

if $V_{GS} < V_{TO}$
then $I_D = 0$

in saturation, for $V_{GS} > V_{TO}$ and

$$I_D = \frac{K_P}{2} \cdot \frac{W}{L} (V_{GS} - V_{TO})^2 (1 + \lambda V_{DS})$$

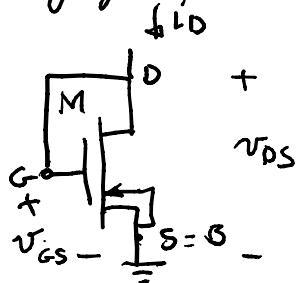
$V_{DS} > (V_{GS} - V_{TO})$
(for saturation)

in Ohmic (triode) region, for $V_{GS} > V_{TO}$,

$$I_D = \frac{K_P}{2} \cdot \frac{W}{L} (2(V_{GS} - V_{TO})V_{DS} - V_{DS}^2) (1 + \lambda V_{DS})$$

(checks at $V_{DS} = V_{GS} - V_{TO}$)

These are key formulas



here M is in saturation

$V_{TO} > 0$ for NMOS enhancement mode

$$V_{GS} - V_{TO} < V_{GS}$$

$$\text{here } V_{GS} = V_{DS}$$

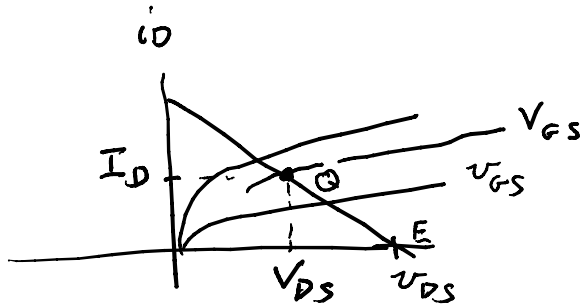
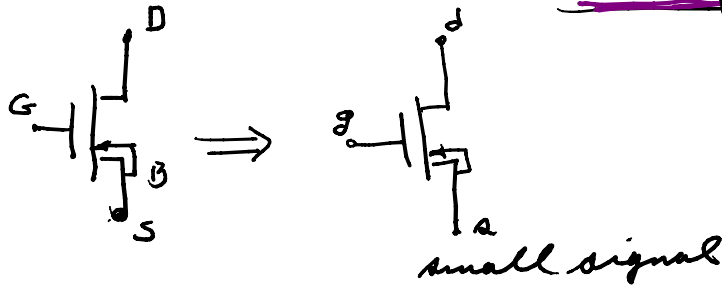
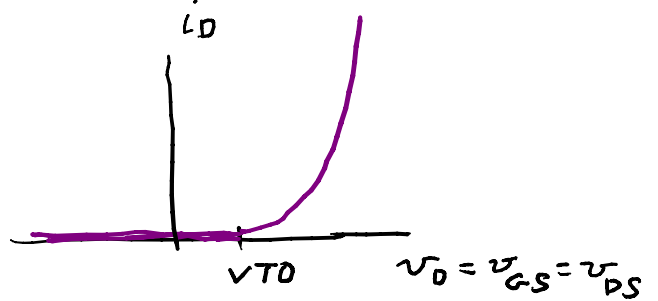
$$\text{or } V_{GS} - V_{TO} < V_{DS}$$

$$i_D = \frac{K_P W}{2 L} (v_{GS} - V_{TO})^2 (1 + \lambda v_{GS})$$

give a cubic law

$$\approx \frac{K_P W}{2 L} (v_{GS} - V_{TO})^2 \quad \text{if } v_{GS} > V_{TO}$$

(= 0 if $v_{GS} \leq V_{TO}$)



$$i_{DS} = f(v_{GS}, v_{DS})$$

$$= \begin{cases} 0 & \text{if } v_{GS} < V_{TO} \\ \frac{K_P W}{2 L} (v_{GS} - V_{TO})^2 (1 + \lambda v_{DS}) & \text{if } v_{GS} - V_{TO} < v_{DS} \\ \frac{K_P W}{2 L} (2(v_{GS} - V_{TO})v_{DS} - v_{DS}^2) (1 + \lambda v_{GS}) & \text{if } v_{GS} - V_{TO} > v_{DS} \end{cases}$$

$$i_{DS} = I_{DQ} + \frac{\partial i_D}{\partial v_{GS}} \bigg|_Q (v_{GS} - V_{GS}) + \frac{\partial i_D}{\partial v_{DS}} \bigg|_Q (v_{DS} - V_{DS}) + \frac{1}{2} \frac{\partial^2 i_{DS}}{\partial v_{GS} \partial v_{DS}} (v_{GS} - V_{GS})(v_{DS} - V_{DS}) + \dots$$

$i_D = i_a - I_D =$ signal drain current
 $=$ total - bias

$$= \frac{\partial i_D}{\partial v_{GS}} \bigg|_Q v_{gs} + \frac{\partial i_D}{\partial v_{DS}} \bigg|_Q v_{ds}$$

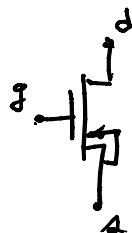
Q point

" " " " " "

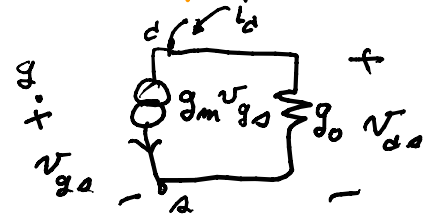
g_m " " " " " "

g_0 " " " " " "

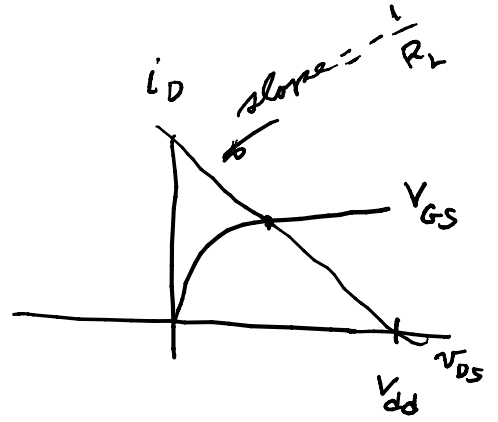
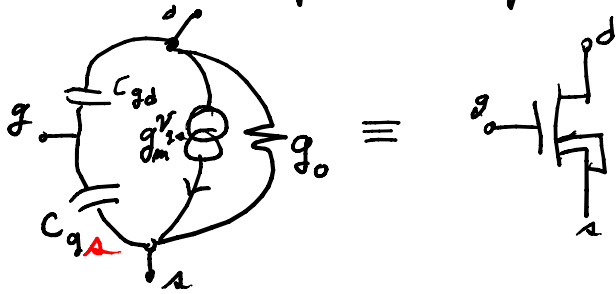
$$i_D = g_m v_{gs} + g_0 v_{ds}$$



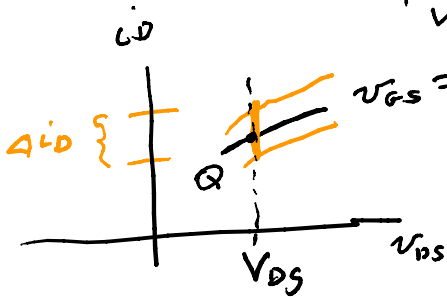
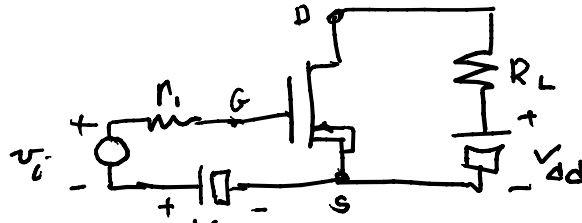
nonlinear terms
 ignore for small signals



also have a capacitor for the gate



To use:

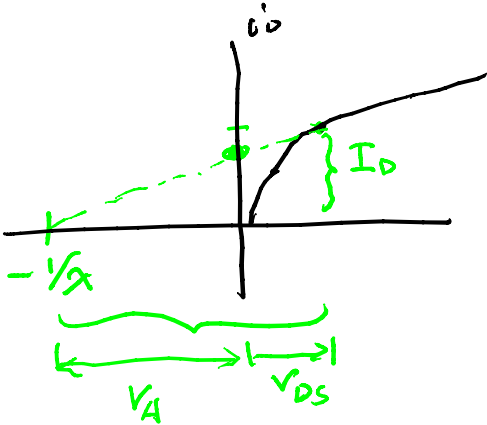


$$g_m = \left. \frac{\partial i_D}{\partial v_{GS}} \right|_Q$$

$v_{DS} = v_{DS} = \text{constant}$
about $v_{GS} = V_{GS}$

$$g_o = \left. \frac{\partial i_D}{\partial v_{DS}} \right|_Q$$

$$\approx \frac{I_D}{V_{DS} + V_A} \approx \frac{I_D}{V_A} = \lambda I_D$$



if in saturation

$$i_D = \frac{K_p \mu}{2 L} (v_{GS} - V_{T0})^2 (1 + \lambda v_{DS})$$

$$g_m = \frac{K_p \mu}{2 L} \cdot 2 (v_{GS} - V_{T0}) (1 + \lambda v_{DS}) \Big|_Q$$

$$= \frac{2 I_D}{V_{GS} - V_{T0}}$$