

adjoint, p. 406-410

optimization, p. 404

$$\begin{bmatrix} v^T & i^T \end{bmatrix} \begin{bmatrix} i^a \\ -v^a \end{bmatrix} = 0$$

if γ exists

$$\begin{bmatrix} v^T & (\gamma v)^T \end{bmatrix} \begin{bmatrix} \gamma^a v^a \\ -v^a \end{bmatrix} = 0$$

$$v^T \begin{bmatrix} \mathbb{1}_b & \gamma^T \end{bmatrix} \begin{bmatrix} \gamma^a \\ -\mathbb{1}_b \end{bmatrix} v^a = 0_{1 \times 1}$$

$$\gamma^a - \gamma^T = 0_{b \times b} \Rightarrow \gamma^a = \gamma^T$$

if no γ use the more general definition

Transformes:



let v_1 & i_1 be m vectors

i_2 & v_2 be n vectors

$$P_{in} = 0 = v^T i = [v_1^T, v_2^T] \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = 0$$

$$1_m \cdot i_1 + \underbrace{T}_{m \times n} \cdot i_2 = 0_{n \times 1}$$

$$[v_1^T, v_2^T] \begin{bmatrix} -T \cdot i_2 \\ i_2 \end{bmatrix} = 0_{1 \times 1}$$

transpose \leftarrow \leftarrow trans ratio

$$= [v_1^T, v_2^T] \begin{bmatrix} -T \\ 1_n \end{bmatrix} \cdot i_2 = 0_{1 \times 1}$$

$$\Rightarrow -v_1^T \cdot T + v_2^T = 0_{1 \times n}$$

$$\left. \begin{aligned} v_2 &= T^T v_1 \\ i_1 &= -T i_2 \end{aligned} \right\} \text{law for} \\ \text{transformer} \\ \text{in terminal input} \\ \text{or terminal output} \\ T \text{ is } n \times n$$

$$A v = B i'$$

$$\begin{matrix} n \\ n \end{matrix} \left\{ \begin{matrix} \begin{bmatrix} T^T & -\mathbf{1}_n \\ 0 & 0 \end{bmatrix} v = \begin{bmatrix} 0 & 0 \\ \mathbf{1}_n & T \end{bmatrix} i' \\ \begin{matrix} \underbrace{\quad}_m & \underbrace{\quad}_n \end{matrix} \end{matrix} \right.$$

to find the adjoint

$$\begin{bmatrix} v^T & i'^T \end{bmatrix} \begin{bmatrix} i^a \\ v^a \end{bmatrix} = 0_{1 \times 1}$$

$$= \begin{bmatrix} v_1^T & v_1^T T & (-T i_2)^T & i_2^T \end{bmatrix} \begin{bmatrix} i^a \\ v^a \end{bmatrix} = 0$$

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r.4

$$\begin{bmatrix} v_1^T & v_1^T T & -l_2^T T^T & l_2^T \end{bmatrix} \begin{bmatrix} l_1^a \\ l_2^a \\ -v_1^a \\ -v_2^a \end{bmatrix} = 0$$

$$\Rightarrow v_1^T l_1^a + v_1^T T l_2^a - l_2^T T^T (-v_1^a) + l_2^T (-v_2^a) = 0$$

$$= v_1^T [l_1^a + T l_2^a] + l_2^T [T^T v_1^a - v_2^a] = 0$$

\Rightarrow need coefficient $l_2 = 0$ or
can freely choose v_1 & l_2

$$L_1^a = -T L_2^a$$

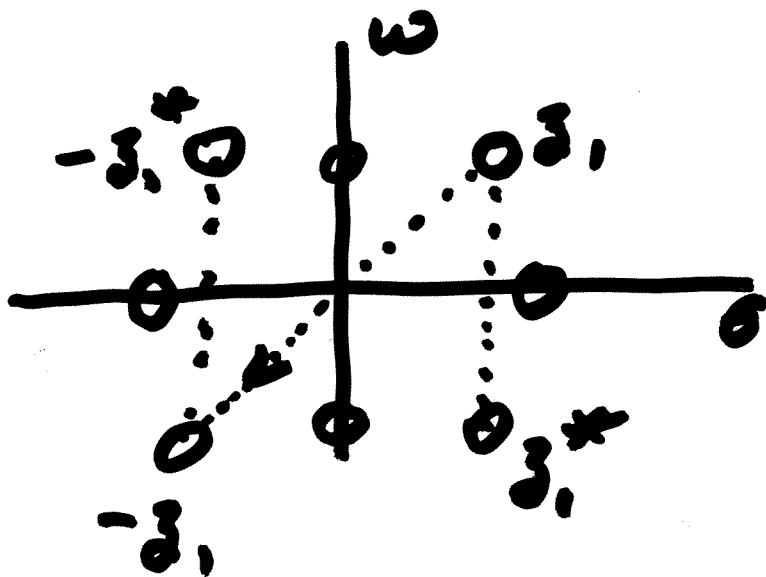
$$V_2^a = T^T V_1^a$$

∴ The adjoint of a transform is another transform.

factoring polynomial
zeros of even parts

$$f(s); \quad E_r f(s) = \frac{f(s) + f(-s)}{2}$$

$$= E_r(f(-s))$$



Given a polynomial
 $P(x)$ with real coefficients
 factor out degree two
 real coefficient terms

$$P_1(x) = x^2 + a_1 x + a_0$$

$$P(x) = P_1(x) \cdot P_2(x); \quad \delta[P] \geq 2$$

$$\text{Ex: } P(x) = x^4 + c_3 x^3 + c_2 x^2 + c_1 x + c_0$$

$$P_1(x) = x^2 + a_1 x + a_0$$

$$P_2(x) = x^2 + d_1 x + d_0$$

$$\text{here } P_1 \cdot P_2 = P$$

$$(x^2 + a_1 x + a_0)(x^2 + d_1 x + d_0)$$

$$= x^4 + c_3 x^3 + c_2 x^2 + c_1 x + c_0$$

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Philosophy: Do a
division, get remainder
& force these to zero

$$\begin{aligned} & x^4 + (a_1 + d_1)x^3 + (d_0 + a_1d_1 + a_0)x^2 \\ & \quad + (a_1d_0 + a_0d_1)x + a_0d_0 \\ & = x^4 + r_3x^3 + r_2x^2 + r_1x + r_0 \end{aligned}$$

$$r_3 = a_1 + d_1$$

$$r_2 = d_0 + a_1d_1 + a_0$$

$$r_1 = a_1d_0 + a_0d_1$$

$$r_0 = a_0d_0$$

in
given choose initial values
for a_1 , d_1 & a_0

then

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this gives

$$d_1 = r_3 - a_1$$

$$d_0 = r_2 - a_1 d_1 - a_0$$

but need not satisfy

$$r_1 = a_1 d_0 + a_0 d_1$$

$$r_0 = a_0 d_0$$

method 1: solves these
for a_1 & a_0 and repeat

$$\begin{bmatrix} r_1 \\ r_0 \end{bmatrix} = \begin{bmatrix} d_0 & d_1 \\ 0 & d_0 \end{bmatrix} \begin{bmatrix} a_1 \\ a_0 \end{bmatrix}$$

$$\Rightarrow \text{new } \begin{bmatrix} a_1 \\ a_0 \end{bmatrix} = \frac{1}{d_0^2} \begin{bmatrix} d_0 - d_1 \\ 0 & d_0 \end{bmatrix} \begin{bmatrix} r_1 \\ r_0 \end{bmatrix}$$

may or may not converge

method 2:

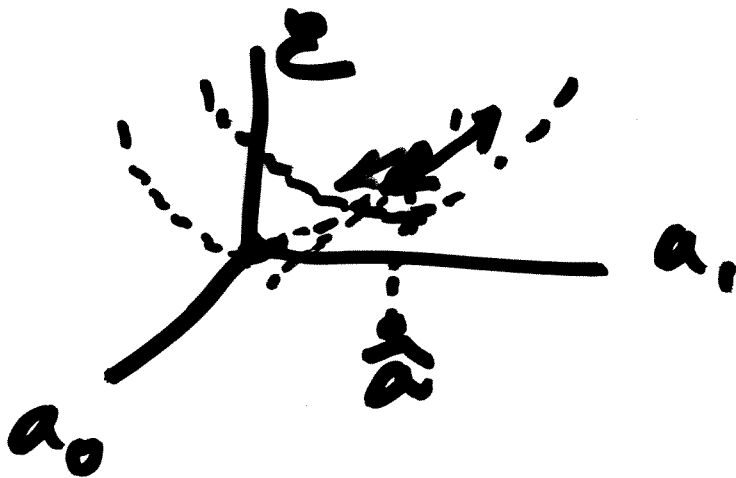
use p. 404

set up an "energy" function
 take its gradient with
 respect to a , and a_0

By long division get a
 remainder $r_1 a + r_0$

$$\text{set } \mathcal{E}(a, a_0) = r_0^2 + r_1^2$$

$$= (r_0 - 0)^2 + (r_1 - 0)^2$$



$$\mathcal{E}(a, a_0) = \mathcal{E}(a) = \mathcal{E}(\hat{a})$$

$$+ \nabla_a^T \mathcal{E}(a) \Big|_{\hat{a}} (a - \hat{a}) + \dots$$

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$$\mathcal{E}(a) = \mathcal{E}(\hat{a}) + \left[\frac{\partial \mathcal{E}}{\partial a_i} \right]^T (a - \hat{a})$$

$$+ [a - \hat{a}]^T \underbrace{\begin{bmatrix} \frac{\partial \mathcal{E}}{\partial a_i} \\ \frac{\partial^2 \mathcal{E}}{\partial a_i \partial a_j} \end{bmatrix}}_{\text{Hessian}} (a - \hat{a}) + \dots$$

desire to force $\mathcal{E}(a) = 0$
or p. 404 shows - choose

$$\Delta a = -\mu \nabla_a \mathcal{E} \Big|_{\hat{a}} ; \mu = \frac{\alpha}{\|\nabla \mathcal{E}\|}$$

choose α small, say 0.1
(α = convergence factor)

To get remainders:

choose $P_1(x) = x^2 + a_1x + a_0$

for a given

$$P(x) = \sum_{i=0}^{\delta} c_i x^i, \quad c_{\delta} = 1$$

then need to form

$$P_2(x) = \sum_{j=0}^{\delta-2} d_j x^j$$

$$\begin{aligned}
 P_1 \cdot P_2 &= \sum_{j=0}^{\delta-2} d_j x^{j+2} + \sum_{j=0}^{\delta-2} a_1 d_j x^{j+1} \\
 &\quad + \sum_{j=0}^{\delta-2} a_0 d_j x^j \\
 &= \sum_{i=2}^{\delta} d_{i-2} x^i + \sum_{i=1}^{\delta-1} a_1 d_{i-1} x^i + \sum_{i=0}^{\delta-2} a_0 d_i x^i
 \end{aligned}$$

$j+2=i$
 $i=2$ to δ

$j+1=i$
 $i=1$ to $\delta-1$

$j=i$
 $i=0$ to $\delta-2$

$$i=0 \quad r_0 = a_0 d_0$$

$$i=1 \quad r_1 = a_1 d_0 + a_0 d_1$$

$$i > 1$$

$$r_i = d_{i-2} + a_1 d_{i-1} + a_0 d_i$$

this gives the d_j down to 0 & 1

the remainders are

$$r_0 = r_0 - a_0 d_0$$

$$r_1 = r_1 - (a_1 d_0 + a_0 d_1)$$

Choose

$$\mathcal{E}(a_1, a_0) = \mathcal{E}(a) = r_0^2 + r_1^2$$

$$= (r_0 - a_0 d_0)^2 + (r_1 - a_1 d_0 - a_0 d_1)^2$$

$$\nabla \mathcal{E} = \begin{bmatrix} \frac{\partial \mathcal{E}}{\partial a_0} \\ \frac{\partial \mathcal{E}}{\partial a_1} \end{bmatrix}$$

$$= \begin{bmatrix} 2r_0 \cdot (-d_0) + 2r_1 \cdot (-d_1) \\ 0 + 2r_1 \cdot (-d_0) \end{bmatrix}$$

choose

$$a_{\text{new}} = \hat{a} + \left(\frac{-\nabla \mathcal{E}}{\|\nabla \mathcal{E}\|^2} \right)$$

$$= \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} - \begin{bmatrix} \uparrow \\ \uparrow \end{bmatrix} \alpha$$