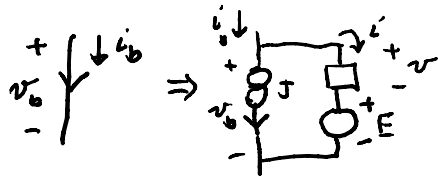


finite (have a bounded graph)

EE610  
09/17/09



$$i_b = J + i$$

$$v_b = E + v$$

$$v_b = \begin{bmatrix} v_t \\ v_r \end{bmatrix}, i_b = \begin{bmatrix} i_t \\ i_r \end{bmatrix}$$

KCL:  $0_t = e v_b$

$$i_b = \sigma^T i_r$$

KVL:  $0_r = \sigma i_b$

$$v_b = e^T v_t$$

Linear time-invariant,

$$Av = Bi$$

(assume A & B are  $b \times b$ )

Use these:  $i = i_b - J$ ,  $v = v_b - E$

$$A[v_b - E] = B[i_b - J] \Rightarrow Av_b - Bi_b = \underbrace{AE - BJ}_{\text{source term}}$$

$$\Rightarrow Ae^T v_t - B\sigma^T i_r = AE - BJ$$

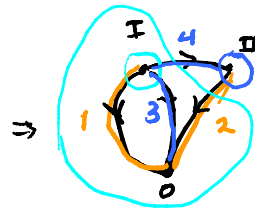
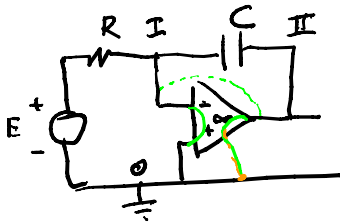
$$\underbrace{[Ae^T \quad -B\sigma^T]}_{b \times b} \underbrace{\begin{bmatrix} v_t \\ i_r \end{bmatrix}}_{b \times 1} = \underbrace{AE - BJ}_{b \times 1}$$

$$b = t + r$$

} b equations

& in general b unknowns

Ex:



$$b = 4$$

$$t = 2, r = 2$$

— tree  
— links  
or "theta"

cut set eqs:  $t \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} 1 & 1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} i_3 \\ i_4 \end{bmatrix}$

tie set eqs:  $r \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} v_3 \\ v_4 \end{bmatrix}$

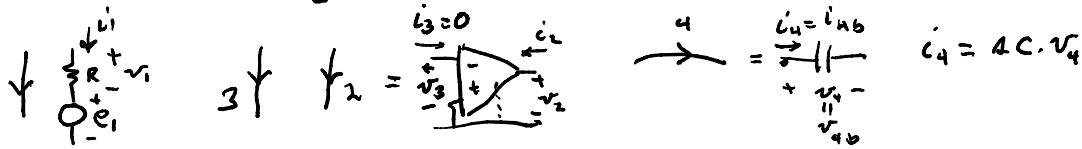


$$e^T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & -1 \end{bmatrix}, \sigma^T = \begin{bmatrix} -1 & -1 \\ 0 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix}$$

$$P_{in} = v_b^T i_b = v_t^T e^T \sigma^T i_r = 0$$

$$\Rightarrow e^T \sigma^T = 0_{t \times r}$$

$$AV = Bi \Rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & AC \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} = \begin{bmatrix} R & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \\ i_4 \end{bmatrix}$$



as  $\det A = 0$  &  $\det B = 0$  no Z or Y matrix for this "graph"

$$[AE^T \quad -B\mathcal{J}^T]$$

$$AE^T = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & AC \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 0 \\ AC & -AC \end{bmatrix}; \quad B\mathcal{J}^T = \begin{bmatrix} R & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & -1 \\ 0 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} -R & -R \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$E = \begin{bmatrix} e_1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \quad \mathcal{J} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}; \quad AE = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & AC \end{bmatrix} \begin{bmatrix} e_1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} e_1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & R & R \\ 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ AC & -AC & 0 & -1 \end{bmatrix} \begin{bmatrix} v_{t1} \\ v_{t2} \\ i_{x3} \\ i_{x4} \end{bmatrix} = \begin{bmatrix} e_1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

when solve will obtain all voltages & currents of the graph

$\Rightarrow -i_{x3} = 0$  (3rd eq.)  $\Rightarrow$  can eliminate row & column 3

$$\begin{bmatrix} 1 & 0 & R \\ 1 & 0 & 0 \\ AC & -AC & -1 \end{bmatrix} \begin{bmatrix} v_{t1} \\ v_{t2} \\ i_{x4} \end{bmatrix} = \begin{bmatrix} e_1 \\ 0 \\ 0 \end{bmatrix}$$

This has  $v_{t1} = 0$  ;  $0 = v_{t1} = -R i_{x4} + e_1 \Rightarrow i_{x4} = \frac{1}{R} e_1$

$$i_{x4} = AC v_{t1} - AC v_{t2} \Rightarrow v_{t2} = -\frac{1}{AC} i_{x4}$$