

for RC

$$y(s) = k_\infty s + k_0 + \sum_{i=1}^N \frac{k_i s}{s + \omega_i^2}$$

note  $\frac{y(s)}{s} = k_\infty + \frac{k_0}{s} + \sum_{i=1}^N \frac{k_i}{s + \omega_i^2}$

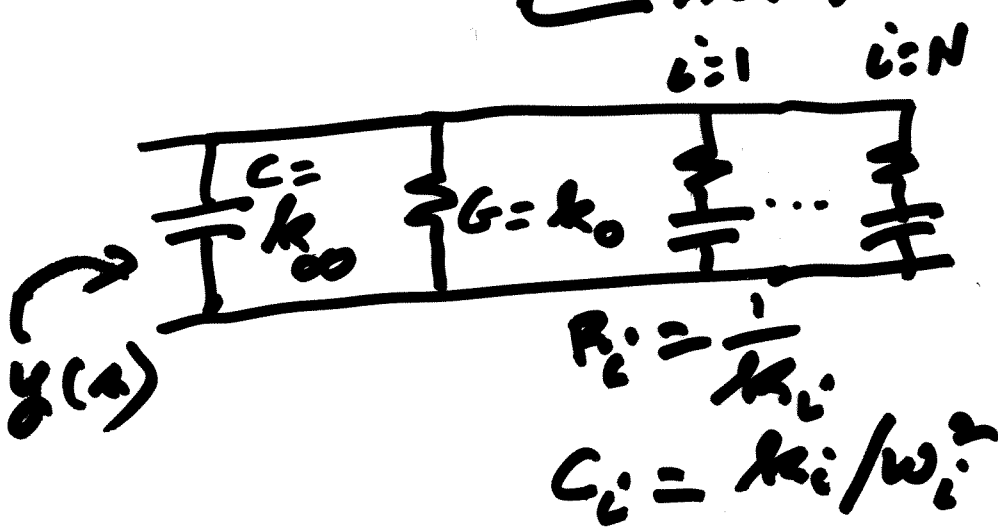
here  $k_i$  are residues at poles of  $\frac{y(s)}{s}$

$$F(s) = \frac{N(s)}{D(s)} = \frac{N(s)}{\prod (s + p_i)^{m_i}} \quad a_i = \text{residue}$$

$$= \frac{a_{m_i}}{(s + p_i)^{m_i}} + \frac{a_{m_i-1}}{(s + p_i)^{m_i-1}} + \dots + \frac{a_1}{(s + p_i)}$$

+  $F_1(s)$

no pole at  $s = -p_0$



$$z_i = \frac{s + \omega_i^2}{k_i s} = \frac{1}{k_i} + \frac{\omega_i^2/k_i}{s}$$

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$$y_{LC}(s) = \frac{s(s^2+3)}{3(s^2+1/3)}$$

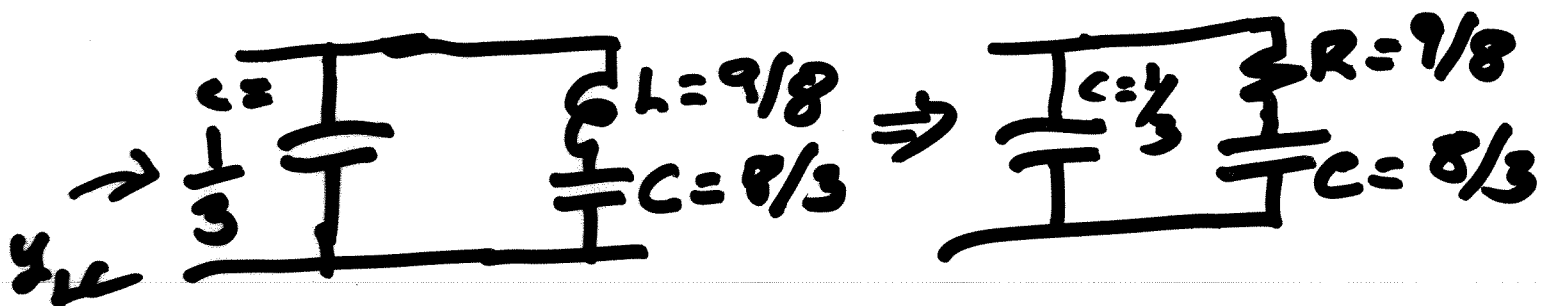
$$= \frac{1}{3}s + \frac{k_1 s}{s^2+1/3}$$

$$= \frac{1}{3}s + \frac{8}{9} \frac{s}{s^2+1/3}$$

$$\frac{\sqrt{s} \cdot \omega}{\sqrt{s} \cdot \sigma} \quad r.2$$

$$j k_1 = \frac{s^2+3}{3} \Big|_{s^2=-1/3}$$

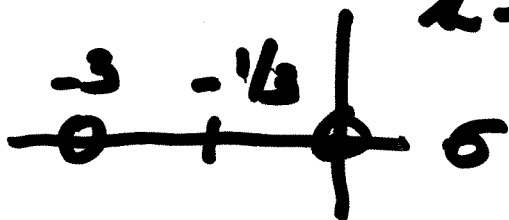
$$= \frac{-1/3+3}{3} = 8/9$$



$$y_{LC}(s) \Rightarrow y_{RC} = \frac{1}{3}s + \frac{1}{\frac{9}{8} + \frac{3}{8s}}$$

$$= \frac{1}{3}s + \frac{8s}{9s+3} = \frac{1}{3}s + \frac{8}{9} \frac{s}{s+1/3}$$

$$= \frac{\frac{1}{3}s^2 + \frac{8}{9}s}{s+1/3} = \frac{s(s+3)}{3(s+1/3)}$$



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$$y_{RC} = \frac{s(s+3)}{3(s+1/3)} = \frac{1}{3}s + \frac{k_1}{s+1/3}$$

$$k_1 = \left[ \frac{s(s+3)}{3} - \frac{1}{3}s(s+1/3) \right]_{s=-1/3}$$

$$= -\frac{1}{3}(-\frac{1}{3}+3) \cdot \frac{1}{3}$$

$$= -\frac{1}{27}(8) = -\frac{8}{27} < 0$$

but

$$\frac{y_{RC}}{s} = \frac{(s+3)}{3(s+1/3)} = \frac{1}{3} + \frac{\hat{k}_1}{s+1/3}$$

$$\hat{k}_1 = \frac{s+3}{3} \Big|_{s=-1/3} = \frac{-1/3+3}{3} = \frac{8}{9}$$

$$\frac{y_{RC}}{s} = \frac{1}{3} + \frac{8/9}{s+1/3} \Rightarrow y_{RC} = \frac{1}{3}s + \frac{8}{9} \frac{s}{s+1/3}$$

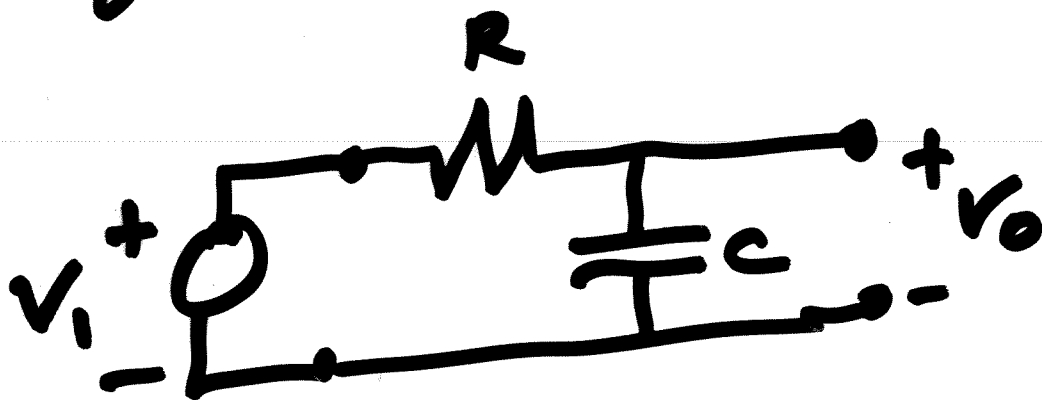
which can be synthesized

sensitivity

$S_x^{T(s)}$  = sensitivity of  $T(s)$  to  $x$

$$= \frac{x}{T(s)} \frac{\partial T(s)}{\partial x}$$

will use the adjoint circuit to find  $\partial T(s)/\partial x$ :



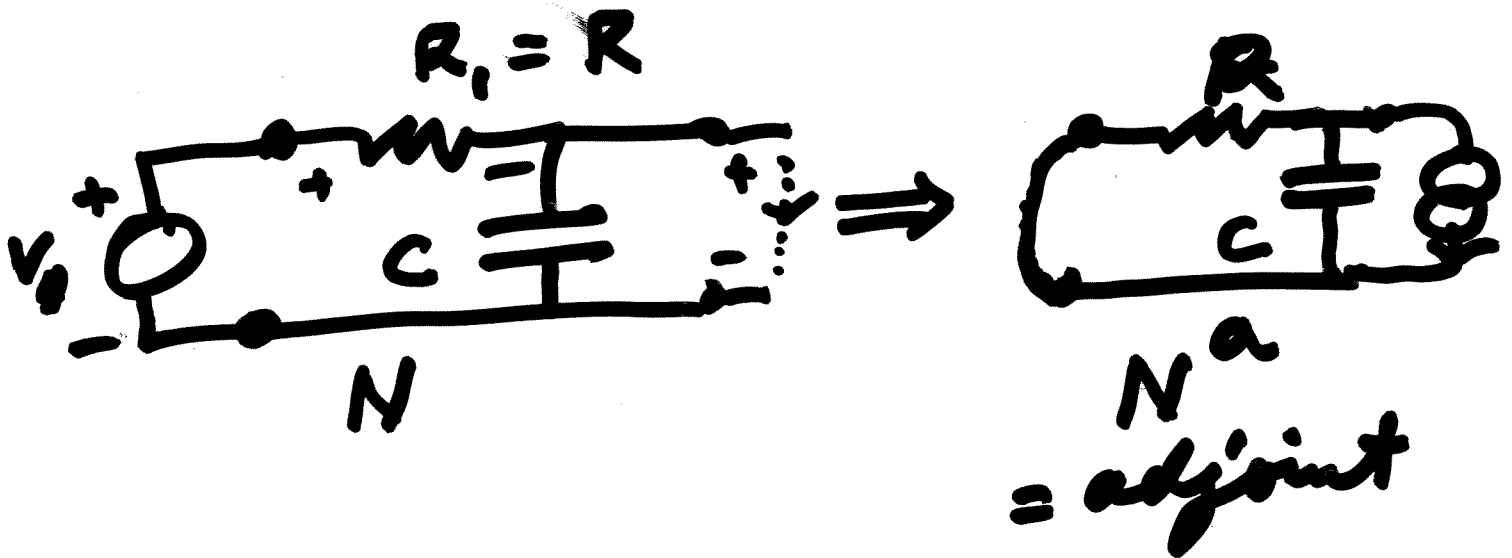
$$\begin{aligned} \frac{V_0}{V_1}(s) = T(s) &= \frac{\frac{1}{Cs}}{R + \frac{1}{Cs}} = \frac{1}{1 + RCs} \\ &= \frac{G}{G + Cs}, \quad G = 1/R \end{aligned}$$

$$S_G^{V_o/V_i} = \frac{G}{(G+CA)}, \frac{\partial T}{\partial G}$$

$$\begin{aligned} \frac{\partial T}{\partial G} &= \frac{1}{G+CA} - \frac{G}{(G+CA)^2} \\ &= \frac{CA}{(G+CA)^2} \end{aligned}$$

$$S_G^{V_o/V_i} = (G+CA) \cdot \frac{CA}{(G+CA)^2} = \frac{CA}{G+CA}$$

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ΣΕΒ10 10/16/02

r.6

$$v_b^T l_b^a - v_b^{Ta} l_b = 0$$

$$v_b = \begin{bmatrix} v_1 \\ v_0 \\ \hat{v}_b \end{bmatrix}, \quad v_b^a = \begin{bmatrix} v_1^a \\ v_0^a \\ \hat{v}_b^a \end{bmatrix}; \quad l_b = \begin{bmatrix} l_1 \\ l_0 \\ \hat{l}_b \end{bmatrix} = l_2$$

$$l_b^a = \begin{bmatrix} l_1^a \\ l_0^a \\ \hat{l}_b^a \end{bmatrix}$$

$$v_1 l_1^a - v_1^a l_1$$

$$+ v_0 l_0^a - v_0^a l_0$$

$$\hat{v}_b^T \hat{l}_b^a - \hat{v}_b^{Ta} \hat{l}_b = 0$$

where

$$\hat{v}_b^T \hat{l}_b^a - \hat{v}_b^{Ta} \hat{l}_b =$$

if  $\hat{\gamma}_b$  exists

$$\hat{v}_b^T \hat{\gamma}_b^a \hat{v}_b^a - \hat{v}_b^{Ta} \hat{\gamma}_b \hat{v}_b$$

$$= \hat{v}_b^T [\hat{\gamma}_b^a - \hat{\gamma}_b^T] \hat{v}_b^a$$

$$\frac{\partial \psi}{\partial G} = \frac{\partial \psi}{\partial \hat{y}_i}$$

fix  $V_1 = v_1$ ,  $\frac{\partial L_i^a}{\partial G} = 0$ ,  $\frac{\partial \psi_1^a}{\partial G} = 0$   
 $\& N^a$

$$\frac{\partial L_0^a}{\partial G} = 0, \frac{\partial \psi_0^a}{\partial G} = 0$$

$$\hat{y}_0 = \begin{bmatrix} G & 0 \\ 0 & AC \end{bmatrix}$$

Take  $\frac{\partial}{\partial G}$  of the  $v_0^T L_0^a - v_0^A T L_0 = 0$

$$0 - v_1^a \cdot \frac{\partial L_i}{\partial G} + \frac{\partial \psi_0}{\partial G} \cdot L_0^a + 0 - 0$$

- " Output a short

$$+ \frac{\partial \hat{v}_0^T}{\partial G} \cdot \hat{y}_0^a \hat{v}_0^a + \hat{v}_0 \cdot \frac{\partial \hat{y}_0^a}{\partial G} \hat{v}_0^a + \hat{v}_0^T \hat{y}_0^a \frac{\partial \hat{v}_0^a}{\partial G} = 0$$

$$- \frac{\partial \hat{v}_0^T}{\partial G} \cdot \hat{y}_0^T \hat{v}_0^a - \hat{v}_0 \cdot \frac{\partial \hat{y}_0^T}{\partial G} \hat{v}_0^a - \hat{v}_0^T \hat{y}_0^T \frac{\partial \hat{v}_0^a}{\partial G} = 0$$

branch                      branch

$$= \frac{\partial v_0}{\partial G} \cdot L_0^a - \hat{v}_0 \cdot \hat{v}_0^a$$

$$+ \frac{\partial \hat{v}_0^T}{\partial G} \underbrace{[\hat{y}_0^a - \hat{y}_0^T]}_{\text{force} = 0} \hat{v}_0^a = 0$$

$y^a \triangleq y^T$

$$\Rightarrow \frac{\partial v_0}{\partial G} \cdot L_0^a = \hat{v}_0 \cdot \hat{v}_0^a$$

$$\text{if } v_1 = 1 \quad \frac{\partial v_0}{\partial G} = \frac{\partial v_0/v_1}{\partial G} = \frac{\partial T}{\partial G}$$

$\therefore$  fix  $L_0^a = 1$  say analyze  
 $N \in N^a$  to get  $\hat{v}_0$  &  $\hat{v}_0^a$