

$$y(s) = \left( \frac{s-1}{s+2} \right)^2$$

Re for  $s = \sigma > 0$

EE 610  
10/08/07

no pole in  $\sigma > 0$ , poles at  $s = -2$

$$\text{Re } y(s), \quad s = \sigma + j\omega; \quad \sigma > 0$$

$$\text{Re}(y(s)) = \frac{1}{2} [y(s) + y(s)^*], \quad * \Rightarrow j \rightarrow -j, \quad j = \sqrt{-1}$$

$$2 \text{Re}(y(s)) = \left( \frac{\sigma + j\omega - 1}{s+2} \right)^2 + \left( \frac{\sigma - j\omega - 1}{s^*+2} \right)^2$$

$$= \frac{(\sigma + j\omega - 1)^2 (\sigma - j\omega + 2)^2 + (\sigma - j\omega - 1)^2 (\sigma + j\omega + 2)^2}{(s+2)(s^*+2)^2}$$

$$= 2 |s+2|^2 \text{Re } y(s) = \left( (\sigma + j\omega)(\sigma - j\omega) - \sigma + j\omega + 2\sigma + 2j\omega - 2 \right)^2 + \left( (\sigma + j\omega)(\sigma - j\omega) - \sigma - j\omega + 2\sigma - 2j\omega - 2 \right)^2$$

$$= \left( [\sigma^2 + \omega^2 + \sigma - 2] + j3\omega \right)^2 + \left( [\sigma^2 + \omega^2 + \sigma - 2] - j3\omega \right)^2$$

$$= [\sigma^2 + \omega^2 + \sigma - 2]^2 - 9\omega^2 + j3\omega[\sigma^2 + \omega^2 + \sigma - 2] - j3\omega[\sigma^2 + \omega^2 - 2] + [\sigma^2 + \omega^2 + \sigma - 2]^2 - 9\omega^2$$

choose  $\sigma = 1, \omega = 1 \quad 1^2 - 9 < 0 \Rightarrow y(s)$  is not positive real

For this  $y(s)$ ,  $\text{Ev}(y(s)) = \frac{1}{2}(y + y^*)$ , lower  $s \rightarrow -s$

$$2 \text{Ev } y(s) = \left( \frac{s-1}{s+2} \right)^2 + \left( \frac{-s-1}{-s+2} \right)^2 = \frac{(s-1)^2(-s+2)^2 + (s+1)^2(s+2)^2}{(s+2)(-s+2)}$$

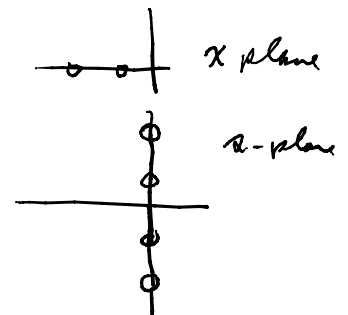
Zeros of  $\text{Ev } y(s)$  are zeros of  $(s-1)^2(-s+2)^2 + (s+1)^2(s+2)^2$

$$= (s^2 - 2s + 1)(s^2 - 4s + 4) + (s^2 + 2s + 2)(s^2 + 4s + 4)$$

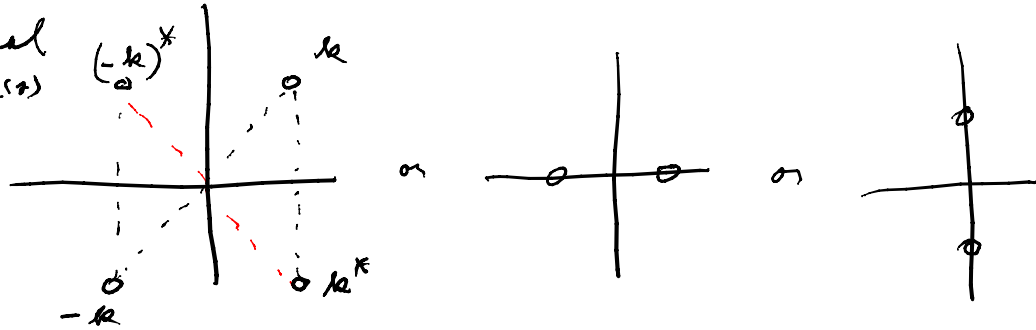
$$= 2[s^4 + 4s^2 + 8s + s^2 + 4] = 2[s^4 + 13s^2 + 4]$$

$$x = s^2 \Rightarrow x^2 + 13x + 4 = 0; \quad x = -\frac{13}{2} \pm \sqrt{\left(\frac{13}{2}\right)^2 - 4}$$

$$s_{1,2,3,4} = \pm \sqrt{-\frac{13}{2} \pm \sqrt{\left(\frac{13}{2}\right)^2 - 4}}$$



In general  
zeros of  $\mathcal{E}r y(s)$



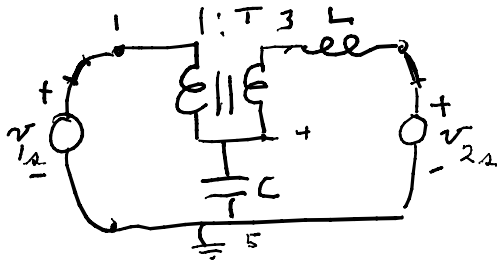
In Richards' function notes, let  $k_2 = k_1^*$

coeff. of  $s^2$  in numerator  $\frac{k_1 y(k_2) - k_2 y(k_1)}{k_1 k_2 [k_1 y(k_1) - k_2 y(k_2)]}$

$$= \frac{k_1 y(k_1^*) - k_1^* y(k_1)}{|k_1|^2 [k_1 y(k_1) - k_1^* y(k_1^*)]}$$

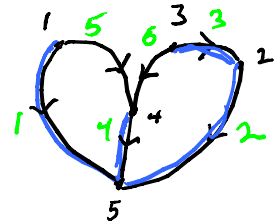
$y(s^*) = y^*(s)$  if PR as  
real coefficients  
(if rational)

$$= \frac{k_1 y^*(k_1) - (k_1 y(k_1))^*}{|k_1|^2 [k_1 y(k_1) - (k_1 y(k_1))^*]} = \frac{2j \operatorname{Im}(k_1 y^*(k_1))}{|k_1|^2 \times 2j \operatorname{Im}(k_1 y(k_1))} = \text{purely real}$$



choose output

$$y = \begin{bmatrix} -i_1 \\ -i_2 \end{bmatrix}$$



here  $i_1 = -i_5 = -x_5$ ,  $i_2 = -i_6 = -x_6$

$$y = \text{output} = \begin{bmatrix} -x_5 \\ -x_6 \end{bmatrix}$$

$$y = Cx = \begin{bmatrix} 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix}$$

= semistate =  $x = \begin{bmatrix} v_1 \\ i_2 \end{bmatrix}$

changed  $x$  state to  $x_{st}$

In terms of the state:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 1-T & 0 \\ 0 & -T \end{bmatrix} \begin{bmatrix} x_4 \\ x_6 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ T & -1 \\ 0 & 0 \end{bmatrix} u \Rightarrow x_6 = x_{2st}$$

$$x_5 = -T x_6 = -T x_{2st}$$

$$-y = \begin{bmatrix} 0 & +T \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x_{1\text{total}} = x_4 \\ x_{2\text{total}} = x_6 \end{bmatrix} = \begin{bmatrix} -x_5 \\ -x_6 \end{bmatrix}$$

or  
output

$$y = \begin{bmatrix} 0 & +T \\ 0 & -1 \end{bmatrix} x_{\text{out}} + \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} u = Cx_{\text{out}} + D$$

$$\frac{d}{dt} \begin{bmatrix} x_4 \\ x_6 \end{bmatrix} = \begin{bmatrix} 0 & \frac{-T+1}{C} \\ \frac{T-1}{L} & 0 \end{bmatrix} \begin{bmatrix} x_4 \\ x_6 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ -\frac{T}{L} & \frac{1}{L} \end{bmatrix} u \quad \left. \begin{array}{l} \text{state eqs.} \\ \text{from last} \\ \text{time} \end{array} \right\}$$

$$y = \begin{bmatrix} 0 & +T \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x_4 \\ x_6 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} u \quad \left. \begin{array}{l} \text{from line above} \end{array} \right\}$$

To get the transfer function take Laplace transform

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \mathcal{L}[y] = \begin{bmatrix} 0 & +T \\ 0 & -1 \end{bmatrix} \left[ sI_2 - \begin{bmatrix} 0 & \frac{-T+1}{C} \\ \frac{T-1}{L} & 0 \end{bmatrix} \right]^{-1} \begin{bmatrix} 0 & 0 \\ -\frac{T}{L} & \frac{1}{L} \end{bmatrix} \mathcal{L}[u] \quad \text{" } \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

2 port

$$\therefore Y(s) = \begin{bmatrix} 0 & T \\ 0 & -1 \end{bmatrix} \begin{bmatrix} s & \frac{T-1}{C} \\ \frac{T-1}{L} & s \end{bmatrix}^{-1} \begin{bmatrix} 0 & 0 \\ -\frac{T}{L} & \frac{1}{L} \end{bmatrix} ; \det(sI_2 - A) = s^2 + \frac{(T-1)^2}{LC}$$

2 port admittance

$$= \begin{bmatrix} 0 & T \\ 0 & -1 \end{bmatrix} \frac{1}{s^2 + \frac{(T-1)^2}{LC}} \begin{bmatrix} s & \frac{T-1}{C} \\ \frac{T-1}{L} & s \end{bmatrix} \begin{bmatrix} 0 & 0 \\ -\frac{T}{L} & \frac{1}{L} \end{bmatrix}$$

$$= \frac{-1}{s^2 + \frac{(T-1)^2}{LC}} \begin{bmatrix} \frac{T^2-T}{L} & sT \\ \frac{1-T}{L} & -s \end{bmatrix} \begin{bmatrix} 0 & 0 \\ -\frac{T}{L} & \frac{1}{L} \end{bmatrix} = \frac{-1}{s^2 + \frac{(T-1)^2}{LC}} \begin{bmatrix} -sT^2/L & sT/L \\ sT/L & -s/L \end{bmatrix}$$

$$= \frac{s/L}{s^2 + \frac{(T-1)^2}{LC}} \begin{bmatrix} T^2 & -T \\ -T & 1 \end{bmatrix} \times (-1) \quad \text{Handwritten: } \times (-1) \quad = \frac{s/L}{s^2 + \frac{(T-1)^2}{LC}} \begin{bmatrix} -T \\ 1 \end{bmatrix} \begin{bmatrix} -T & 1 \end{bmatrix}$$