

Semistate:

P. 1

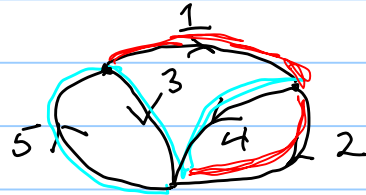
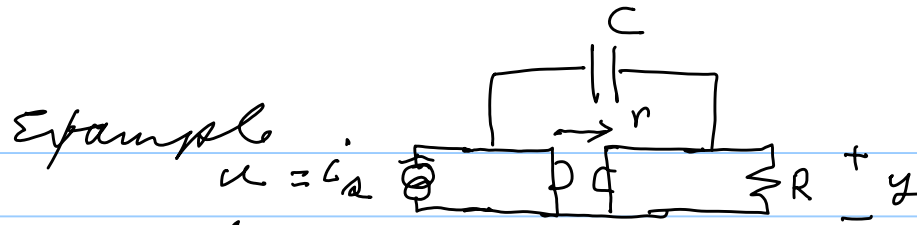
$$E \frac{dx}{dt} = Ax + Bu; \quad y = Cx$$

$x = \text{semistate}$ ;  $E$  could be singular;  
assume for now  $E, A, B, C$  are constant  
matrices

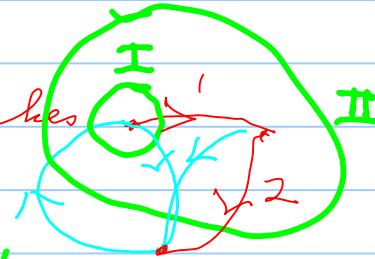
will choose for now  $x = \begin{bmatrix} v_t \\ i_r \end{bmatrix}$

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— = tree branches  
— = link branches



KCL

$$\text{I} \Rightarrow 0 = i_{1b} + i_{3b} - i_{5b}$$

$$\text{II} \Rightarrow 0 = i_{2b} + i_{3b} + i_{4b} - i_{5b} \Rightarrow \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \\ i_3 \\ i_4 \\ i_5 \end{bmatrix}_b$$

KVL

$$\begin{matrix} 3 \rightarrow \text{I} \\ 4 \rightarrow \text{II} \\ 5 \rightarrow \text{III} \end{matrix} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} -1 & -1 & 1 & 0 & 0 \\ 0 & -1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \end{bmatrix}_b$$

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assume an admittance matrix for all branches

$$Y_{bb} = \begin{bmatrix} CA & 0 & 0 & 0 & 0 \\ 0 & G & 0 & 0 & 0 \\ 0 & 0 & 0 & -g0 & 0 \\ 0 & 0 & g & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$Y_{sys} = Z_{sys}^{-1} = \begin{bmatrix} 0 & -g \\ g & 0 \end{bmatrix} \quad \text{if } g = \frac{n}{r2}$$

$$Z_{sys} = \begin{bmatrix} 0 & r \\ -r & 0 \end{bmatrix} \quad = \frac{1}{n}$$

$$Av = B\dot{i} \Rightarrow Y_{bb}v = 1_b \dot{i} \quad b=5$$

$$v = v_b - \mathcal{Q} \Rightarrow v = v_b = e^T v_t \Rightarrow Ae^T v_t = B(i_b - j)$$

$$i = i_b - j$$

$$= 1_5 (\mathcal{Q}^T i_{\mathcal{Q}} - j)$$

$$\text{or } [Ae^T \mid -B\mathcal{Q}^T] \begin{bmatrix} v_t \\ i_{\mathcal{Q}} \end{bmatrix} = Ae - Bj$$

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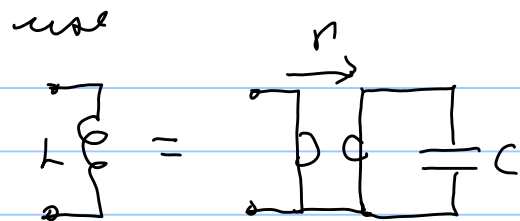
$$Y_{bb} C^T = A C^T = \begin{bmatrix} c_1 & c_2 & c_3 & c_4 & c_5 \\ 0 & -g & 0 & 0 & 0 \\ g & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \\ 1 & 1 \\ 0 & -1 \\ -1 & -1 \end{bmatrix} = \begin{bmatrix} c_1 & c_2 & c_3 & c_4 & c_5 \\ 0 & -g & 0 & 0 & 0 \\ 0 & 0 & 0 & -g & 0 \end{bmatrix}$$

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$$\begin{bmatrix} c_1 & 0 & 1 & 0 & -1 \\ 0 & -g & 1 & 1 & -1 \\ 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \frac{dx}{dt} = \begin{bmatrix} 0 & 0 & -1 & 0 & 1 \\ 0 & -g & -1 & -1 & 1 \\ 0 & g & 1 & 0 & 0 \\ -g & -g & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} x + \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ -1 \end{bmatrix} u$$

$$z = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \end{bmatrix} x$$



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