

EE 610

09/13/16

$$E \frac{dx}{dt} = Ax + Bu$$

$$y = Cx$$

If E is nonsingular E^{-1} exists, $\frac{dx}{dt} = E^{-1}Ax + E^{-1}Bu$

$$y = Cx$$

$$AE x = Ax + Bu$$

$$y = Cx$$

state variable eqs

$$y(s) = T(s)u(s) \iff (AE - A)x = Bu$$

$$y = Cx$$

$$x = (AE - A)^{-1}Bu$$

$$y = C(AE - A)^{-1}Bu, \quad T(s) = C(AE - A)^{-1}B$$

= transfer function matrix

$$\text{If } E = I_n \text{ then } T(s) = C(AI_n - A)^{-1}B \rightarrow 0 \text{ if } A \rightarrow \infty$$

if a state eq: $Ax = Ax + Bu$, $y = Cx + Du$ + $\epsilon u' + \dots$ to handle resonances

But semi-state equations can give $T(s) \rightarrow x^p \dots$, p any integer

Reason:

$$ANx = I_n x + Bu, \quad y = Cx$$

$$-(I_n - AN)x = Bu, \quad x = -(I_n - AN)^{-1} Bu$$

$$(I_n - AN)^{-1} = \sum_{k=0}^{\infty} (AN)^k \Rightarrow I_n \stackrel{?}{=} \left(\sum_{k=0}^{\infty} (AN)^k \right)$$

$$= \sum_{k=0}^{\infty} (AN)^k - \sum_{k=1}^{\infty} (AN)^k$$

if $N = 0$ and $N \neq 0$ $= (AN)^0 = I_n$

When N is called nilpotent

$$\text{then } (I_n - AN)^{-1} = \sum_{k=0}^p (AN)^k$$

$$\therefore ANx = I_n x + Bx, \quad y = Cx$$

$$\text{then } T(A) = C(A - I_n)^{-1} B = C(-I)^{\times} \left(\sum_{k=0}^{\infty} (AN)^k \right) B$$

given $T(A)$ for the polynomial in \mathbb{R}

$$\text{Ex: } N = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \quad N^2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\mathbb{R} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \mathbb{R} + \begin{bmatrix} B_1 \\ B_2 \end{bmatrix} \mathbb{R}, \quad y = \begin{bmatrix} C_1 & C_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$T(A) = \begin{bmatrix} C_1 & C_2 \end{bmatrix} \begin{bmatrix} -1 & \mathbb{R} \\ 0 & -1 \end{bmatrix}^{-1} \begin{bmatrix} B_1 \\ B_2 \end{bmatrix} = \begin{bmatrix} C_1 & C_2 \end{bmatrix} \begin{bmatrix} -1 & -\mathbb{R} \\ 0 & -1 \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \end{bmatrix}$$

$$\text{choose } C_1 \neq 0, C_2 = 0, B_1 = 0, B_2 \neq 0$$

$$= \begin{bmatrix} C_1 & 0 \end{bmatrix} \begin{bmatrix} -1 & -\mathbb{R} \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ B_2 \end{bmatrix} = -\mathbb{R} C_1 B_2 = T(A)$$

$$A \in \mathbb{R}^n = Ax + Bu, \quad y = Cx$$

$$A \in \mathbb{R}^n = PAx + PBu, \quad y = Cx, \quad P \text{ nonsingular}$$

$$x = Q\hat{x}, \quad Q \text{ nonsingular}$$

$$A \in \mathbb{R}^n = PAQ\hat{x} + PBu, \quad y = CQ\hat{x}$$

$$A \in \hat{\mathbb{R}}^n = \hat{A}\hat{x} + \hat{B}u, \quad y = \hat{C}\hat{x}, \quad \hat{E} = PEQ, \hat{A} = PAQ, \hat{B} = PB$$

$$\hat{C} = CQ$$

$$T(x) = C(AE - A)^T B, \quad T(\hat{x}) = \hat{C}(\hat{A}\hat{E} - \hat{A})^T \hat{B} = CQ(APEQ - PAQ)^T PB$$

$$= CQ(P(AEQ - PAQ))^T PB$$

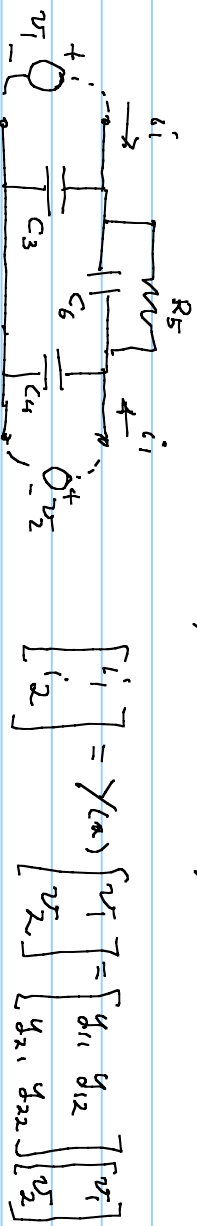
$$= CQ(P[A(EQ - AQ)])^T PB$$

$$= CQ(P(AE - A)Q)^T PB$$

$$= CQQ^T(AE - A)^T P^T PB$$

$$= C(AE - A)^T B \equiv T(x)$$

derive admittance matrix as TCA , $2 \times 2 = 2$ -port

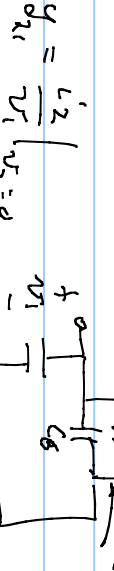


$$\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = Y(s) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$



$$y_{11} = \frac{i_1}{v_1} \Big|_{v_2=0}$$

$$y_{11} = sC_3 + sC_6 + G_5, \quad G_5 = 1/R_5$$



$$i_2 = -(sC_6 + G_5)v_1 = y_{21}v_1$$



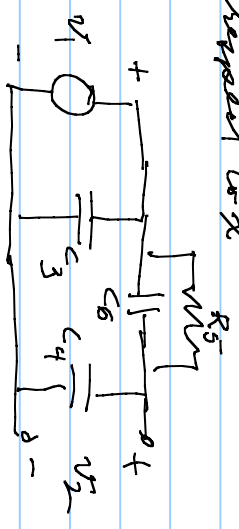
$$y_{12} = \frac{i_2}{v_1} \Big|_{v_2=0}$$

$$y_{12} = y_{21} = -(sC_6 + G_5)$$

$$y_{22} = sC_4 + sC_6 + G_5 \quad \text{by symmetry}$$

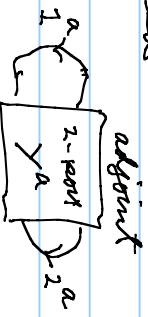
$$Y = \begin{bmatrix} A(C_3 + C_6) + G_5 & -A C_6 - G_5 \\ -A C_6 - G_5 & A(C_4 + C_6) + G_5 \end{bmatrix} = Y_{2 \times 2 \text{ port}}$$

Transferability $S_x^{T(x)} = \frac{\Delta T(x)/kx}{T(x)/x}$
of T(x) with respect to x



$$T(x) = \frac{v_2}{v_1} = \frac{1/kx}{\frac{1}{Ac_4} + \frac{1}{Ac_6 + G_5}}$$

do not $S_x^{C_6}$ are adjacent nodes



adjacent

use these 2 to find $\partial T / \partial x$ by analyzing
 assume the adjoint has the same graph $\mathcal{V}_b^T i_b' = \mathcal{V}_b^a i_b^a = 0$

$$\Rightarrow \mathcal{V}_b^T i_b^a = 0 \quad \mathcal{V}_b^a i_b^T = 0 \quad ; \quad i_{b-a}^a = \mathcal{Y}_{b-2 \times b-2}^a \cdot \mathcal{V}_{b-2}^a$$

$$\mathcal{V}_b^T i_b^a - \mathcal{V}_b^a i_b^T = 0 \quad l_{b-2}^a = \mathcal{Y}_{b-2 \times b-2}^a \cdot \mathcal{V}_{b-2}^a$$

$$\mathcal{V}_{b_1, l_{b_1}}^a + \mathcal{V}_{b_2, l_{b_2}}^a - \mathcal{V}_{b_1}^a l_{b_1} - \mathcal{V}_{b_2}^a l_{b_2} + \mathcal{V}_{b-2}^T i_{b-2}^a - \mathcal{V}_{b-2}^a i_{b-2}^T = 0$$

$$\frac{\partial \mathcal{V}_{b_1, l_{b_1}}^a}{\partial x} + \mathcal{V}_{b_1}^a \frac{\partial l_{b_1}^a}{\partial x} + \frac{\partial \mathcal{V}_{b_2, l_{b_2}}^a}{\partial x} + \mathcal{V}_{b_2}^a \frac{\partial l_{b_2}^a}{\partial x} -$$