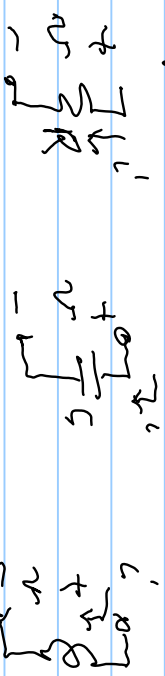


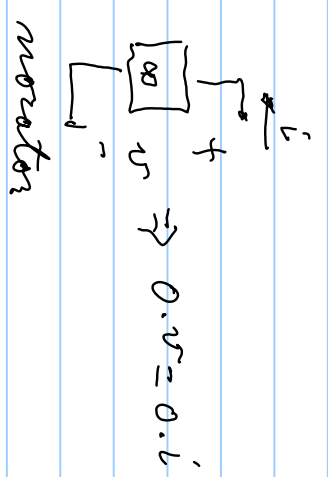
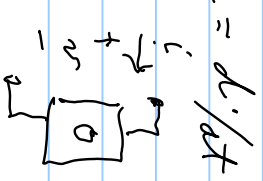
$A v = B i$ Linear if A & B are constants

1-ports



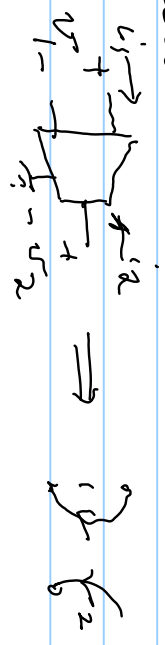
$i = G v$
 $v = R i$
 $i = C \frac{dv}{dt}$
 $v = L \frac{di}{dt}$

$R = v/i$



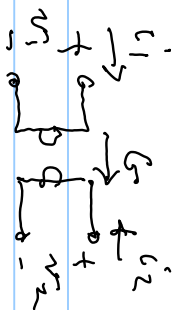
$v = 0$
 $i = 0$
 multipliers
 multipliers

2-ports



$$\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ g & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix}$$

OTA = operational transconductance amplifiers

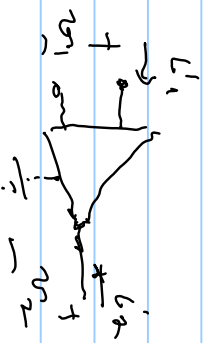


gyrator

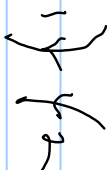


$$i = \begin{bmatrix} 0 & G \\ -G & 0 \end{bmatrix} v, \quad G = -G^T$$

$V = \text{transposes}$



ideal op-amp



$$v_1 = 0 \Rightarrow \text{virtual connection} \\ i_1 = 0$$

v_2 & i_2 are

free & fixed by external connections

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix}$$



ideal transformer

$$v_2 = T v_1$$

$$P_{inc}(t) = 0 = v_1 i_1 + v_2 i_2 = v_1 i_1 + T v_1 i_2 = 0 \Rightarrow i_1 + T i_2 = 0$$

or v_1 can be anything

$$\begin{bmatrix} -T & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 1 & T \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix}$$

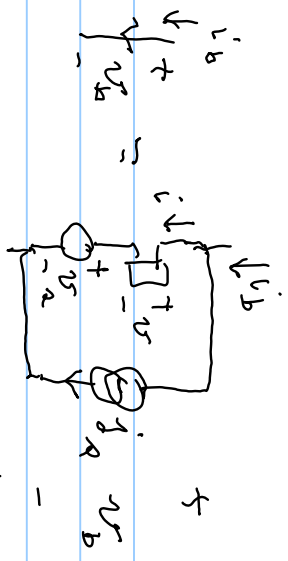
general theory: $\begin{cases} KVL: v_b = e^T v_T \\ KCL: i_b = \sigma^T i_R \end{cases}, \quad \begin{matrix} Q_a = \sigma^T v_b \\ O_r = e^T i_b \end{matrix}$

connection laws

components, linear time-invariant

$A v = B i$; $A \in \mathbb{R}^{a \times b \times b}$

$i_b = i + j_a$
 $v_b = v + v_a$
 $v = v_b - v_a$



combine $\Rightarrow A(v_b - v_a) = B(i_b - j_a) \Rightarrow A v_b - B i_b = A v_a - B j_a$

sources (Norton-Thvenin types)

$\Rightarrow A e^T v_T - B \sigma^T i_R = A v_a - B j_a$

$\begin{matrix} b \times T & b \times R \\ \underbrace{[A e^T \quad -B \sigma^T]}_{b \times b} \end{matrix} \begin{bmatrix} v_T \\ i_R \end{bmatrix} = \begin{bmatrix} A v_a + (-B j_a) \\ B \begin{bmatrix} v_a \\ i_a \end{bmatrix} \end{bmatrix}$

$$\therefore E dx/dt = Qx + Bu, \quad y = Cx, \quad x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}, \quad \begin{array}{l} u = \text{input} = m\text{-vector} \\ x = \text{state} \\ y = \text{output} = m\text{-vector} \end{array}$$

$$E_{n \times n} x =$$

$$\dim \text{ of } E = 5 = \text{degree}; \quad (E_{n \times n} - Q)x = Bu$$

$$y = C \cdot (E_{n \times n} - Q)^{-1} B \cdot u, \quad \sigma_{T(A)} = \text{transfer function} = C (sE - Q)^{-1} B$$

If $E = I_s$ then $x \rightarrow$ state

But we have singular E , so will need to manipulate to get state equations

$$\begin{array}{l} Ax = Ax + Bu \\ y = Cx + Du \end{array} \quad \begin{array}{l} \sigma_{T(A)} = D + C (sI_s - A)^{-1} B \\ \sigma_{T(AD)} = D \end{array}$$

Look at getting $\sigma(x) = x$

$$\begin{bmatrix} A & 0 \\ 0 & 0 \end{bmatrix} x = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} x + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u, \quad y = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$x_1 \approx -u, \quad Ax_1 = x_2, \quad y = x_2 = Ax_1 = A(-u)$$

$$y = -Au$$

note can get desired time due to singular Ξ

By transforming the variables we can get

$$\begin{bmatrix} I_s & 0 \\ 0 & N \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} A_1 & 0 \\ 0 & A_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} B_1 \\ B_2 \end{bmatrix} u$$

\therefore find nonsingular matrices P, Z, Q so

$$PEQ = \begin{bmatrix} I_s & 0 \\ 0 & N \end{bmatrix}, \quad PAQ = \begin{bmatrix} A_1 & 0 \\ 0 & A_2 \end{bmatrix}$$

$$APEDQ^{-1}x = PAQD^{-1}x + PBu, \quad y = CQD^{-1}x$$

$$A \begin{bmatrix} 1 & 0 \\ 0 & N \end{bmatrix} \hat{x} = \hat{A} \hat{x} + \hat{B}u, \quad y = \hat{C} \hat{x}, \quad \hat{A} = PAQ, \hat{B} = PB, \hat{C} = CQ$$

$$\hat{x} = D^{-1}x$$

$$N \text{ is nilpotent, } N^i = 0_{(n-s) \times (n-s)}, \quad N^{i-1} \neq 0$$