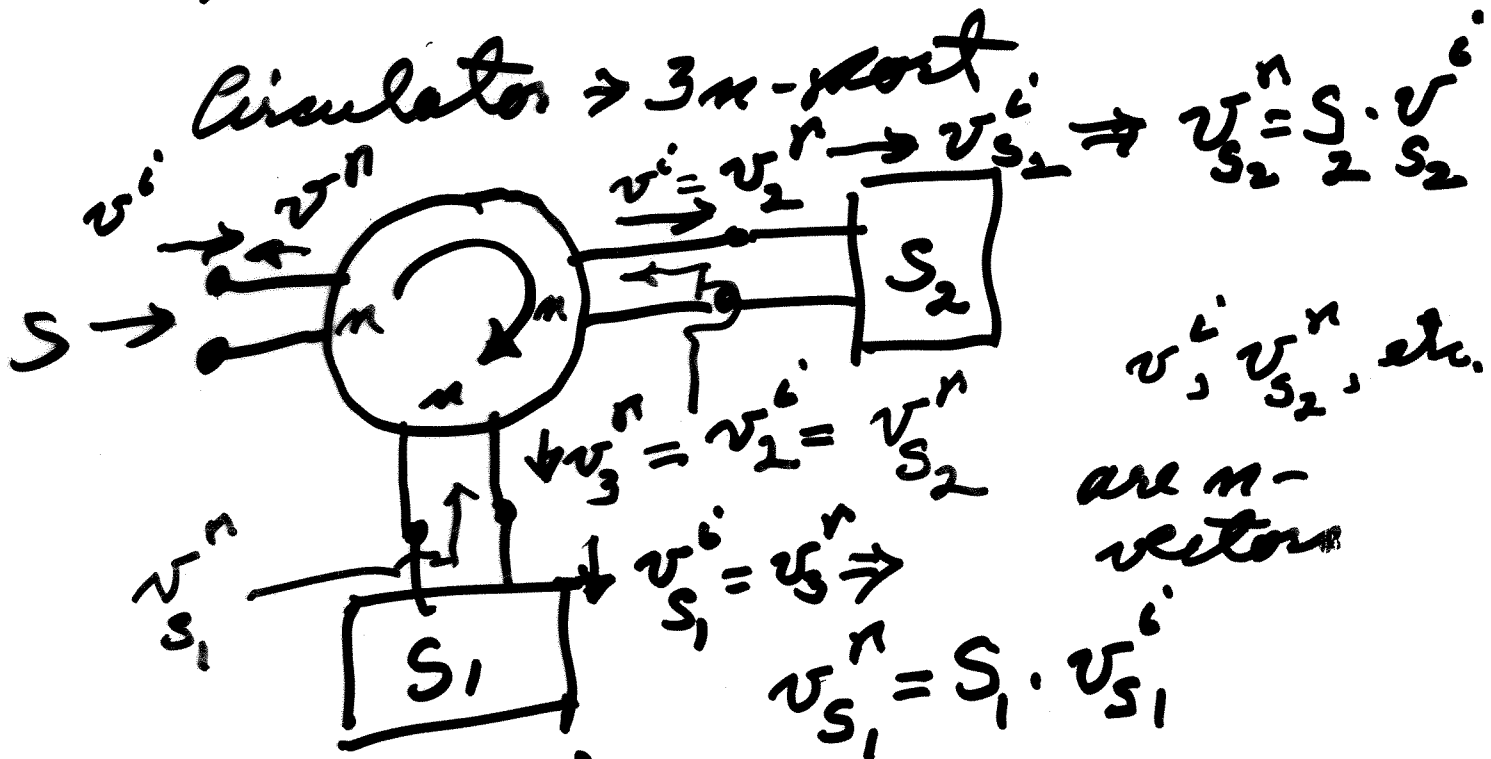
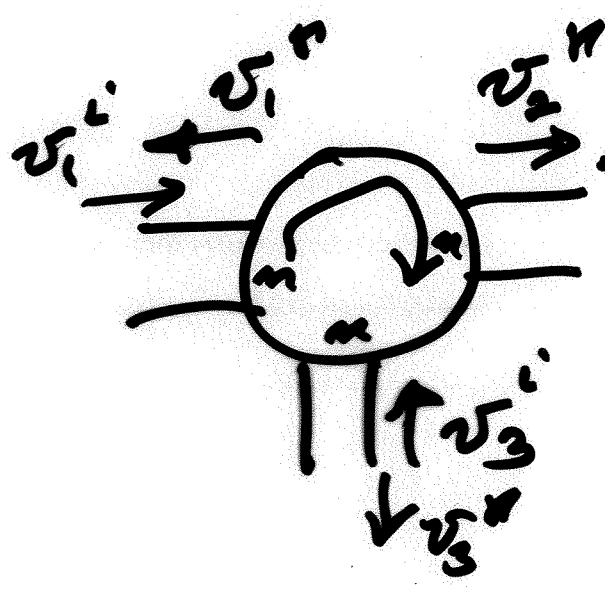


1. Given a circulator can make

$$S_1 \cdot S_2 = S$$



$$\begin{aligned}
 v^n &= v_{S_1}^n = S_1 \cdot v_{S_1}^i = S_1 \cdot v_3^n = S_1 \cdot v_2^i = S_1 \cdot v_{S_2}^i \\
 &= S_1 \cdot S_2 \cdot v_{S_2}^i = S_1 \cdot S_2 \cdot v_2^n \\
 &= S_1 \cdot S_2 \cdot v^i \Rightarrow v^n = S_1 \cdot S_2 \cdot v^i \\
 &= S \cdot v^i \\
 \Rightarrow S &= S_1 \cdot S_2
 \end{aligned}$$



$$\begin{bmatrix} v_1^o \\ v_2^o \\ v_3^o \end{bmatrix} = S_{\text{net}} \begin{bmatrix} v_1^i \\ v_2^i \\ v_3^i \end{bmatrix}$$

$$\begin{bmatrix} v_1^o \\ v_2^o \\ v_3^o \end{bmatrix} = \begin{bmatrix} 0_m & 0_m & 1_m \\ 1_m & 0_m & 0_m \\ 0_m & 1_m & 0_m \end{bmatrix} \begin{bmatrix} v_1^i \\ v_2^i \\ v_3^i \end{bmatrix}$$

$3m\text{-vector}$ $3m \times 3m$ S_{net} $3m\text{-vector}$

$$S_{\text{net}}^T S_{\text{net}} = \begin{bmatrix} 0_m & 0_m & 0_m \\ 0_m & 0_m & 1_m \\ 1_m & 0_m & 0_m \end{bmatrix} \begin{bmatrix} 0_m & 0_m & 1_m \\ 1_m & 0_m & 0_m \\ 0_m & 1_m & 0_m \end{bmatrix}$$

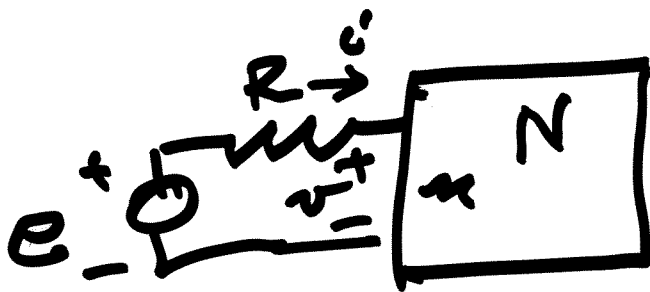
$$= \begin{bmatrix} 1_m & 0_m & 0_m \\ 0_m & 1_m & 0_m \\ 0_m & 0_m & 1_m \end{bmatrix}$$

$3m\text{-port net}$

$$\frac{1}{3m} S_{\text{net}}^T S_{\text{net}} = \mathbf{O}_{3m} \leftarrow \text{is lossless}$$

$$2v^r = v - Ri$$

$$e = 2v^i = v + Ri$$



if N has an admittance $i = Yv$

$$2v^r = 2Sv^i$$

$$= v - RYv = (I_n - RY)v$$

$$= S[v + Ri] = S[v + RYv]$$

$$= S[I_n + RY]v$$

assume $(I_n - RY)^{-1}$ exists

$I_n v = v = (I_n - RY)^{-1} S (I_n + RY) \cdot v$
 as Y exists (assumed) any v
 can be used

$$I_n = (I_n - RY)^{-1} S (I_n + RY)$$

$$\text{or } \underline{(I_n - RY)(I_n + RY)^{-1} = S}$$

$$\equiv (I_n + RY)^{-1} (I_n - RY)$$

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now $(I_n - X)(I_n + X)^{-1}(I_n + X)$

$$= I_n - X$$

let's $(I_n + X)(I_n - X) = I_n + X - X - X^2$

$$= (I_n - X)(I_n + X) = I_n - X + X - X^2$$

times $(I_n + X)^{-1}$ on right & left

$$(I_n - X)(I_n + X)^{-1} = (I_n + X)^{-1}(I_n - X)$$

to get Y given S

$$(I_n - RY) = S(I_n + RY)$$

$$= I_n - RY = S + SRY$$

$$\Rightarrow I_n - S = RY + SRY = (I_n + S)RY$$

$$\text{or } RY = (I_n + S)^{-1}(I_n - S)$$

$$= (I_n - S)(I_n + S)^{-1}$$

$$\text{or } Y = G(I_n + S)^{-1}(I_n - S); \quad G = R^{-1}$$

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$$P_{av}(j\omega) = \text{Re} \left(V(j\omega)^{T*} I(j\omega) \right) \quad \text{r.5}$$

in SSS.
sinusoidal
steady
state

$$= \frac{V(j\omega)^{T*} I(j\omega) + I(j\omega)^{T*} V(j\omega)}{2}$$

given $Y(s)$ exists:

$$2 P_{av}(j\omega) = V^{T*} Y(j\omega) V + V^{T*} Y(j\omega) V$$

$$= V^{T*} \left[Y + Y^{T*} \right] V \geq 0$$

if passive

if lossless

$$P_{av}(j\omega) \equiv 0 \Rightarrow Y(j\omega) + Y(j\omega)^{T*} = 0_n$$

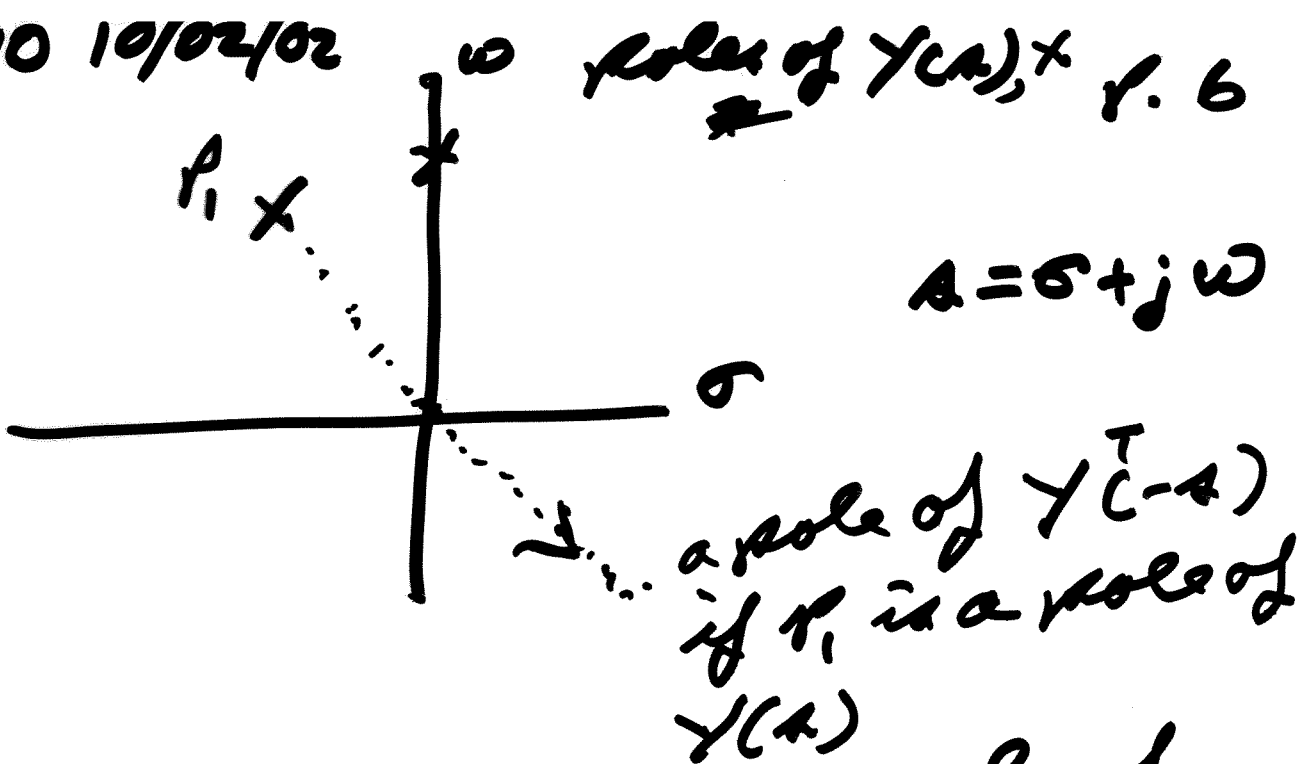
$$Y(j\omega) + Y(-j\omega)^T = 0$$

$$Y(s) + Y(-s)^T = 0_n \quad s = \frac{\alpha}{j}$$

in all of α -
plane if
rational

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roles of $Y(s)$, p. 6

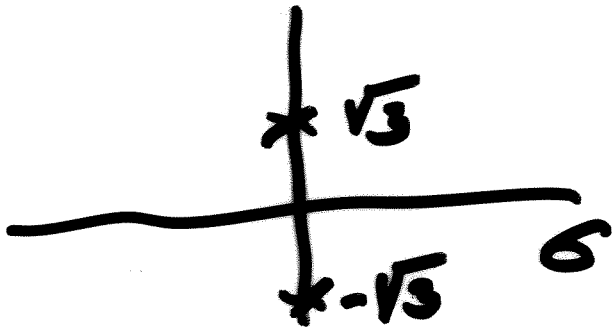


can't be as a pole of
 $Y(-s) = -Y(s) \Rightarrow$ a
pole of $Y(s)$

\Rightarrow all poles of a lossless
 $Y(s)$ are on $j\omega$ axis
also true any pole is simple
with positive semi-definite
residue matrix.

Ex: $Y(s) = \frac{2s}{s^2+3}$ is PR because

$$Y(s) + Y(-s) = \frac{2s}{s^2+3} + \frac{-2s}{(-s)^2+3} = 0$$



$$Y(s) = \frac{r_1}{s + j\sqrt{3}} + \frac{r_2 = r_1^*}{s - j\sqrt{3}} = \frac{1}{s + j\sqrt{3}} + \frac{1}{s - j\sqrt{3}}$$

$$r_1 = (s + j\sqrt{3}) Y(s) = \frac{r_1^* (s + j\sqrt{3})}{s - j\sqrt{3}}$$

$$\approx \frac{2s}{s - j\sqrt{3}} - \frac{r_1^* (s + j\sqrt{3})}{s - j\sqrt{3}}$$

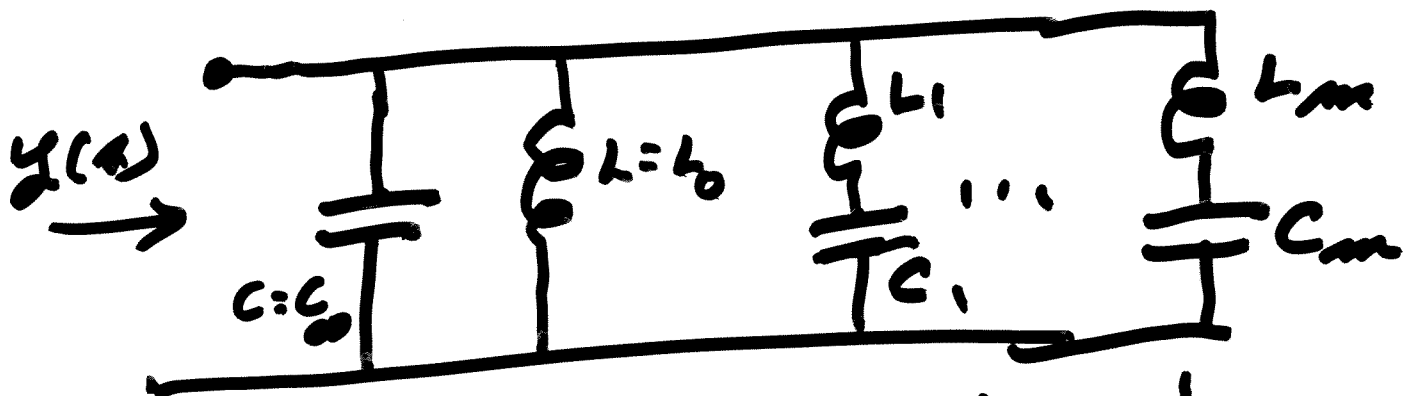
Let $s = -j\sqrt{3}$

$$r_1 = \frac{2(-j\sqrt{3})}{-j\sqrt{3} - j\sqrt{3}} = 1$$

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$$Y(s) = \frac{1}{s} + \frac{1}{s} + \sum_{i=1}^m \frac{2\sigma_i R}{s^2 + \omega_i^2}$$

by partial fraction expansion



$$g_i = \frac{2\sigma_i R}{s^2 + \omega_i^2}$$

$$L_i = \frac{1}{2\sigma_i}$$

$$C_i = \frac{2\sigma_i}{\omega_i^2}$$

$$L_i C_i = \frac{1}{\omega_i^2}$$

$$\omega_i = \frac{1}{\sqrt{L_i C_i}}$$