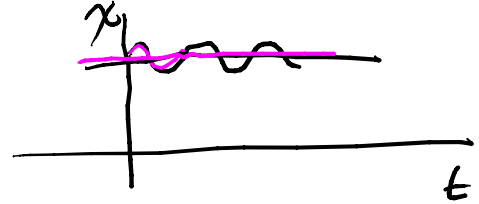
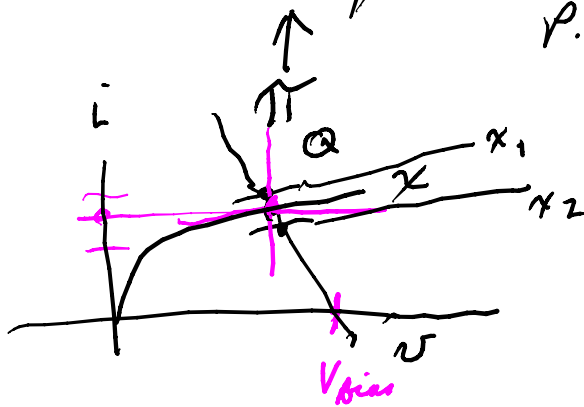


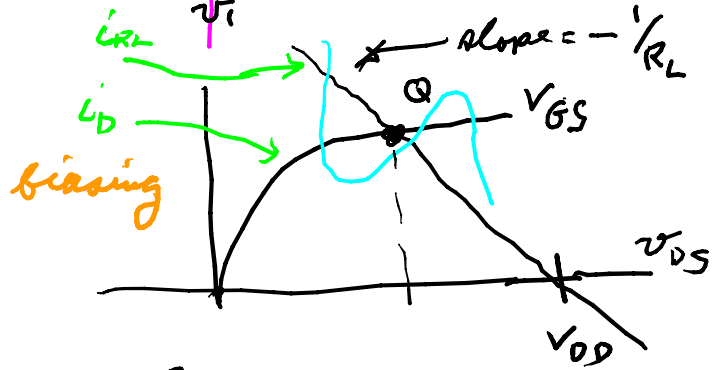
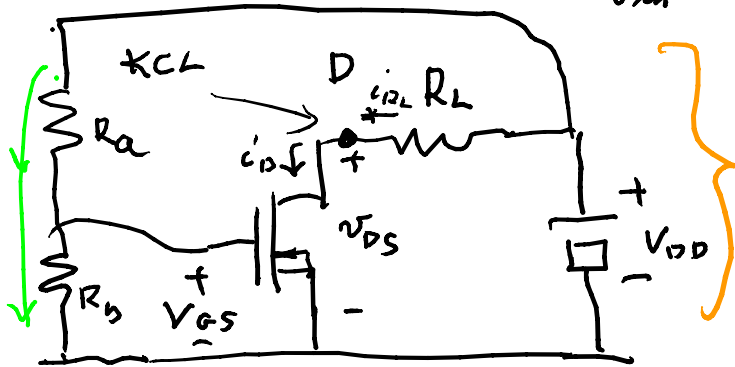
BJT & MOS equivalent circuits

P.557 Table 7.A.3

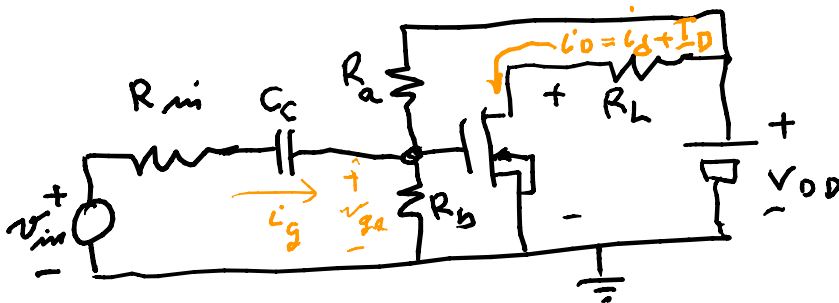


$$v_1 = v_{in}$$

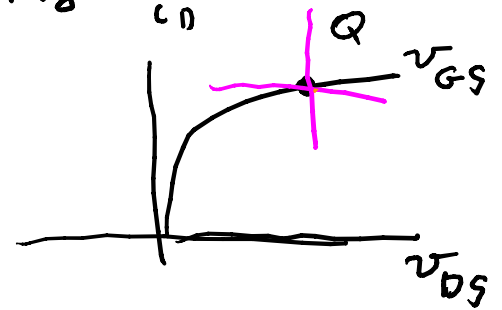
$$\frac{v_{out}}{v_{in}} = -R_L g_m \frac{v_1}{v_1} = A_v = -g_m R_L$$



$$V_{GS} = \frac{R_b}{R_a + R_b} \cdot V_{DD}$$



$$i_D = f(v_{GS}, v_{DS}) = i_d + I_D$$



$$y_x = y_x + Y_x$$

↑ total signal ↑ DC bias

$i_D \rightarrow$ expansion (power series)

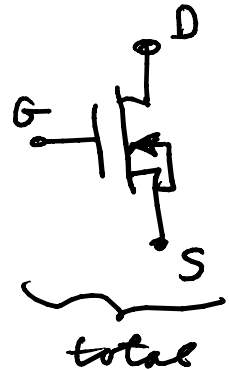
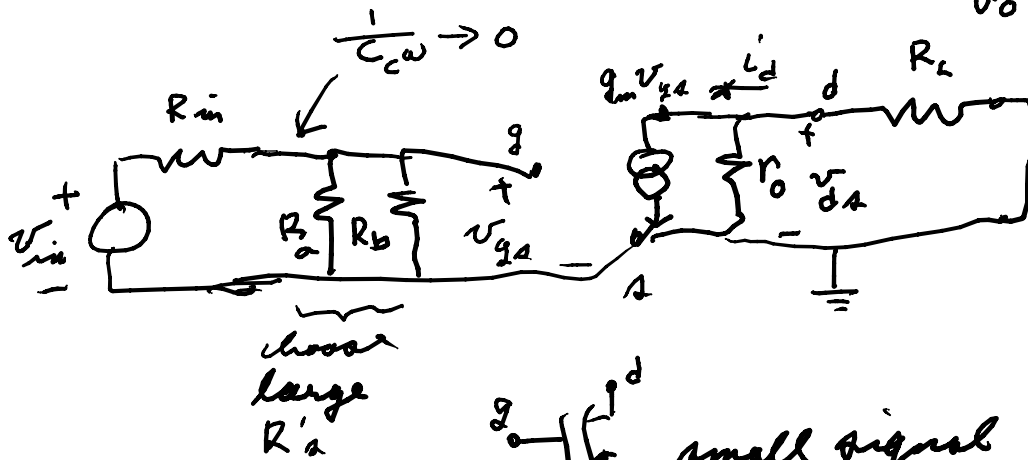
$$i_D = f(V_{GS}, V_{DS}) + \left. \frac{\partial f}{\partial V_{GS}} \right|_Q (V_{GS} - V_{GS}) + \left. \frac{\partial f}{\partial V_{DS}} \right|_Q (V_{DS} - V_{DS}) + \text{higher order}$$

(ignore for small signal)

$$i_D = I_D + g_m v_{gs} + g_o v_{ds}$$

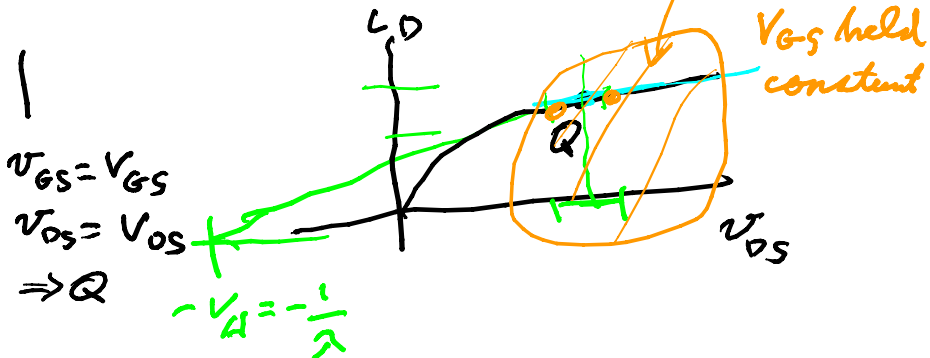
$$i_D - I_D = i_d = g_m v_{gs} + g_o v_{ds}$$

$$r_o = \frac{1}{g_o} = \text{output}$$



$$\frac{v_o}{v_{in}} = -g_m \frac{r_o R_L}{r_o + R_L} \Rightarrow -g_m R_L \text{ if } r_o \rightarrow \infty$$

$$r_o = \frac{1}{g_o} ; g_o = \left. \frac{\partial i_D}{\partial V_{DS}} \right|_Q$$



i. $g_o =$ slope of i_D line when $V_{GS} = Q$ point value is held constant

if in saturation $i_D = \frac{k_p}{2} \frac{W}{L} (v_{GS} - v_{TO})^2 (1 + \lambda v_{DS})$

$$\left. \frac{\partial i_D}{\partial v_{DS}} \right|_Q = \frac{k_p}{2} \frac{W}{L} (V_{GS} - V_{TO})^2 \cdot \lambda \approx I_0 \cdot \lambda$$

$$= \frac{I_0}{(1 + \lambda V_{DS})} = g_o$$

$$g_m = \left. \frac{\partial i_D}{\partial v_{GS}} \right|_Q = 2 \cdot \frac{k_p}{2} \frac{W}{L} (V_{GS} - V_{TO}) (1 + \lambda V_{DS})$$

$$= \frac{I_0}{(V_{GS} - V_{TO})} = \frac{I_0}{V_{ov}}$$

over drive voltage

