + m_v m_i)$ except when $1 + m_v m_i = 0$ in which case $E(t)$ can be < 0 unless $m_v m_i = -1$ when $E(t) = 0$. Therefore the 2-port is passive and lossless only when $m_i = -1/m_v$ (which is an ideal transformer)

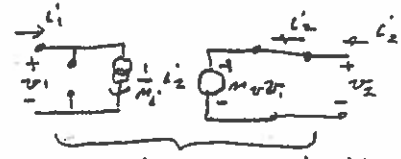
c) 
$$y_{in} = \frac{i_1}{v_1} = \frac{(1/m_v) i_2}{(1/m_i) v_2} = \frac{m_v}{m_i} \left(\frac{-i_2}{v_2} \right) = -\frac{m_v}{m_i} y_L = y_{in}$$

If m_v & m_i have the same sign y_{in} is the scaled negative of y_L & the 2-port is a negative impedance converter. If the 2-port is passive it is a transformer & $y_{in} = (m_v)^2 y_L$

d) $v_2 = m_v v_1$ is a VCVS & $i_2 = m_i i_1$ is a CCCS, better as $i_1 = \frac{1}{m_i} i_2$

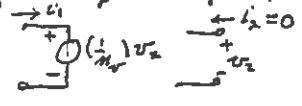


Using the latter form of $i_1 = \frac{1}{m_i} i_2$ allows the connection if $m_i \neq 0$

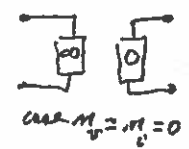


2-port $v_2 = m_v v_1, i_1 = (\frac{1}{m_i}) i_2$ (which holds if $m_i \neq 0, m_v = 0$)

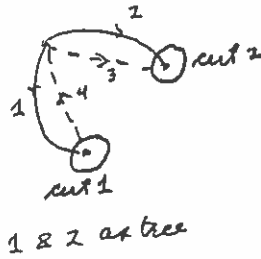
If $m_i = 0$ then $i_2 = 0$ and i_1 can be in a short requiring use of $v_1 = (\frac{1}{m_v}) v_2$



If m_i & $m_v = 0$ we have $v_2 = i_2 = 0$ & v_1 & i_1 arbitrary or a nullator @ port 2 & a norator @ port 1



#4 a)



Cut set

$$\begin{matrix} \text{cut 1} \\ \text{cut 2} \end{matrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{matrix} \text{KCL} \\ \text{KCL} \end{matrix} \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \\ i_4 \end{bmatrix} \equiv \mathbf{C}_1 = \mathbf{C} i_b$$

$$\Rightarrow \mathbf{C}_1 = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

The set

$$\begin{matrix} \text{link 3} \\ \text{link 4} \end{matrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{matrix} \text{KVL} \\ \text{KVL} \end{matrix} \begin{bmatrix} 0 & -1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} \equiv \mathbf{Q}_1 = \mathcal{Q} v_b$$

$$\Rightarrow \mathcal{Q}_1 = \begin{bmatrix} 0 & -1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix}$$

b) 3 & 4 as tree

$$\begin{matrix} \text{cut 1} \\ \text{cut 2} \end{matrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{matrix} \text{KCL} \\ \text{KCL} \end{matrix} \begin{bmatrix} 0 & 1 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix} i_b \Rightarrow \mathbf{C}_2 = \begin{bmatrix} 0 & 1 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{matrix} \text{link 1} \\ \text{link 2} \end{matrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{matrix} \text{KVL} \\ \text{KVL} \end{matrix} \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & -1 & 0 \end{bmatrix} v_b \Rightarrow \mathcal{Q}_2 = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & -1 & 0 \end{bmatrix}$$

c) $\mathbf{C}_2 = \mathbf{R}_c \mathbf{C}_1 \Rightarrow \begin{bmatrix} 0 & 1 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} r_{11} & r_{12} \\ r_{21} & r_{22} \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$

\mathbf{R}_c multiplies row 1 by -1 & then permutes rows

$$\therefore \mathbf{R}_c = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

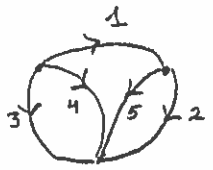
or $\mathcal{Q}_2 = \mathbf{R}_t \mathcal{Q}_1 = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & -1 & 0 \end{bmatrix} = \begin{bmatrix} \Downarrow \\ \Downarrow \end{bmatrix} \begin{bmatrix} 0 & -1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix}$

row 1 $\times (-1)$
then permute rows

$$\Rightarrow \mathbf{R}_t = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \equiv \mathbf{R}_c$$

#5.

Graph



tree: 1, 2, 3
links: 4, 5

Cutset $\begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 & 1 \end{bmatrix} i_b$; $v_b = C^T v_e$

Tree cut $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 & -1 & 1 & 0 & 0 \\ -1 & -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 & 1 \end{bmatrix} v_b$; $i_b = \sigma^T i_e$

$Av = Bi'$
 $\begin{bmatrix} \alpha C_1 & 0 & 0 & 0 & 0 \\ 0 & \alpha C_2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & g \\ 0 & 0 & 0 & -g & 0 \end{bmatrix} v = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} i'$

$e = \begin{bmatrix} 0 \\ 0 \\ e_3 \\ 0 \\ 0 \end{bmatrix}$, $i = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$

$v_b = v + e$, $i_b = i + j = i'$
 \Downarrow
 $v = v_b - e$, $i = \sigma^T i_e \Rightarrow A C^T v_e - A e = B \sigma^T i_e \Rightarrow A C^T v_e - B \sigma^T i_e = A e$
 $= e^T v_e - e$

$A C^T = \begin{bmatrix} \alpha C_1 & & & & \\ & \alpha C_2 & & & \\ & & 1 & & \\ & & 0 & g & \\ & & -g & 0 & \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \alpha C_1 & 0 \\ 0 & \alpha C_2 \\ 1 & 1 \\ 0 & g \\ -g & 0 \end{bmatrix}$, $B \sigma^T = \begin{bmatrix} 1 & & & & \\ & 1 & & & \\ & & 0 & & \\ & & & 1 & \\ & & & & 1 \end{bmatrix} \begin{bmatrix} -1 & -1 & 0 \\ -1 & -1 & -1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -1 & -1 & 0 \\ -1 & -1 & -1 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$A e = \begin{bmatrix} \alpha C_1 & & & & \\ & \alpha C_2 & & & \\ & & 1 & & \\ & & 0 & g & \\ & & -g & 0 & \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ e_3 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ e_3 \\ 0 \\ 0 \end{bmatrix}$, $i = \begin{bmatrix} i_1 \\ i_2 \\ i_3 \\ i_4 \\ i_5 \end{bmatrix} \Rightarrow [A C^T - B \sigma^T] \begin{bmatrix} v_1 \\ v_2 \\ i_3 \\ i_4 \\ i_5 \end{bmatrix} = A e$

$\therefore \begin{bmatrix} \alpha C_1 & 0 & 0 & 0 & 0 \\ 0 & \alpha C_2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} x = \begin{bmatrix} 0 & 0 & -1 & -1 & 0 \\ 0 & 0 & -1 & -1 & -1 \\ -1 & -1 & 0 & 0 & 0 \\ 0 & -g & 0 & 1 & 0 \\ g & g & 0 & 0 & 1 \end{bmatrix} x + \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} e_3 \Rightarrow A E x = A x + B e_3$

as $y = v_2 \Rightarrow v_{e_2} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \end{bmatrix} x$

b) $y_{2-port} = \begin{bmatrix} \alpha C_1 & -\alpha C_1 + g \\ -\alpha C_1 - g & \alpha C_1 \end{bmatrix} \Rightarrow y_{in} = y_{11} - y_{12} \cdot \frac{1}{y_{22} + y_L} \cdot y_{21} = \frac{y_{11} y_L + \det y}{y_{22} + y_L} = (\alpha C_1 + \alpha C_2 + g^2) / (\alpha C_1 + \alpha C_2)$

$v_{C_2} / i_3 = -g_{21} / (y_{21} + y_{22}) = \frac{-(-\alpha C_1 - g)}{\alpha C_1 + \alpha C_2}$ from $i_2 = -y_L v_2 = y_{21} v_1 + y_{22} v_2$

c) For the semistate eqs. need to calculate $v_2 = v_{e_2} = C(AE - A)^{-1} B e_3$ along with finding $A E x = A x + B u$ & $y = C x$ for just the voltage gain, so using 2-port directly is much simpler though less general