

Van der Pol

$$\dot{x}_1 = x_2$$

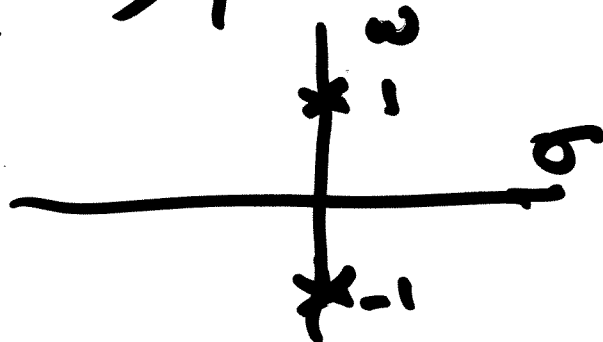
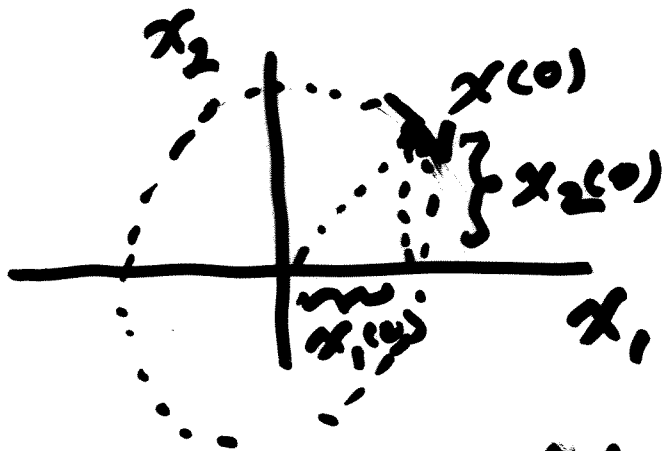
$$\dot{x}_2 = -x_1$$

$$\cdot = d/dt$$

$$x(0) \text{ given, } x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\Rightarrow \ddot{x}_1 = \dot{x}_2 = -x_1 \Rightarrow \ddot{x}_1 + x_1 = 0$$

$$(\omega^2 + 1)x_1 = 0$$



$$\frac{dx_2}{dx_1} = \frac{dx_2/dt}{dx_1/dt} = \frac{-x_1}{x_2} = \frac{-1}{x_2/x_1}$$

$$= \frac{-1}{\text{slope of vector (from origin)}}$$

gives circles as limit cycles
which depend on initial

conditions. These are structurally unstable if add positive resistance makes it structurally stable but the limit cycle is the origin.

$$\frac{dx_1}{dt} = x_2 - f(x_1) \quad ; \text{ if } f(x_1) = x_1$$

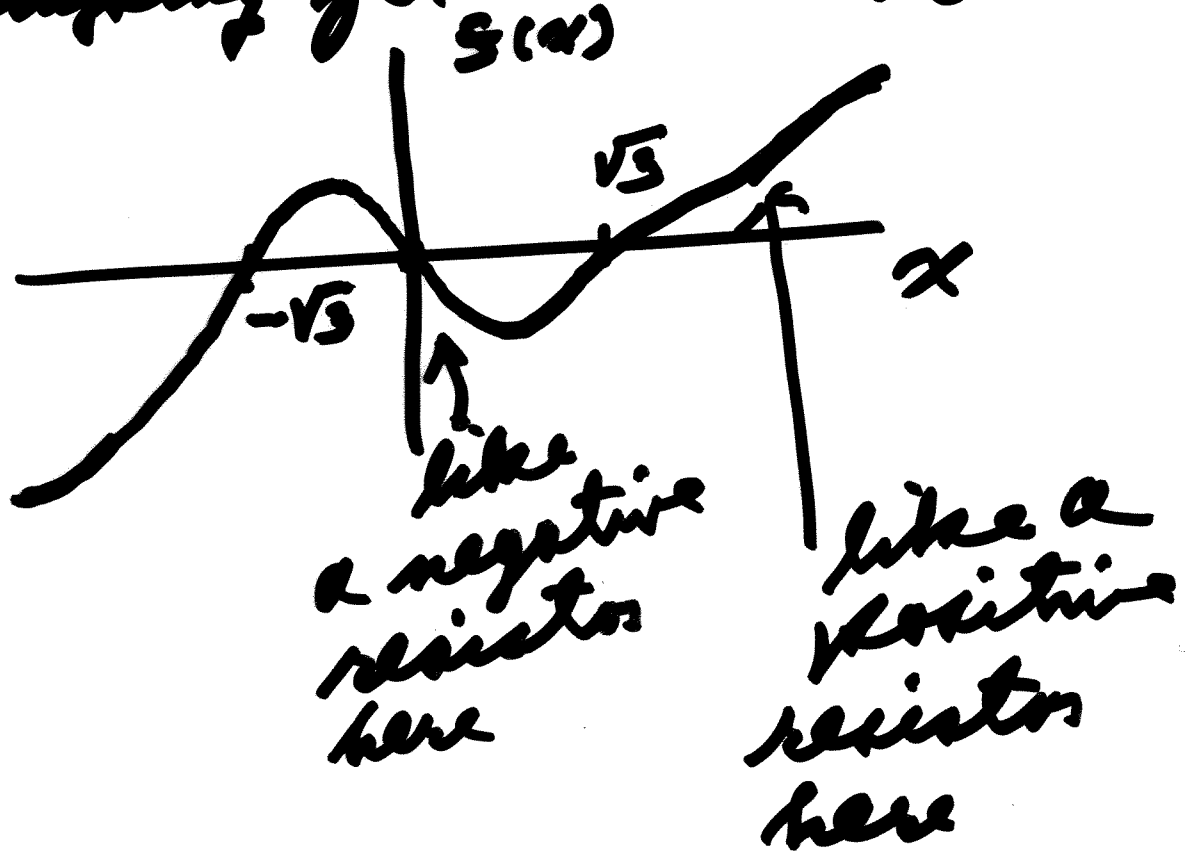
$$\frac{dx_2}{dt} = -x_1$$

This damps force to $x(t) = 0$

By adding $f(x_1)$ can make a structurally stable limit cycle ($\neq 0$).

Choose $\epsilon x \left(\frac{x^2}{3} - 1 \right) = f(x)$
gives positive damping

EE 610 10/23/02 p.3
 for large ϵ & negative
 damping for small ϵ ; $\epsilon > 0$



$$\frac{dx_1}{dt} = x_2 - \epsilon x_1 \left(\frac{1}{3} x_1^2 - 1 \right)$$

$$\frac{dx_2}{dt} = -x_1$$

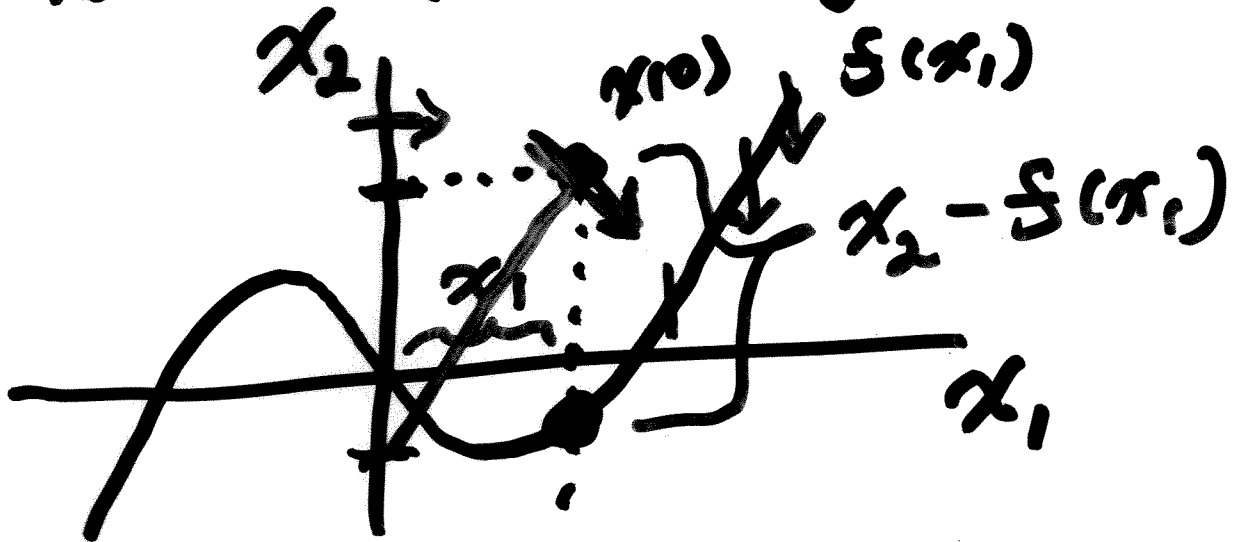
$$\begin{aligned} \ddot{x}_1 &= \dot{x}_2 - \epsilon \left[\frac{2}{3} x_1 \right] \cdot \frac{dx_1}{dt} \\ &= -x_1 - \epsilon (x_1^2 - 1) \dot{x}_1 \end{aligned}$$

EE 610 10/23/02 r.4

$$\ddot{x}_1 + \epsilon(x_1^2 - 1)\dot{x}_1 + x_1 = 0$$

need $x_1(0), \dot{x}_1(0)$

state space trajectory:



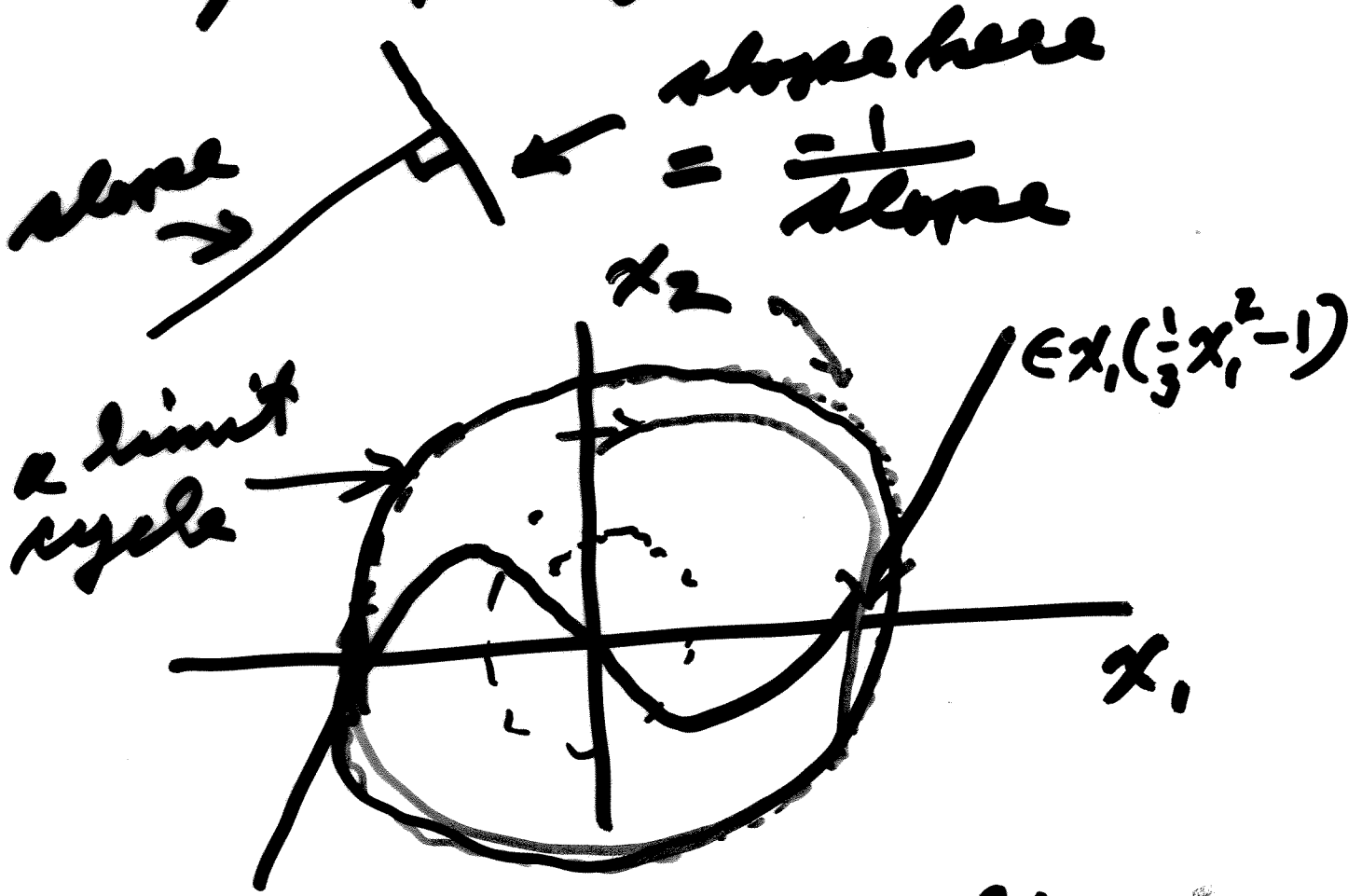
$$\frac{dx_1}{dt} = x_2 - S(x_1)$$

$x(0)$
given

$$\frac{dx_2}{dt} = -x_1$$

$$\begin{aligned} \frac{dx_2}{dx_1} &= \frac{dx_2/dt}{dx_1/dt} = \frac{-x_1}{x_2 - S(x_1)} \\ &= -\frac{[x_2 - S(x_1)]}{x_1} \end{aligned}$$

note: The slope of
a line \perp to line is
 $-1/\text{slope of the line}$



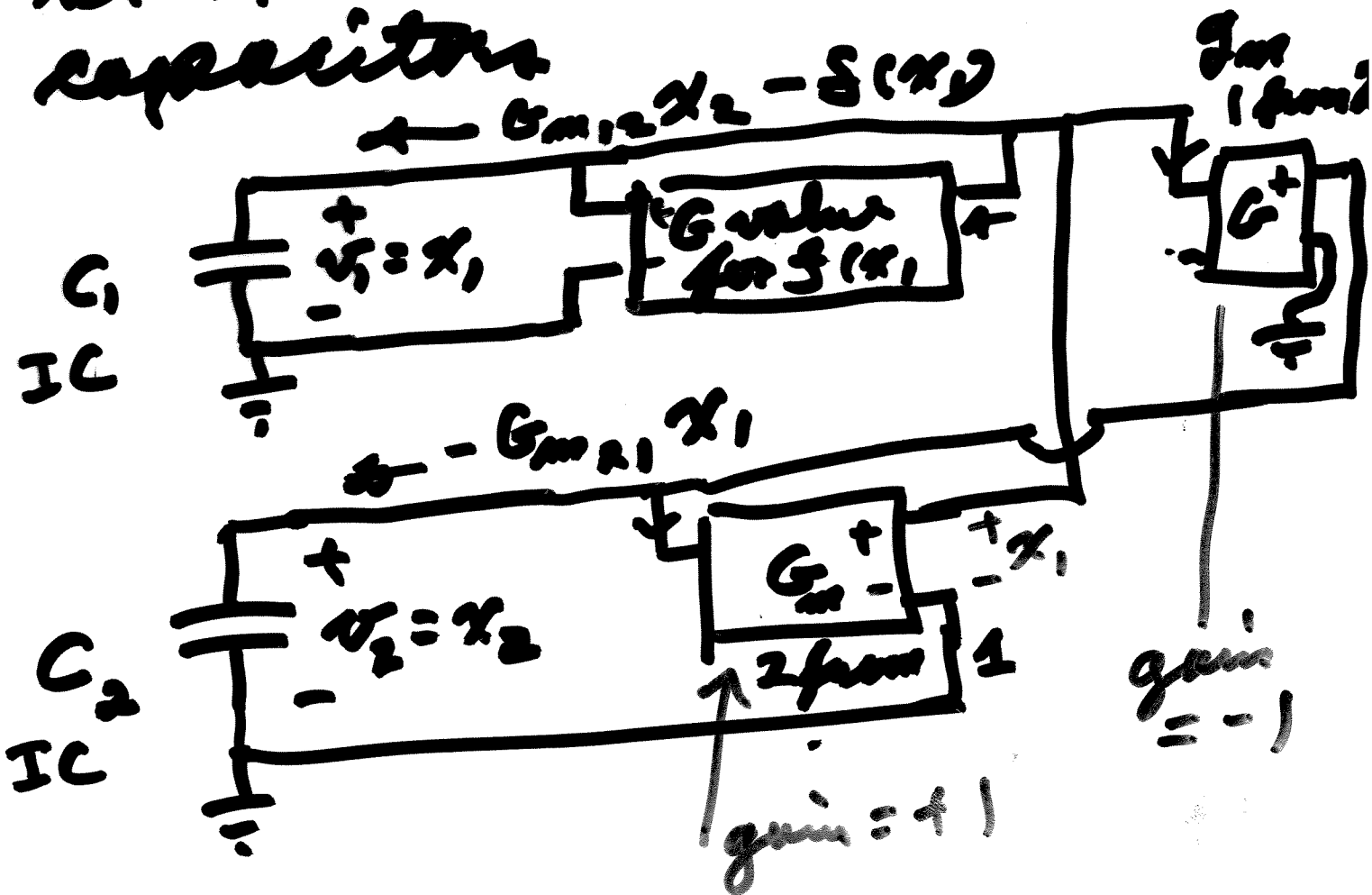
Use a piecewise linear curves

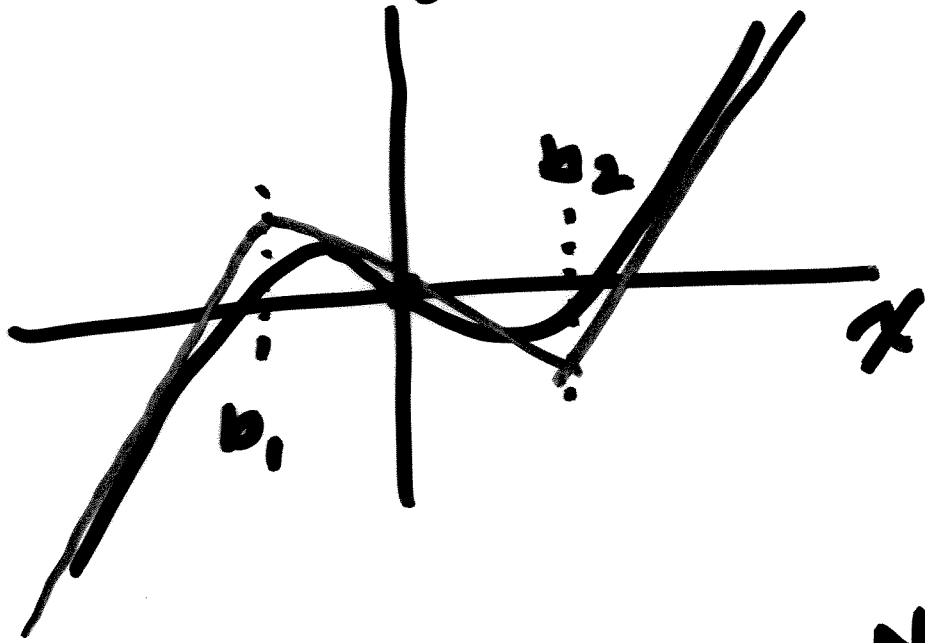
$$C_1 \frac{dx_1}{dt} = G_{m12} x_2 - f(x_1)$$

$$C_2 \frac{dx_2}{dt} = -G_{m21} x_1$$

↳ a conductance
 (current out
 voltage x_1 , in)

let x_1 & x_2 be voltages on capacitors





use

$$y(x) = a_{\infty}x + b_{\infty} + \sum_{i=1}^N a_i |x - b_i|$$

here b_i are the break points

$$b_1 < b_2 < b_3 \dots$$

$N = \#$ of break points

Take derivative

$$x < b_1; \quad y_1(x) = a_{\infty}x + b_{\infty} - \sum_{i=1}^N a_i (x - b_i)$$

$$y_1'(x) = a_{\infty} - \sum_{i=1}^N a_i = a_{\infty} - a_1 - a_2 \dots - a_N$$

EE610 10/23/02 Y.8

$$b_1 < x < b_2$$

$$y_2(x) = a_{\infty} x + b_{\infty} + a_1(x - b_1) - \sum_{i=2}^N a_i(x - b_i)$$

$$\frac{dy_2(x)}{dx} = a_{\infty} + a_1 - a_2 - \dots - a_N$$

$$\text{take } y_2'(x) - y_1'(x) = 2a_1 + 0$$

$$\text{or } 2a_1 = y_2'(x_2) - y_1'(x_1)$$

$$x_1 < b_1, b_1 < x_2 < b_2$$

Continue, as go through a break point get a new a_i

$$\text{now } y(x) = b_{\infty} + \sum_{i=1}^N a_i |x - b_i|$$

$$\Rightarrow b_{\infty} = y(x) - \sum_{i=1}^N a_i |x - b_i|$$

EE610

10/23/02

p.9

still need a_∞ :

$$y(x_0) = a_\infty x_0 + b_\infty + \sum a_i |x_0 - b_i|$$

gives a_∞

end result

given a piecewise linear
curve can write

$$y(x) = a_\infty x + b_\infty + \sum_{i=1}^N a_i |x - b_i|$$