

Problem 1

①

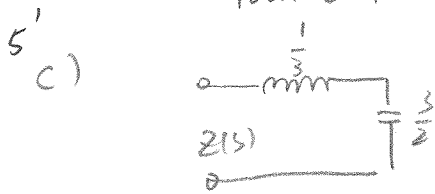
$$P(s) = s^6 + 3s^5 + 4s^4 + 6s^3 + 5s^2 + 3s + 2$$

$$5' a) \quad Z(s) = \frac{Ev P(s)}{Od P(s)} = \frac{s^6 + 4s^4 + 5s^2 + 2}{3s^5 + 6s^3 + 3s}$$

$$5' b) \quad \begin{array}{r} \frac{1}{3}s \\ \hline 3s^5 + 6s^3 + 3s \quad \sqrt{s^6 + 4s^4 + 5s^2 + 2} \\ \underline{s^6 + 2s^4 + s^2} \qquad \frac{3}{2}s \\ 2s^4 + 4s^2 + 2 \quad \sqrt{3s^5 + 6s^3 + 3s} \\ \underline{3s^5 + 6s^3 + 3s} \\ 0 \end{array}$$

$$Z(s) = \frac{1}{3}s + \frac{1}{\frac{3}{2}s} = \frac{s^2 + 2}{3s}$$

Positive Real and lossless



15' d)

$$\begin{array}{r} s^4 + 2s^2 + 1 \\ \hline s^2 + 3s + 2 \quad \sqrt{s^6 + 3s^5 + 4s^4 + 6s^3 + 5s^2 + 3s + 2} \\ \underline{s^6 + 3s^5 + 2s^4} \\ 2s^4 + 6s^3 + 5s^2 + 3s + 2 \\ \underline{2s^4 + 6s^3 + 4s^2} \\ s^2 + 3s + 2 \\ \underline{s^2 + 3s + 2} \\ 0 \end{array}$$

$$P(s) = s^6 + 3s^5 + 4s^4 + 6s^3 + 5s^2 + 3s + 2$$

$$P_1(s) = s^2 + 3s + 2$$

5' if conclude that $P_2(s)$ is HP.

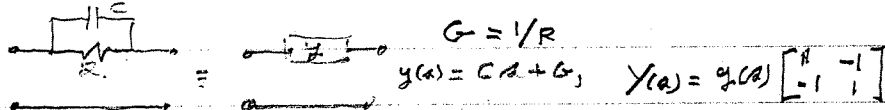
$$\therefore P(s) = P_1(s) \cdot P_2(s)$$

$Z(s) = \frac{s^2 + 2}{3s}$ is a reactance function $\Rightarrow P_1(s)$ is Hurwitz polynomial

$P_2(s) = s^2 + 2s + 1$ clearly not a Hurwitz 1st and 3rd order cofactor = 0

$\therefore P(s) = P_1(s) \cdot P_2(s)$ not Hurwitz.

#2



$$y_i = \frac{1}{s + z_L} = \frac{1}{\frac{1}{y} + \frac{1}{z_L}} = \frac{y z_L}{y + z_L}$$

also found by $i_2 = -y_L v_2 = y_{21} v_1 + y_{22} v_2 \Rightarrow (y_L + y_{22}) v_2 = -y_{21} v_1$

$$i_1 = y_{11} v_1 + y_{12} v_2 = (y_{11} - \frac{y_{12} y_{21}}{y_L + y_{22}}) v_1 = \frac{\Delta Y + y_{11} y_L}{y_{22} + y_L} v_1$$

$$\therefore y_L = \frac{\Delta Y + y_{11} y_L}{y_{22} + y_L} \quad \text{where } \Delta Y = 0 \text{ here}$$

$$\Rightarrow y_L y_{22} + y_L^2 = \Delta Y + y_{11} y_L \Rightarrow (y_L - y_{11}) y_L = \Delta Y - y_{22} y_L$$

$$\Rightarrow y_L = \frac{\Delta Y - y_{22} y_L}{y_L - y_{11}} \quad \therefore y_L = \frac{y y_L}{y + y_L} \quad \& \quad y_L = \frac{y y_L}{y - y_L}$$

$$y_i = \frac{(sC + G) y_L}{(sC + G) + y_L} \quad ; \quad y_L = \frac{(sC + G) y_L}{(sC + G) - y_L} = \frac{1}{z_i - \frac{1}{sC + G}}$$

$$\Rightarrow z_L = z_i - \frac{1}{sC + G}$$

$$\text{for } y_L = PR \Rightarrow z_L = PR \Rightarrow \exists \text{ pole in } z_L \text{ @ } s = -C/G$$

\therefore for degree reduction $\frac{1}{y_i} = z_i$ has a simple pole at $s_0 = \sigma_0 \leq 0$ necessarily must choose $C/G = \sigma_0$ for degree reduction (if at $\sigma_0 = 0, G = 0$)

if $z_i = \frac{1}{sC + G} + z_2$ then, as degree reduction was forced, z_2 must be PR

\therefore necessary & sufficient

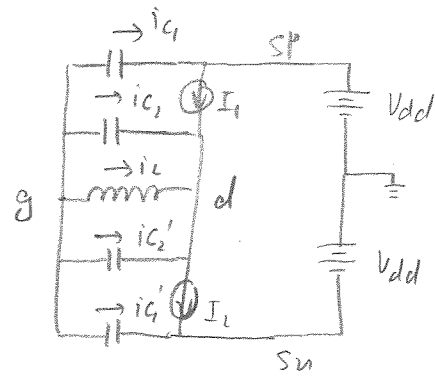
$$\frac{1}{y_i} = \frac{k_0}{s - s_0} + z_2, \quad s_0 \leq 0, k_0 > 0, z_2 = PR$$

& no pole @ s_0

problem 3:

$$x = [i_L, v_g, v_L]^T$$

20' a) state variable equation



$$v_L = L \frac{di_L}{dt} \Rightarrow \frac{di_L}{dt} = \frac{1}{L} v_L \quad \text{--- (1)}$$

$$I_1 + i_{c2} + i_L + i_{c2}' - I_2 = 0$$

$$i_{c2} = i_{c2}' = C_2 \frac{dv_L}{dt}$$

$$\therefore 2C_2 \frac{dv_L}{dt} = I_2 - I_1 - i_L$$

$$\begin{aligned} I_2 - I_1 &= \beta (V_g + V_{dd} - V_{T0})^2 - \beta (V_g - V_{dd} - V_{T0})^2 \\ &= \beta (2V_g - 2V_{T0})(2V_{dd}) = 4\beta V_{dd} (V_g - V_{T0}) \end{aligned}$$

$$\therefore 2C_2 \frac{dv_L}{dt} = 4\beta V_{dd} (V_g - V_{T0}) - i_L$$

$$\therefore \frac{dv_L}{dt} = -\frac{1}{2C_2} i_L + \frac{2\beta V_{dd}}{C_2} V_g - \frac{2\beta V_{dd} V_{T0}}{C_2} \quad \text{--- (2)}$$

$$\begin{aligned} i_{c1} + i_{c2} + i_L + i_{c2}' + i_{c1}' &= 0 \\ I_1 + i_{c2} + i_L + i_{c2}' - I_2 &= 0 \end{aligned} \quad \Rightarrow \quad i_{c1} + i_{c1}' = I_1 - I_2$$

$$i_{c1} = i_{c1}' = C_1 \frac{dv_g}{dt}$$

$$\therefore \frac{dv_g}{dt} = -\frac{2\beta V_{dd}}{C_1} V_g + \frac{2\beta V_{dd} V_{T0}}{C_1} \quad \text{--- (3)}$$

$$\begin{aligned} \frac{di_L}{dt} &= \frac{1}{L} v_L \\ \frac{dv_g}{dt} &= -\frac{2\beta V_{dd}}{C_1} V_g + \frac{2\beta V_{dd} V_{T0}}{C_1} \\ \frac{dv_L}{dt} &= -\frac{1}{2C_2} i_L + \frac{2\beta V_{dd}}{C_2} V_g - \frac{2\beta V_{dd} V_{T0}}{C_2} \end{aligned}$$

5' for each equation
3 for 20'

$$\frac{d}{dt} \begin{bmatrix} i_L \\ v_g \\ v_L \end{bmatrix} = \begin{bmatrix} 0 & 0 & \frac{1}{L} \\ 0 & -\frac{2\beta V_{dd}}{C_1} & 0 \\ -\frac{1}{2C_2} & \frac{2\beta V_{dd}}{C_2} & 0 \end{bmatrix} \begin{bmatrix} i_L \\ v_g \\ v_L \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{2\beta V_{dd} V_{T0}}{C_1} \\ -\frac{2\beta V_{dd} V_{T0}}{C_2} \end{bmatrix}$$

Problem 5.

10' b) linearize the state variable equation

$$\frac{d}{dt} \begin{bmatrix} i_L \\ v_g \\ v_c \end{bmatrix} = \begin{bmatrix} 0 & 0 & \frac{1}{L} \\ 0 & -\frac{2\beta V_{dd}}{C_1} & 0 \\ -\frac{1}{2C_2} & \frac{2\beta V_{dd}}{C_2} & 0 \end{bmatrix} \begin{bmatrix} i_L \\ v_g \\ v_c \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & 0 & \frac{1}{L} \\ 0 & -\frac{2\beta V_{dd}}{C_1} & 0 \\ -\frac{1}{2C_2} & \frac{2\beta V_{dd}}{C_2} & 0 \end{bmatrix}$$

$$\det(sI_3 - A) = \begin{vmatrix} s & 0 & -\frac{1}{L} \\ 0 & s + \frac{2\beta V_{dd}}{C_1} & 0 \\ \frac{1}{2C_2} & -\frac{2\beta V_{dd}}{C_2} & s \end{vmatrix} = s^2 \left(s + \frac{2\beta V_{dd}}{C_1} \right) + \frac{1}{2LC_2} \left(s + \frac{2\beta V_{dd}}{C_1} \right)$$

↑
+s' for easily this without solving $s_{1,2,3}$

$$\therefore \det(sI_3 - A) = \left(s + \frac{1}{2LC_2} \right) \left(s + \frac{2\beta V_{dd}}{C_1} \right)$$

Natural frequency: $s_{1,2} = \pm j / \sqrt{2LC_2}$ $s_3 = -\frac{2\beta V_{dd}}{C_1}$

5' c) oscillation frequency.

$$\omega = \frac{1}{\sqrt{2LC_2}}$$

$$\text{or } f = \frac{1}{2\pi \sqrt{2LC_2}}$$