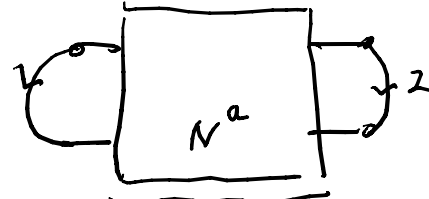
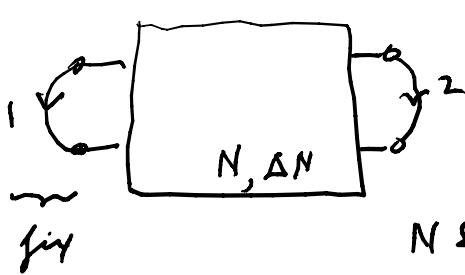


sensitivity $S_x^T = \frac{\partial T / \partial x}{(T/x)}$



N & N^a have the fixed same graph

for the graph

from $P_{in} = 0 \Rightarrow v^T i = 0 \Rightarrow e^T i = 0 \Rightarrow v^T i^a - v^{aT} i = 0$

$\Delta = \text{change}$ $\Delta(v^T i^a - v^{aT} i) = \Delta v^T \cdot i^a - v^{aT} \Delta i = 0$

keeps N^a fixed

assume that for branches of # > 2 that there is a γ matrix

$$[\Delta v_1, \Delta v_2, \Delta v_b]^T \cdot \begin{bmatrix} i_1^a \\ i_2^a \\ \vdots \\ i_b^a \end{bmatrix} - [v_1^a, v_2^a, v_b^a]^T \begin{bmatrix} \Delta i_1 \\ \Delta i_2 \\ \vdots \\ \Delta i_b \end{bmatrix} = 0$$

$i_b^a = \gamma_{b \times b} v_b^a, \Delta i_b^a = \Delta \gamma_{b \times b} v_b^a + \gamma_{b \times b} \Delta v_b^a$

$\Delta v_1 = 0$ as fixed branch one as a voltage source feeding N

$\Delta v_1 i_1^a + \Delta v_2 i_2^a + \Delta v_b^T \gamma_{b \times b}^a v_b^a - v_1^a \Delta i_1 - v_2^a \Delta i_2 - v_b^{aT} \Delta i_b = 0$

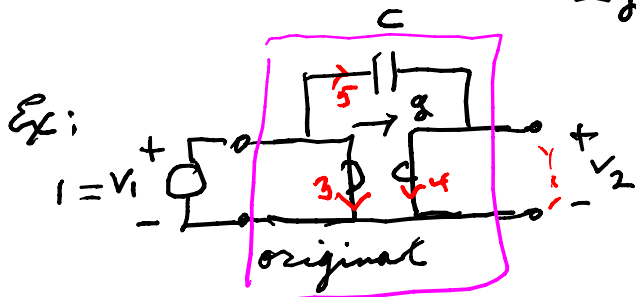


$\Delta v_2 \cdot 1 + \Delta v_b^T \gamma_{b \times b}^a v_b^a - v_b^{aT} [\Delta \gamma_{b \times b} v_b^a + \gamma_{b \times b} \Delta v_b^a] = 0$

$\Delta v_2 + \Delta v_b^T \gamma_{b \times b}^a v_b^a - v_b^{aT} \Delta \gamma_{b \times b} v_b^a - \Delta v_b^T \gamma_{b \times b}^a v_b^a = 0$

set $\Delta v_b^T Y_{b \times b}^a v_b^a - \Delta v_b^T Y_{b \times b}^T v_b^a = \Delta v_b^T [Y_{b \times b}^a - Y_{b \times b}^T] v_b^a = 0$
 \Rightarrow set $Y_{b \times b}^a = Y_{b \times b}^T$ this defines the adjoint circuit

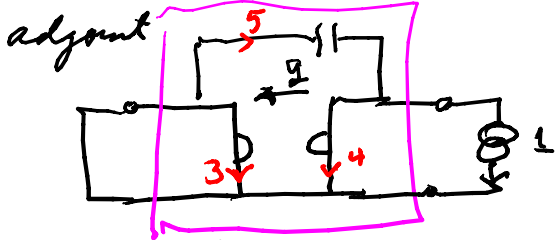
$\Delta v_2 = + v_b^{aT} \Delta Y_{b \times b} v_b^a$ if only a g_m changes $g_m = g_{12}$
 $\Rightarrow \Delta v_2 / 1 = + v_{b1}^a \Delta g_{12} v_2$
 $\Rightarrow \frac{\Delta v_2 / 1 = v_1}{\Delta g_{12}} = + v_{b1}^a v_2 = \frac{\partial v_2 / v_1}{\partial g_{12}}$ in the limit



$$Y_{b \times b} = \begin{bmatrix} 0 & g & 0 \\ -g & 0 & 0 \\ 0 & 0 & ac \end{bmatrix}$$

← 3
← 4
← 5

$T(ac) = \frac{v_2}{v_1}$



$$Y_{b \times b}^a = Y_{b \times b}^T = \begin{bmatrix} 0 & -g & 0 \\ g & 0 & 0 \\ 0 & 0 & ac \end{bmatrix}$$

$$\Delta v_2 = -v_b^{aT} \begin{bmatrix} 0 & \Delta g & 0 \\ -\Delta g & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} v_b^a$$

$$v_b = \begin{bmatrix} v_3 \\ v_4 \\ v_5 \end{bmatrix}, v_b^a = \begin{bmatrix} v_3^a \\ v_4^a \\ v_5^a \end{bmatrix}$$

$$\frac{\Delta v_2}{\Delta g} = -[v_3^a \ v_4^a] \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} v_3 \\ v_4 \end{bmatrix} = + v_4^a v_3 - v_3^a v_4$$

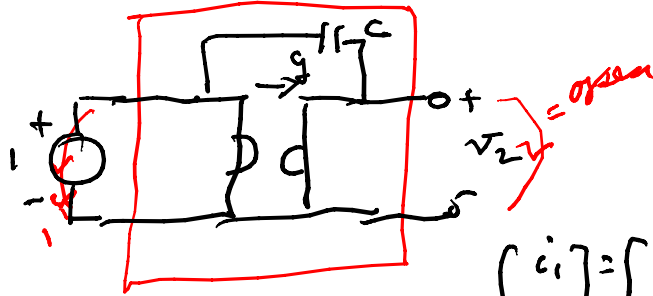
" " " " by $v_1^a = 0$
at $v_3 = v_1$

$v_4^a \Rightarrow -\frac{1}{ac} \times 1 \Rightarrow v_4^a = -\frac{1}{ac}$

$$\frac{\partial v_2}{\partial g} = + \frac{1}{ac}; \quad S_g = \frac{\partial (v_2/v_1)}{\partial g} = + \frac{1}{ac} \times \frac{g}{(1+g/ac)} = \frac{1}{1+ac/g}$$

↓ see v_2/v_1 below

as a check analyze for $T(ac) = v_2/v_1$



$$Y_{2-port} = \begin{bmatrix} 2C & -2C+g \\ -2C-g & 2C \end{bmatrix}$$

$$0 = \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} Y \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \Rightarrow 0 = y_{21}v_1 + y_{22}v_2$$

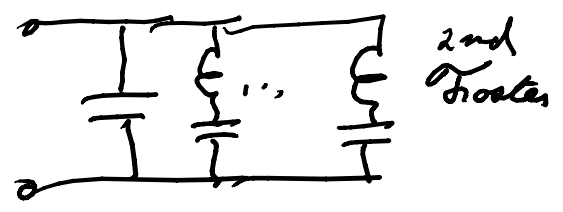
$$\frac{v_2}{v_1} = -\frac{y_{21}}{y_{22}} = \frac{-(-2C-g)}{2C} = 1 + \frac{g}{2C}; \quad \frac{\partial v_2/v_1}{\partial g} = \frac{1}{2C}$$

used on p. 393 in a hidden way. see N. Tenen & La Patra
(book on synthesis & analysis)

Passive RC circuits

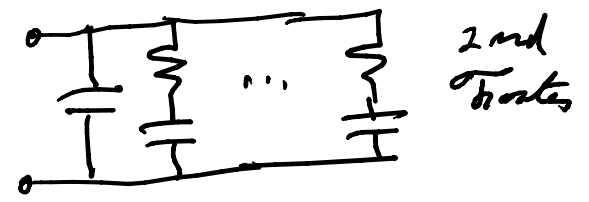
do from LC circuit

$$y_{LC}(s) = \sum_{i=0}^m \frac{k_i s}{s^2 + \omega_i^2} + Cs \Rightarrow$$



go to RC \Rightarrow let $L/s \Rightarrow R/s$

$$y_{i_{LC}} = \frac{k_i s}{s^2 + \omega_i^2} = \frac{1}{\frac{s}{k_i} + \frac{\omega_i^2}{k_i s}}$$



$$y_{i_{RC}} = \frac{1}{\frac{s}{k_i} + \frac{\omega_i^2}{k_i s}} \Rightarrow y_{RC} = \sum_{i=0}^m \frac{k_i s}{s^2 + \omega_i^2} + Cs \Rightarrow \text{all poles are on } -\sigma \text{ axis}$$

look at $\frac{y_{RC}}{s} = \sum_{i=0}^{\infty} \frac{k_i}{s^2 + \omega_i^2} + C$ is a partial fraction expansion with residues > 0