

Richard's function

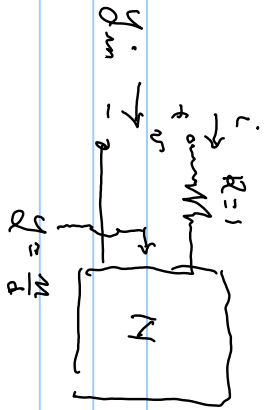
$$y_i(s) = y_i(s) \left[\frac{R y_i(s) - A y_i(s)}{R y_i(s) - A y_i(s)} \right]$$

Polynomials: $P(s) = \sum_{i=0}^{\delta} a_i \cdot s^i$ $\delta = \text{degree}$

Thurswity: not zero in $\sigma > 0$, $R = \sigma + j\omega$ } stable system
 & only singular on $\sigma = 0$ (jw axis) } if imaginary axis
 will satisfy Thurswity

For $P(s) = \frac{1}{2} (P(s) + P(-s))$ (removes s^{2n+1} terms)

$\Rightarrow \mathcal{O}d P(s) = \frac{1}{2} (P(s) - P(-s)) \Rightarrow \mathcal{E}o P(s) + \mathcal{O}d P(s) = P(s)$



$$y_{in} = \frac{1}{1 + \underbrace{y}_{\frac{1}{1 + \frac{m(s)}{d(s)}}}} = \frac{d(s)}{m(s) + d(s)}$$

$$c = y_{in} \Rightarrow i = \frac{d(s)}{m(s) + d(s)} \cdot v \approx \frac{d(s)}{d(s)} \cdot v \quad \text{if } v = 0 \Rightarrow P(s) = 0 \text{ can give } (input = 0) \text{ nonzeros } i(s)$$

\Rightarrow zeroes of $P(s) = m(s) + d(s)$ are short circuit natural frequencies

if N is lossless then $y = LPR = \frac{m}{d}$ no even/odd or odd/even

$\Rightarrow R$ requires $P(s) = m + d$ to be of unity $P(s) = \sum_{\text{ev}} P(s) + \sum_{\text{od}} P(s) = \sum_{\text{ev}} P(s) \left[1 + \frac{\text{od}}{\text{ev}} P(s) \right]$

\therefore given a polynomial $P(s)$ form $y(s) = \frac{\text{od}P}{\text{ev}P}$ & if this is LPR then

$P(s)$ is Hurwitz except for common even polynomials which can factor out of $y(s)$

$$P(s) = s^4 + 2s^3 + 3s^2 + 2s + 1 = (s^4 + 3s^2 + 1) + (2s^3 + 2s) = (s^4 + 3s^2 + 1) + s(2s^2 + 2)$$

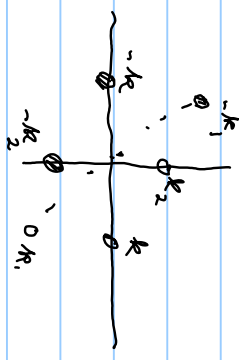
$$= (s^4 + 3s^2 + 1) \left[1 + \frac{2s^3 + 2s}{s^4 + 3s^2 + 1} \right]$$

24 $g_c(s) = \frac{2s^3 + 2s}{s^4 + 3s^2 + 1}$ an LPR function \Rightarrow try 1st cases

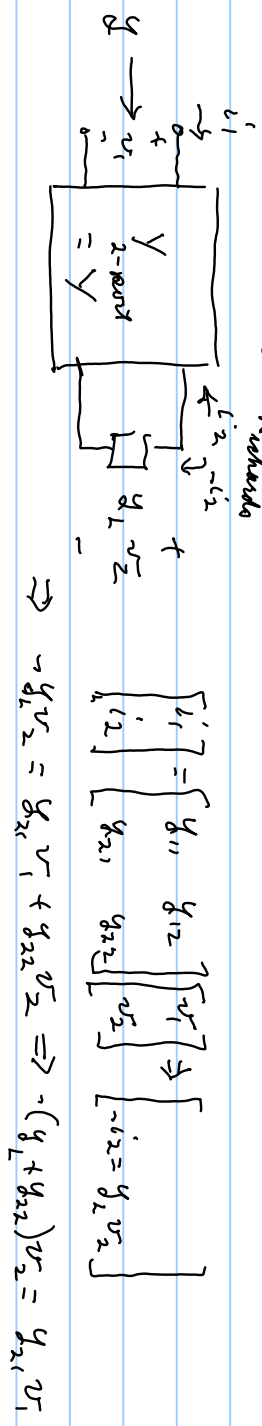
$$g_c(s) = \frac{1}{3(s)} \cdot \frac{2s^3 + 2s}{s^4 + 3s^2 + 1} \Rightarrow \frac{1}{s} \cdot \frac{2s^3 + 2s}{s^4 + 3s^2 + 1} = \frac{A}{s} + \frac{B}{s^2 + 1} + \frac{C}{s^2 + 1}$$

} $g_c(s)$ is LPR
 \Rightarrow P(z) is "quasistable"
 strictly

Other Richards functions:
 $s = \frac{1+z}{1-z}$ where if k is a zero of $g_c(s)$; $\Rightarrow g_c(z) + g_c(-z) = 0$



for LPR, for $g_c(s) \equiv 0$ \therefore any real positive k is a zero of $g_c(s)$
 this allows the design of $g_{R, Richards}$

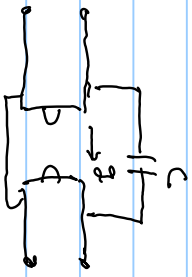


$$v_2 = - \frac{b_{21}}{g_L + g_{22}} \cdot v_1 \Rightarrow v_1 = \frac{g_{21}}{g_L + g_{22}} v_2 \Rightarrow \begin{bmatrix} g_{11}g_L + g_{11}g_{22} - g_{12}g_{21} \\ g_L + g_{22} \end{bmatrix} v_1$$

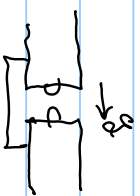
$$y = \frac{g_{11}y_L + \Delta y}{g_L + g_{22}} \quad \Delta y = \text{determinant } y = g_{11}g_{22} - g_{12}g_{21}$$

$$\Rightarrow y_1 g_L + y_2 g_{22} = g_{11} g_L + \Delta y \Rightarrow (g - g_{11}) g_L = \Delta y - y_2 g_{22} \Rightarrow g_L = \frac{\Delta y - y_2 g_{22}}{g - g_{11}}$$

revert to give Richards' function for g_L when load



= combination of



$$Y_g = \begin{bmatrix} 0 & g \\ -g & 0 \end{bmatrix}$$

$$Y_c = \begin{bmatrix} g_c & -g_c \\ -g_c & g_c \end{bmatrix}$$

$$Y = \begin{bmatrix} g_c & g - g_c \\ -g - g_c & g_c \end{bmatrix} \Rightarrow \Delta y = (g_c)^2 - (g - g_c)(-g - g_c) = (g_c)^2 + (g^2 - (g_c)^2) = g^2$$

$$\therefore y_L = \frac{\Delta y - y_{ss} y}{y - y_{ss}} = \frac{g^2 - RC y_L(\alpha)}{y^{(n)} - RC} = g^2 \left(\frac{1 - \frac{RC}{g} \cdot \frac{y_L(\alpha)}{g}}{\frac{y_L(\alpha)}{g} - \frac{RC}{g}} \right) = g \left(\frac{1 - \left(\frac{RC}{g}\right) \left(\frac{y_L(\alpha)}{g}\right)}{\left(\frac{y_L(\alpha)}{g}\right) - \frac{RC}{g}} \right)$$

$$y_I(\alpha) = y_I^{(k)} \left[\frac{R y_I^{(k)} - \alpha y_I^{(k-1)}}{R y_I^{(k)} - \alpha y_I^{(k-1)}} \right] \Rightarrow \frac{y_I(\alpha)}{y_I^{(k)}} = \frac{R y_I^{(k)}}{R y_I^{(k)}} \left[\frac{1 - \frac{\alpha}{R} \cdot \frac{y_I^{(k-1)}}{y_I^{(k)}}}{\frac{y_I^{(k-1)}}{y_I^{(k)}} - \frac{\alpha}{R}} \right] = \left(\frac{1 - \frac{\alpha}{R} \cdot \frac{y_I^{(k-1)}}{y_I^{(k)}}}{\left(\frac{y_I^{(k-1)}}{y_I^{(k)}}\right) - \frac{\alpha}{R}} \right)$$

$\Rightarrow \frac{y}{C} = K, \quad g = y_I^{(k)}$
 $C = \frac{g^2 - y_I^{(k)}}{R}$

$\therefore y_I(\alpha)$ results by reading the system - C 2-part in $y_I(\alpha)$

Example: $y_I(\alpha) = \frac{3\alpha}{\alpha^2 + 4}$ choose any real $k > 0$, $k=3$, $y_I^{(k)} = \frac{9}{\alpha + 4} = \frac{9}{13}$

$$y_I = y_I^{(k)} \left[\frac{R y_I^{(k)} - \alpha y_I(\alpha)}{R y_I^{(k)} - \alpha y_I^{(k-1)}} \right] = \frac{9}{13} \left[\frac{3 \times \frac{9}{13} - \frac{3\alpha^2}{\alpha^2 + 4}}{\frac{9\alpha}{\alpha^2 + 4} - \frac{9}{13}} \right] = \frac{9}{13} \left[\frac{\frac{27\alpha^2 + 4 \times 27 - 3\alpha^2}{13}}{9\alpha - \left(\frac{9}{13}\alpha^3 + \frac{4 \times 9}{13}\right)} \right]$$

and $x^2 - k^2$ cancels, as k is a root of Eq (1) $\Rightarrow x^2 - 9$ cancels