

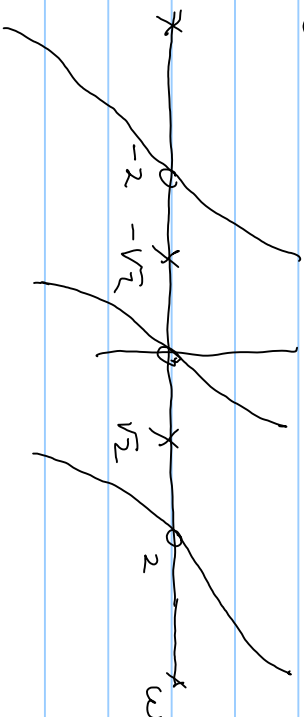
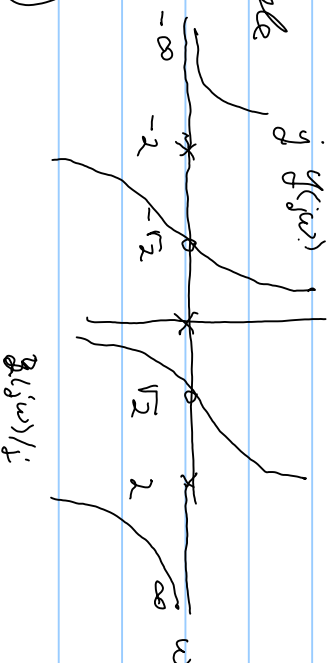
EE 610
10/04/16

synthesis example

$$g(s) = \frac{3(s^2+2)}{s(s^2+4)}$$

$$s^2 g'(s) = \frac{3}{s} \left(\frac{-s^2+2}{-s^2+4} \right) = \frac{3(-s^2+2)}{s(-s^2+4)}$$

$$g(s) = \frac{1}{s} = \frac{1}{3} \frac{3}{s(s^2+4)}$$



$g(s) \rightarrow$ partial fraction expansion

$$g(s) = \frac{3/2}{s} + \frac{3/4}{s+j2} + \frac{3/4}{s-j2}$$

$$= \frac{3/2}{s} + \frac{3/2}{s^2+4}$$

$$\underbrace{g_1}_{\sigma_1 = 2/3} + \underbrace{g_2}_{\sigma_2 = 3/8}$$

and roots

$$z_1 = \frac{1}{g_1} = \frac{s^2+4}{(3/2)s} = \frac{2}{3}s + \frac{4}{3s}$$

$$f(x) = \frac{1}{3} \frac{x(x^2+4)}{x^2+2} = \frac{1}{3}x + \frac{2k_1x}{x^2+2} \Rightarrow \left(\frac{x^2+2}{x} \right) \left(\frac{1}{3}x(x^2+4) \right) = \frac{1}{3}x(x^2+2) + 2k_1$$

$x^2 = -2$ $x^2 = -2$

$$\frac{x^2+4}{3} = 0 + 2k_1 \Rightarrow 2k_1 = \frac{2}{3}$$

$x^2 = -2$

$$f(x) = \frac{1}{3}x + \frac{2/3x}{x^2+2}$$



set of axes
 max minimum
 # of L'a e c'a

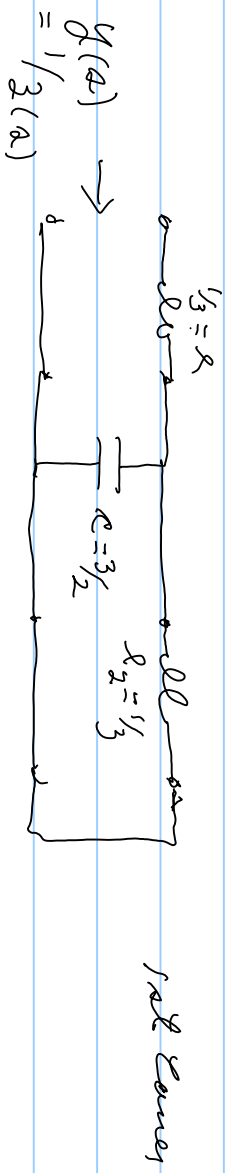
$$y_1 = 1/3 = \frac{x^2+2}{2/3x} = \frac{3}{2}x + \frac{1}{2/3x}$$

1st term \Rightarrow remove poles @ ∞

$$\begin{array}{c}
 \underbrace{x^2 + 2}_{\frac{1}{3}R} \quad \left| \quad \underbrace{\frac{1}{3}x^3 + \frac{4}{3}x}_{\frac{1}{3}R^3 + \frac{2}{3}R} \right. \\
 \underbrace{\frac{2}{3}x}_{\frac{2}{3}R} \quad \left| \quad \underbrace{x^2 + 2}_{\frac{1}{3}R} \right. \\
 \underbrace{2}_{\frac{2}{3}R} \quad \left| \quad \underbrace{\frac{2}{3}x}_{\frac{2}{3}R} \right. \\
 \underbrace{0}_{\frac{2}{3}R}
 \end{array}$$

$$y(x) = \frac{3(x^2+2)}{2(x^3+4)} = \frac{1}{3}x + \frac{1}{\frac{3}{2}x + 1}$$

continued fraction expansion about $x = \infty$



2nd Case \Rightarrow continued fraction expansion about $a=0$

$$y(a) = \frac{3(a^2+2)}{a(a^2+4)} = \frac{3a^2+6}{a^3+4a}$$

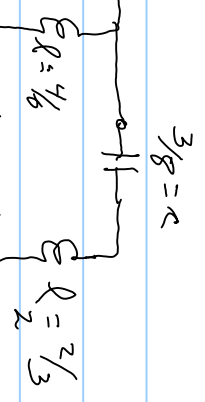
$$\frac{4a + a^3}{6 + 3a^2} \left[\frac{6 + 3a^2}{6 + \frac{6}{2}a^2} \right]$$

$$\frac{\frac{3}{2}a^2}{4a + a^3} \left[\frac{4a + a^3}{\frac{8}{3a}} \right]$$

$$\frac{a^3}{\frac{3}{2}a^2}$$

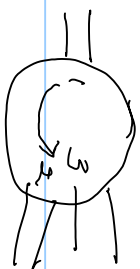
$$y(a) = \frac{6}{4a} + \frac{1}{\frac{8}{3a} + \frac{1}{\frac{3}{2a} + 0}}$$

2nd Case



Eigenvalues:
3-root

$$S = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$



$$\text{character} \Rightarrow S^{-1} S^T(-\kappa) = \frac{1}{3} \Rightarrow$$

$$\begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

find Y or Z

$$Y = (I_3 + S)^{-1} (I_3 - S)$$

$$I_3 + S = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}, \quad I_3 - S = \begin{bmatrix} 1 & 0 & -1 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

$$\det(I_3 + S) = 1 \cdot \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} - 1 \cdot \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} = 1 - (-1) = 2$$

The $(2,1)$ entry of $(I_3 + S)$ we need the $(1,2)$ cofactor = $(-1)^{1+2} \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = -1$
for all: $(I_3 + S)^{-1} = \frac{1}{2} \begin{bmatrix} 1 & 1 & -1 \\ -1 & 1 & 1 \\ 1 & -1 & 1 \end{bmatrix}$

$$Y = \frac{1}{2} \begin{bmatrix} 1 & 1 & 1 \\ -1 & 1 & 1 \\ 1 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 0 & +2 & -2 \\ -2 & 0 & 2 \\ +2 & -2 & 0 \end{bmatrix} = -Y^T \text{ is skew-symmetric}$$

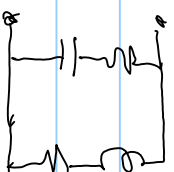
Lossless condition is $Y(x) + Y^T(-x) = 0 \Rightarrow Y = -Y^T$ here
 \Rightarrow 3-port circulator is lossless

$$Y = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ +1 & 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix} \leftarrow \text{3 gyrators}$$

\therefore Look @ degree 1 PR $g(a) = \frac{a^2 + b}{a^2 + d}$, $a, b, c, d \geq 0$

$$= \frac{a^2}{a^2 + d} + \frac{b}{a^2 + d} \text{ each is PR}$$

$$= \frac{1}{\frac{a}{a} + \frac{d}{a^2}} + \frac{1}{\frac{a}{b} + \frac{d}{b}}$$



$$T(\alpha) = \frac{\mathcal{L}[\text{output}]}{\mathcal{L}[\text{input}]} = \frac{Y(\alpha)}{U(\alpha)} = \frac{N(\alpha)}{D(\alpha)} = \frac{\alpha^m a_m + \alpha^{m-1} a_{m-1} + \dots + \alpha_1 a_1 + \alpha_0 a_0}{b_m \alpha^n + b_{m-1} \alpha^{n-1} + \dots + b_1 \alpha + b_0}$$

$$= \frac{\mathcal{L}[y(t)]}{\mathcal{L}[u(t)]}$$

\Rightarrow differential eq. $[b_m \frac{d^m y}{dt^m} + \dots + b_0 y] = a_m \frac{d^m u}{dt^m} + \dots + a_1 \frac{du}{dt} + a_0 u$

$$\text{Laplace of } \mathcal{L}[f(t)] = \int_{-\infty}^{\infty} f(t) e^{-\alpha t} dt \quad \text{if } f(t) = 0 \text{ for } t < 0$$

$$\Rightarrow \mathcal{L}[f(t)] = \int_0^{\infty} f(t) e^{-\alpha t} dt$$

$$\text{analysis of } \mathcal{L}[f(t)] = \int_0^{\infty} f(t) e^{-\alpha t} dt$$