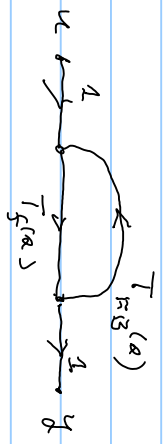


of feedback

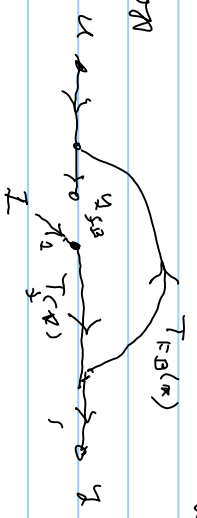


$$u_1 \rightarrow u_0 = u_1 + u_2$$

$$u_2 \rightarrow u_0 = u_1 + u_2$$

$$y_{o1} = y_{o2}$$

Break down



$$y_{FB}(s) \text{ with unit input to } T_{FB}(s), \quad y_{FB}|_{u=0} = T_{FB} \cdot T_s$$

$$\text{return ratio is } y_{FB} = \frac{T_{FB} \cdot T_s \cdot 1}{1}, \quad \text{return difference } \mathcal{N} = y_{FB} - 1$$

for no input u , oscillations will be sustained if $q_{FB} = 1$

has a $\omega = j\omega_0$, $T_{FB}(j\omega) T_G(j\omega) = 1$ for $\omega = \omega_0$

$T_{FB} = 1$, $T_G(s) = N(s)/D(s)$, ratio of two polynomials

$$1 \cdot \frac{N(s)}{D(s)} = 1 \Rightarrow P(s) = N(s) - D(s) \Rightarrow -P(s) = D(s) - N(s)$$

of lower power, $N(s) = 1$, $D(s) = a_n s^n + a_{n-1} s^{n-1} + \dots + a_1 s + a_0$

Ex: $D(s) = R^3 + a_2 s^2 + a_1 s + a_0 - 1$

$D(j\omega) = (a_0 - 1) + a_1 j\omega - a_2 \omega^2 - j\omega^3$

$= ((a_0 - 1) - a_2 \omega^2) + j(a_1 \omega - \omega^3)$

$= (a_0 - 1 - a_2 \omega^2) + j\omega(a_1 - \omega^2)$

Signs of the form
 Constant + j sin/cos

denominator $D(s) = 0$ at $\omega = \omega_0 \Rightarrow a_1 = \omega_0^2$ from imaginary part

from real part $a_0 - 1 - a_2 \omega_0^2 = 0 \Rightarrow a_0 - 1 - a_2 a_1 = 0$
 $\Rightarrow a_0 = 1 + a_1 a_2 = 1 + \omega_0^2 a_2$; can choose an a_2 real > 0

$$\text{given } T_f(s) = \frac{1}{s^3 + a_2 s^2 + a_1 s + a_0} = \frac{1}{\underbrace{(a_1 s + a_3) + (a_0 + a_2 s^2)}}_{\text{for stability}}$$

Hurwitz polynomial of stable

$$= \frac{1/(a_1 s + a_3)}{1 + \frac{(a_0 + a_2 s^2)}{a_1 s + a_3}} = \frac{1/N_f}{1 + D_f/N_f} = \frac{1/N_f}{1 + G_{11}(s)} = \frac{1}{a_3 + \dots + a_8}$$

$$y(a) = \frac{a_0 + a_2}{a_1 a + a_3} a^2 = \frac{a_0 + a_2 a^2}{a(a^2 + a_1)} = \frac{k_1}{a} + \frac{k_2}{a + j\sqrt{a_1}} + \frac{k_2^*}{a - j\sqrt{a_1}}$$

$$R_1 = \left. \begin{array}{l} k_1(a) \\ a=0 \end{array} \right| \Rightarrow \frac{a(a_0 + a_2 a^2)}{a(a^2 + a_1)} \Big|_{a=0} = \frac{a_0}{a_1} = k_1 + \frac{a k_2}{a + j\sqrt{a_1}} + \frac{a k_2^*}{a - j\sqrt{a_1}}$$

$$k_1 = a_0/a_1 > 0$$

$$R_2 = (a + j\sqrt{a_1}) \cdot y(a) \Big|_{a = -j\sqrt{a_1}} = \frac{a_0 + a_2 a^2}{a(a + j\sqrt{a_1})(a - j\sqrt{a_1})} \times (a + j\sqrt{a_1}) \Big|_{a = -j\sqrt{a_1}} = \frac{a - a_2 a_1}{a(-\sqrt{a_1})(-2j\sqrt{a_1})}$$

$$= \frac{a_0 - a_2 a_1}{-2a_1} = \frac{a_0 - \frac{1}{2} a_0}{2} = \frac{1}{2} (a_1 a_2 - a_0)$$

$$y(a) = \frac{a_0 + a_2 a^2}{a(a^2 + a_1)} = \frac{a_0/a_1}{a} + \frac{1}{2} \left(\frac{a_1 a_2 - a_0}{a_1} \right) + \frac{1}{2} \left(\frac{a_1 a_2 - a_0}{a_1} \right) \frac{1}{a - j\sqrt{a_1}}$$

$$\frac{a_1 a_2 - a_0}{a_1} \frac{1}{a - j\sqrt{a_1}}$$

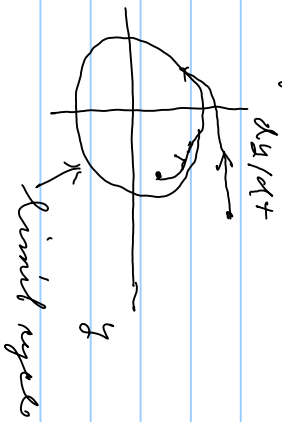
$$y(\omega) = \frac{1}{\alpha_1 \omega} + \frac{(a_1 a_2 - a_0) \omega}{\alpha_1 \omega^2 + a_1} = \frac{1}{\alpha_1 \omega} + \frac{1}{\alpha_1 \left(\frac{a_1}{\alpha_1 a_2 - a_0} \omega + \frac{a_1}{\alpha_1} \right)}$$

$$y(\omega) \rightarrow \underbrace{\frac{1}{\alpha_1 \omega}}_{\omega_h = a_1 / \alpha_0} + \underbrace{\frac{1}{\alpha_1 \left(\frac{a_1}{\alpha_1 a_2 - a_0} \omega + \frac{a_1}{\alpha_1} \right)}}_{\omega_c = \frac{a_1}{\alpha_1 a_2 - a_0}} = \frac{1}{\alpha_1} \cdot \frac{1}{\omega} = \frac{1}{\alpha_1} = \omega_0^2$$

$\omega_0 = \omega_0^2$

For a structurally stable oscillator look at the Van der Pol oscillator (it limit cycles of ODE's)

$$\frac{d^2 y}{dt^2} + \epsilon (y^2 - 1) \frac{dy}{dt} + \omega_0^2 y = 0$$



$$\frac{d}{dt} \left(\frac{dy}{dt} + F(\epsilon, y) \right) = -\omega_0^2 y, \quad x = \frac{dy}{dt} + F(\epsilon, y)$$

$$\frac{dx}{dt} = -\omega_0^2 y$$

$$\frac{dy}{dt} = x - F(\epsilon, y)$$

$$\frac{dx}{dt} = -\omega_0^2 y$$

$$\frac{dF(\epsilon, y)}{dt} = \epsilon (y^2 - 1) \frac{dy}{dt}$$

$$F(\epsilon, y) = \int_{y_0}^{y(t)} \epsilon (y^2 - 1) dy = \epsilon \frac{y^3}{3} - \epsilon y$$

$$\frac{dx}{dt} = -\omega_0^2 y$$

$$\frac{dy}{dt} = x - \epsilon \left(\frac{y^3}{3} - y \right)$$

} can make with Hilbert multipliers & capacitors

if on left side: $C \frac{dV}{dt} = i \Rightarrow$ right side are currents

depending on voltage

interested in the limit cycle:

can make with OTRs



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