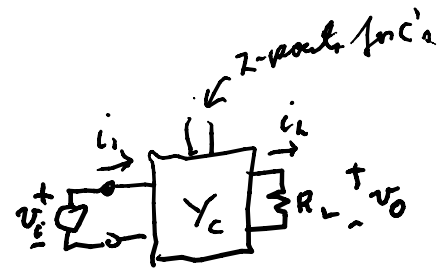


Synthesis of $v_o(s)/v_i$ from state:

$$\frac{v_o}{v_i} = \frac{3}{s^2 + \sqrt{2}s + 1}$$

$$\dot{\hat{x}} = \begin{bmatrix} 0 & 1 \\ -1 & -\sqrt{2} \end{bmatrix} \hat{x} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} v_i$$

$$R_L i_o = v_o = [3 \ 0] \hat{x} + [0] v_i$$



$$\begin{bmatrix} i_1 \\ i_2 \\ -\hat{x} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & -3G_L & 0 \\ 0 & +3G_L & 0 & -1 \\ -1 & 0 & 1 & \sqrt{2} \end{bmatrix} \begin{bmatrix} v_i \\ v_o \\ \gamma \end{bmatrix}$$

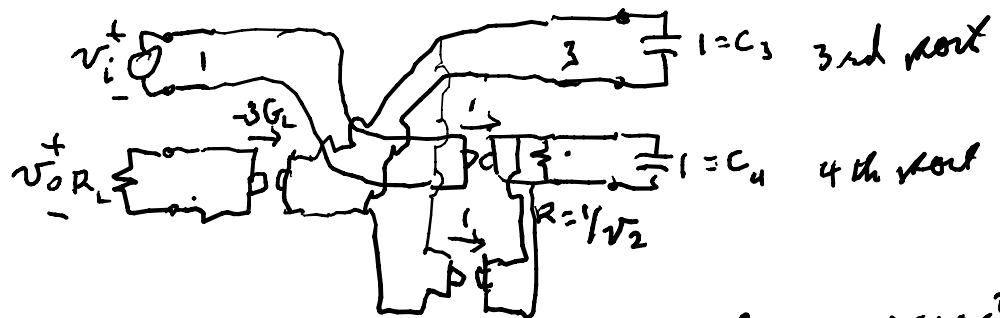
$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

can always find a Q such that

$$QAQ^{-1} + Q^{-T}A^TQ^T = -L L^T$$

$$\Rightarrow \hat{x} = Qx \quad \text{here } Q = \mathbb{1}_2$$

$$Y_c = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & -3G_L & 0 \\ 0 & 3G_L & 0 & -1 \\ -1 & 0 & 1 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \sqrt{2} \end{bmatrix}$$



passive realization as $Y_c + Y_c^T \geq 0$
(positive semi-definite)