

EE610
09/29/15

$$\dot{x} = Ax + Bu \quad T(s) = D + C(A - sI)^{-1}B \quad T(\infty) = D$$

does not allow a pole at ∞

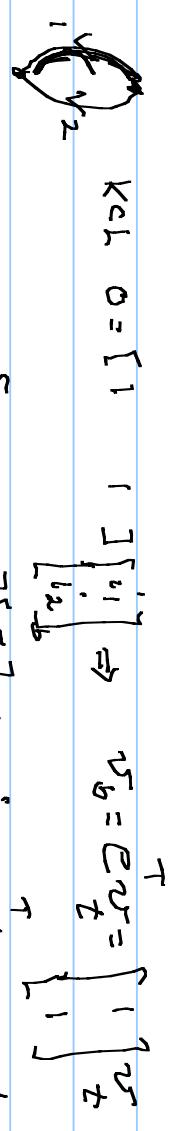
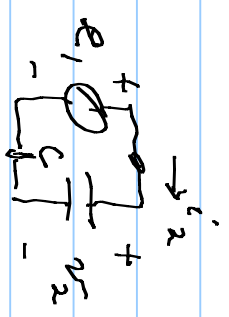
$$y = Cx + Du + R E + R^2 F \dots$$

But $\int \frac{1}{s} ds = \ln s$

$$T(s) = AC \cdot v(s) \Rightarrow T(s) = AC \text{ has a pole at } \infty$$

allowed in $E \dot{x} = Ax + Bu$, E possibly singular

$$y = Cx$$



KVL $0 = [1 \quad 1 \quad 1] \begin{bmatrix} v_1 \\ v_2 \\ v_2 \end{bmatrix} \Rightarrow v_2 = -v_1$

KVL $0 = [1 \quad -1 \quad 1] \begin{bmatrix} v_1 \\ v_2 \\ v_2 \end{bmatrix} \Rightarrow v_2 = v_1$

$$v_b = e + v = \begin{bmatrix} e_1 \\ 0 \end{bmatrix} + \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$i_b = i + i = \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} i_1 \\ i_2 \end{bmatrix}$$

$b = 2$, A, B for $A \cdot v = B \cdot i$ are 2×2

$$\begin{bmatrix} 1 & 0 \\ 0 & AC \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$\begin{cases} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} e_1 \\ 0 \end{bmatrix} - \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \\ = \begin{bmatrix} x_1 \\ 0 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \end{bmatrix} v_2 \\ \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = u_b = \begin{bmatrix} -1 \\ 1 \end{bmatrix} v_2 \end{cases}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & AC \end{bmatrix} \begin{cases} \begin{bmatrix} x_1 \\ 0 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \end{bmatrix} v_2 \\ \begin{bmatrix} 0 \\ 1 \end{bmatrix} v_2 \end{cases} = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix} v_2$$

$$\begin{bmatrix} -1 & 0 \\ 0 & -AC \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} v_2 - \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix} v_2 = \begin{bmatrix} -1 & 0 \\ 0 & -AC \end{bmatrix} \begin{bmatrix} e_1 \\ 0 \end{bmatrix} = \begin{bmatrix} +e_1 \\ 0 \end{bmatrix}$$

$$\begin{aligned} &= \begin{bmatrix} +1 \\ 0 \\ +AC \end{bmatrix} v_2 - \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} v_2 = \begin{bmatrix} +1 & 0 \\ +AC & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} +x_1 \\ 0 \end{bmatrix} \quad x = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} x = \begin{bmatrix} -1 & 0 \\ 0 & +1 \end{bmatrix} x + \begin{bmatrix} 1 \\ 0 \end{bmatrix} e_1 \end{aligned}$$

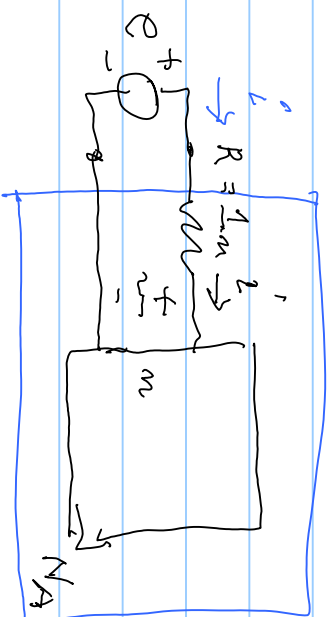
$$v' = u = \begin{bmatrix} 0 & 1 \end{bmatrix} x$$

$$\text{then } v' = AC v', \quad x_1 = v$$

1st eq. $x_1 = e_1$, $C_A x_1 = +x_2$; $C_A \cdot e_1 = +v_2 = +v_2$

for a double pole @ ∞ can add another branch in parallel with $g_3 = a_1 z^{-1}$ etc.,

realizing



$$i = Y_A e$$

$$e = v^i + v^o \Rightarrow v^o = e - v^i$$

$$v^o = \frac{1}{m} \cdot e - Y_A \cdot e = (1 - Y_A) e$$

$$A v^o = B v^i$$

$$A (1 - Y_A) e = B Y_A e$$

also $2 v^o = v^i + v^o$

$$2 v^o = v^i + v^o$$

$$\Rightarrow v^o = v^i + v^o \quad i = v^i - v^o$$

$$A (v^i + v^o) = B (v^i - v^o) \Rightarrow$$

$$(A+B)v^o = (B-A)v^i$$

$$v^o = (B+A)^{-1} (B-A) v^i$$

$$S = (B+A)^{-1} (B-A) \quad \text{for } v^T = S v^i$$

choose $A = Y_A$ & $B = (I_m - Y_A)$ then $A(I_m - Y_A) = Y_A - Y_A^2$
 $= B(Y_A) =$

$$Y_A v = (I_m - Y_A) v \Rightarrow A = Y_A, B = (I_m - Y_A)$$

\Rightarrow S goes with this A & B

$$S = (B+A)^{-1} (B-A) = (I_m - Y_A + Y_A)^{-1} (I_m - Y_A - Y_A) = I_m - 2Y_A$$

$S = I_m - 2Y_A$ one way to find S

if Z exists then $v = Z v^i \Rightarrow A = I_m, B = Z$

$$S = (I_m + Z)^{-1} (Z - I_m) \quad ; \quad \text{if } i \text{ : number of } Z = RL, v = RL v^i$$

$$S = (1+RL)^{-1} (RL-1)$$

if Y exists $\Rightarrow v = Y v^i$

$$= \frac{(RL-1)}{(RL+1)}$$

$$A = Y, B = I_m \Rightarrow S = (Y + I_m)^{-1} (I_m - Y)$$

$S(00) = 1$ works

$$S = (Y + I_n)^{-1} (I_n - Y) = (Z + I_n)^{-1} (Z - I_n) = I_n - Z^{-1} Y$$

den time domain; N is passive if $\int_{-\infty}^t p(x) dx = \int_{-\infty}^t v(x) i(x) dx \geq 0$

$$\int_0^t e^{i\tau} v(\tau) d\tau \geq 0 \text{ \& finite if } e_i \text{ are in } h_2 = \text{square integrals}$$

$$= \int_0^t [v + i] [v + i]^T d\tau = \int_0^t [v^T v(\tau) + i v^T(\tau) + 2v^T(\tau) i(\tau)] d\tau$$

≥ 0 & finite [in h_2 by assumption] [product of passives]

\Rightarrow if e is in h_2 then v & i are also if N is passive

$$\text{look at } p_m^i(\omega) = \text{Re } v^T(\omega) i(\omega)$$

$$= \text{Re} [(v^i(\omega) + v^n(\omega))^T (v^i(\omega) - v^n(\omega))]$$

$$= \text{Re} [v^{iTx}(\omega) v^i(\omega) - v^{nTx}(\omega) v^i(\omega) + v^{iTx}(\omega) v^n(\omega) - v^{nTx}(\omega) v^n(\omega)]$$

cancel as they
cancel the part

$$\begin{aligned}
 P_m(\gamma, \omega) &= \operatorname{Re} \nu(\gamma, \omega) \nu(\gamma, \omega)^{T*} = \nu(\gamma, \omega) \nu(\gamma, \omega)^{T*} - \nu(\gamma, \omega)^{T*} \nu(\gamma, \omega) \\
 &= \operatorname{Re} \nu(\gamma, \omega)^{T*} \nu(\gamma, \omega) \nu(\gamma, \omega) = \nu(\gamma, \omega)^{T*} \left[I_m - S(\gamma, \omega) S(\gamma, \omega)^{T*} \right] \nu(\gamma, \omega) \\
 &= \frac{1}{2} \left[\nu(\gamma, \omega)^{T*} \nu(\gamma, \omega) + \nu(\gamma, \omega) \nu(\gamma, \omega)^{T*} \right]
 \end{aligned}$$

Conditions for positivity

1) $\gamma(\alpha)$ (and $Z(\alpha)$) is positive-real \Leftrightarrow 2) $S(\alpha)$ is bounded real

iff

a) $\gamma(\alpha)$ is real for α real & positive a) also $S(\alpha)$ is real for real positive α
 (coefficients real of $\gamma(\alpha)$)
 no solutions = rational
 of 2 polynomials)

(note $\sqrt{\alpha}$ is positive-real)

b) $\gamma(\alpha)$ has no singularity in \mathbb{R}_+ b) $S(\alpha)$ has no singularity in \mathbb{R}_+ & $\sigma > 0$
 [the sum is stable]

c) $\operatorname{Re}(\gamma(\alpha))$ is positive semi-definite in $\sigma > 0$ c) $I_m - S(\alpha)^* S(\alpha)$ is positive semi-definite in $\sigma > 0$

$$\text{if } P(j\omega) = 0 \Rightarrow Y(j\omega)^{TK} + Y(j\omega) = 0 \quad (\text{for almost all } \omega)$$

if PR

$$Y^{TK}(j\omega) = Y^T(-j\omega)$$

$$\Rightarrow Y^{TK}(j\omega) + Y(j\omega) = Y^T(-j\omega) + Y(j\omega)$$

$$= (Y^T(-a) + Y(a)) \Big|$$

$$a = j\omega \Rightarrow \omega = \sigma/j$$

,