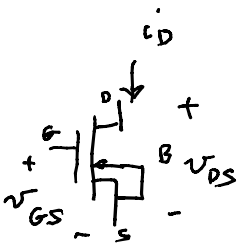
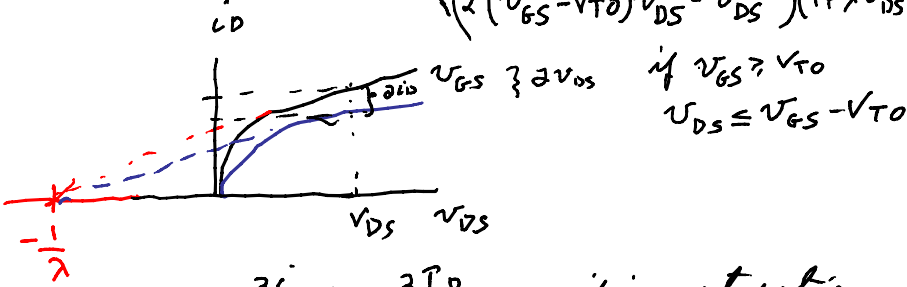


EE610
09/07/10

$$A \begin{bmatrix} C & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -L_1 & 0 \\ 0 & 0 & 0 & 0 & -L_2 \end{bmatrix} X = \begin{bmatrix} 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & -1 & -1 & -1 \\ G_0 - (g_m + G) & 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 \end{bmatrix} X$$



$$i_D = \frac{K_P \cdot W}{2 \cdot L} \begin{cases} (v_{GS} - V_{T0})^2 (1 + \lambda v_{DS}) & \text{if } v_{GS} \geq V_{T0} \\ 0 & \text{if } v_{GS} \leq V_{T0} \\ (2(v_{GS} - V_{T0})v_{DS} - v_{DS}^2) (1 + \lambda v_{DS}) & \text{if } v_{GS} \geq V_{T0} \\ & v_{DS} \leq v_{GS} - V_{T0} \end{cases}$$



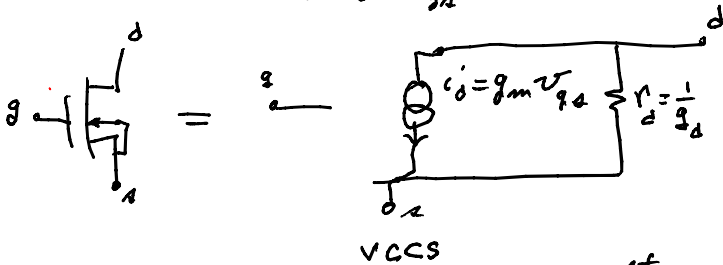
$$g_m = \left. \frac{\partial i_D}{\partial v_{GS}} \right|_{v_{DS} = v_{DS}} = \frac{2I_D}{(v_{GS} - V_{T0})} \quad \text{if in saturation}$$

(Q point)

$$i_D = I_D + i_d = I_D + \frac{\partial i_D}{\partial v_{GS}} (v_{GS} - v_{GS}) + \dots \text{ higher order terms}$$

total bias signal

$$i_d = g_m v_{gs}$$



$$g_d = \left. \frac{\partial i_D}{\partial v_{DS}} \right|_Q = \lambda \frac{I_D}{1 + \lambda v_{DS}} \quad ; \quad A = \frac{d}{dt} \quad ; \quad \omega \quad ; \quad A = \sigma + j\omega$$

$$A \begin{bmatrix} C & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -L_1 & 0 \\ 0 & 0 & 0 & 0 & -L_2 \end{bmatrix} X = \begin{bmatrix} 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & -1 & -1 & -1 \\ G_0 - (g_m + G) & 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 \end{bmatrix} X \quad ; \quad X = \begin{bmatrix} v_1 \\ v_2 \\ i_x \\ i_4 \\ i_5 \end{bmatrix}$$

semi-state

eliminate via 2nd row:

$$0 = -i_3 - i_4 - i_5 \Rightarrow i_3 = -i_4 - i_5$$

eliminate via 3rd row: $G_m = g_m + G_0$

$$0 = G_0 v_1 - G_m v_2 + i_3 \Rightarrow G_m v_2 = G_0 v_1 - i_4 - i_5$$

$$a c v_1 = a c x_1 = i_3 + i_5 = -i_4 - i_5 + i_5 = -i_4$$

$$-a L_1 i_4 = -a L_1 x_4 = -v_2 = -\frac{1}{G_m} [G_0 v_1 - i_4 - i_5] \quad ; \quad R_m = 1/G_m$$

$$-a L_2 i_5 = -a L_2 x_5 = v_1 - v_2 = v_1 - \frac{G_0}{G_m} v_1 + \frac{1}{G_m} i_4 + \frac{1}{G_m} i_5$$

$$a \begin{bmatrix} c & 0 & 0 \\ 0 & L_1 & 0 \\ 0 & 0 & L_2 \end{bmatrix} \underline{x} = \begin{bmatrix} 0 & -1 & 0 \\ R_m G_0 & -R_m & -R_m \\ (R_m G_0 - 1) & -R_m & -R_m \end{bmatrix} \underline{x} \quad \begin{matrix} \text{state} = \underline{x} = \\ \text{variable} \end{matrix} \begin{bmatrix} v_1 \\ i_4 \\ i_5 \end{bmatrix}$$

$$a \frac{1}{s} \underline{x} = \underline{E}^{-1} \underline{A} \underline{x} = \underline{A} \underline{x}$$

$$x(t) = e^{A t} x(0)$$

$$E = \begin{bmatrix} c & 0 & 0 \\ 0 & L_1 & 0 \\ 0 & 0 & L_2 \end{bmatrix}$$

$$E^{-1} = \begin{bmatrix} c^{-1} & 0 & 0 \\ 0 & 1/L_1 & 0 \\ 0 & 0 & 1/L_2 \end{bmatrix}$$

$$(sE - A) x(s) = x(0)$$

$$x(s) = (sE - A)^{-1} x(0)$$

$\det(sE - A) = 0$ solve for s but instead find L_1, L_2, C, G_m to oscillate

Choose $s = j\omega_0$ as oscillation "complex" frequency.

Work with the degree three polynomial in s

$$p(s) = \det(sE - A) = c_3 s^3 + c_2 s^2 + c_1 s + c_0$$

$$\det \begin{bmatrix} a c & 1 & 0 \\ -R_m G_0 & a L_1 + R_m & R_m \\ 1 - R_m G_0 & R_m & a L_2 + R_m \end{bmatrix} = a c \det \begin{bmatrix} a L_1 + R_m & R_m \\ R_m & a L_2 + R_m \end{bmatrix} - 1 \det \begin{bmatrix} -R_m G_0 & R_m \\ 1 - R_m G_0 & a L_2 + R_m \end{bmatrix}$$

$$= a c [(a L_1 + R_m)(a L_2 + R_m) - R_m^2] - [-a L_2 R_m G_0 - R_m^2 G_0 - R_m + R_m^2 G_0]$$

$$= L_1 L_2 C s^3 + (L_1 + L_2) R_m C s^2 + L_2 R_m G_0 s + R_m$$

= characteristic polynomial $p(s)$

$$P(j\omega_0) = -(L_1 + L_2) R_m C \omega_0^2 + R_m + j[-L_1 L_2 C \omega_0^3 + L_2 R_m G_0 \omega_0]$$

desire this = 0 for oscillator; $p(s) = C_0(s^2 + \omega_0^2)(s + \sigma_0)$

real = 0

$$-(L_1 + L_2)R_m C \omega_0^2 = -R_m \Rightarrow \omega_0^2 = \frac{1}{(L_1 + L_2)C} \Rightarrow \omega_0 = \frac{1}{\sqrt{(L_1 + L_2)C}}$$

as $R_m \neq 0$

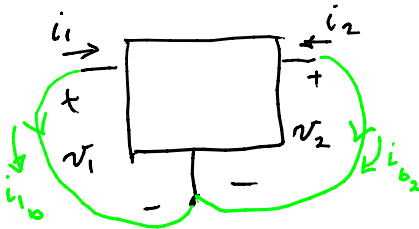
j term = 0

$$L_1 L_2 C \omega_0^2 = L_2 R_m G_0 \quad \text{as } \omega_0 \neq 0$$

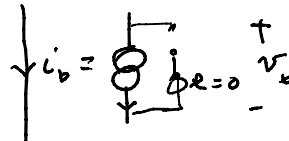
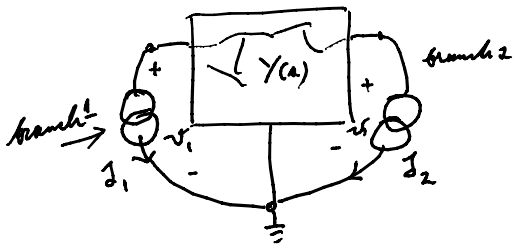
||

$$\frac{L_1 L_2 C}{(L_1 + L_2)C} = L_2 R_m G_0 \Rightarrow R_m = \frac{L_1}{G_0(L_1 + L_2)} = \frac{1}{g_m + G_0}$$

\therefore choose g_m to make it oscillate



$$Y(s) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} i_1 \\ i_2 \end{bmatrix}$$



$$i_b = i + j = j \quad \text{for 1st 2 branches}$$

$$v_b = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} \Bigg\} v_t$$

assume here no internal node but branches

$$v_b = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}_b = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$