

note



this has the same graph
with v_1 & v_2 can be independent
 i_3, i_4, i_5 " " "

} the tree branch voltages
can be "variables"
& same for coltree
branch currents

write $i_b =$ branch currents $= \begin{bmatrix} i_1 \\ i_2 \\ i_3 \\ i_4 \\ i_5 \end{bmatrix} = i_b$, $v_b =$ branch voltages $= \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \end{bmatrix} = \begin{bmatrix} v_t \\ -v_r \end{bmatrix}$

$= \begin{bmatrix} i_t \\ i_r \end{bmatrix}$

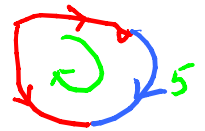
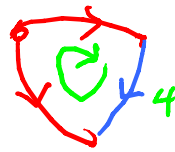
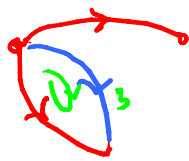
KCL:

$$\begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & | & 1 & 1 & 1 \\ 0 & 1 & | & 0 & -1 & -1 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \\ i_4 \\ i_5 \end{bmatrix} = \text{cut set equations}$$

$$0_t = C i_b$$

$$= \begin{bmatrix} 1 & 2 & | & -K \end{bmatrix} \begin{bmatrix} i_t \\ i_r \end{bmatrix} \Rightarrow i_t = K i_r \Rightarrow i_b = \begin{bmatrix} i_t \\ i_r \end{bmatrix} = \begin{bmatrix} -K \\ 1 \end{bmatrix} i_r$$

KVL: use loops



$$\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 & 0 & | & 1 & 0 & 0 \\ -1 & 1 & | & 0 & 1 & 0 \\ -1 & 1 & | & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \end{bmatrix} \Rightarrow \underline{o}_r = \mathcal{T} v_b, \quad \mathcal{T} = \text{tie set matrix} \\ \underline{o}_r = \mathcal{T} v_b, \quad \mathcal{C} = \text{cut set matrix} \\ = \begin{bmatrix} K^T & | & \underline{1}_3 \end{bmatrix} \begin{bmatrix} v_t \\ v_r \end{bmatrix} \Rightarrow v_r = -K^T v_t \Rightarrow \begin{bmatrix} v_t \\ v_r \end{bmatrix} = \begin{bmatrix} \underline{1}_t \\ -K^T \end{bmatrix} v_t \\ \underline{v}_b = e^T v_t$$

$$v_b = e^T v_t, \quad \underline{o}_t = e i_b \\ i_b = \mathcal{T}^T i_r; \quad \underline{o}_r = \mathcal{T} v_b$$

note if know K , know both
 $e \ \& \ \mathcal{T}$ so $KVL \Leftrightarrow KCL$



$$\Rightarrow \text{Power} = 0 = \sum_{i=1}^b v_b i_b = v_b^T i_b = v_b^T \mathcal{T} i_r = v_t^T e \mathcal{T}^T i_r \\ \Rightarrow v_b^T \mathcal{T} = \underline{o}_r$$

$$\Rightarrow e \mathcal{T}^T = \underline{o}_{t,r}$$

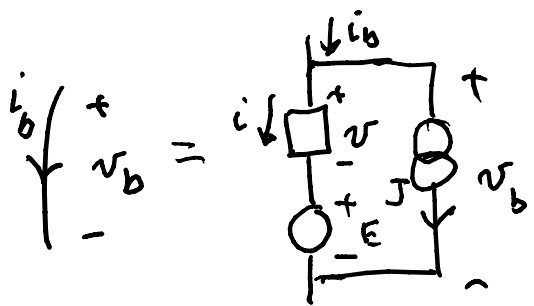
$$\begin{bmatrix} \underline{1}_t & | & -K \end{bmatrix} \begin{bmatrix} Q \\ \underline{1}_r \end{bmatrix} \Rightarrow Q = K \Rightarrow \mathcal{T}^T = \begin{bmatrix} Q \\ \underline{1}_r \end{bmatrix}$$

$$\mathcal{T} = \begin{bmatrix} Q^T & \underline{1}_r \end{bmatrix} \\ = \begin{bmatrix} -K^T & \underline{1}_r \end{bmatrix}$$

for loops of components use

$$Y_{b \times b} = \begin{bmatrix} G_i & 0 & 0 & 0 & 0 \\ 0 & sC_p & 0 & 0 & 0 \\ 0 & 0 & g_r + sC_r & 0 & 0 \\ g_m & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & G_L \end{bmatrix}$$

$$i = \begin{bmatrix} R_i \\ \underline{0}^+ \\ -v_i \end{bmatrix}$$



$$v_b = v + E$$

$$i = Y_{b \times b} v$$

$$i_b = i + J$$

$$i = i_b - J = Y_{b \times b} \cdot v = Y_{b \times b} (v_b - E) \Rightarrow$$

$$i_b = Y_{b \times b} \times v_b + (J - Y_{b \times b} E)$$

$$i_b = \mathcal{Q}^T i_l, \quad 0 = \mathcal{C} i_b = 0 = \mathcal{C} Y_{b \times b} e^T \cdot v_t + \mathcal{C} (J - Y_{b \times b} E)$$

$$\Rightarrow (\mathcal{C} Y_{b \times b} E - \mathcal{C} J) = \mathcal{C} Y_{b \times b} e^T \cdot v_t$$

t equations
for t unknowns
(v_t)

$$\Rightarrow v_t = [\mathcal{C} Y_{b \times b} e^T]^{-1} \times (\mathcal{C} Y_{b \times b} E - \mathcal{C} J)$$

Norton's equivalent current
sources feeding tree branches

$$\left[\begin{array}{c|ccc} 1 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & -1 & -1 \end{array} \right] \begin{bmatrix} G_i & 0 & 0 & 0 & 0 \\ 0 & \alpha C_\mu & 0 & 0 & 0 \\ 0 & 0 & g_\pi + \alpha C_\pi & 0 & 0 \\ g_m & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & G_L \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ \vdots & 0 \\ \vdots & -1 \\ \vdots & -1 \end{bmatrix} = \mathcal{C} Y_{b \times b} e^T$$

$$= \begin{bmatrix} G_i + g_m & 0 & g_\pi + \alpha C_\pi & 0 & G_L \\ -g_m & \alpha C_\mu & 0 & 0 & -G_L \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ \vdots & 0 \\ \vdots & -1 \\ \vdots & -1 \end{bmatrix} =$$

$$= \begin{bmatrix} G_i + g_m + g_\pi + \alpha C_\pi + G_L & -G_L \\ -g_m - G_L & \alpha C_\mu + G_L \end{bmatrix}$$