## **ENEE681**

Lecture 2 Displacement Current Fields in Matter Boundary Conditions

## Maxwell's Displacement Current

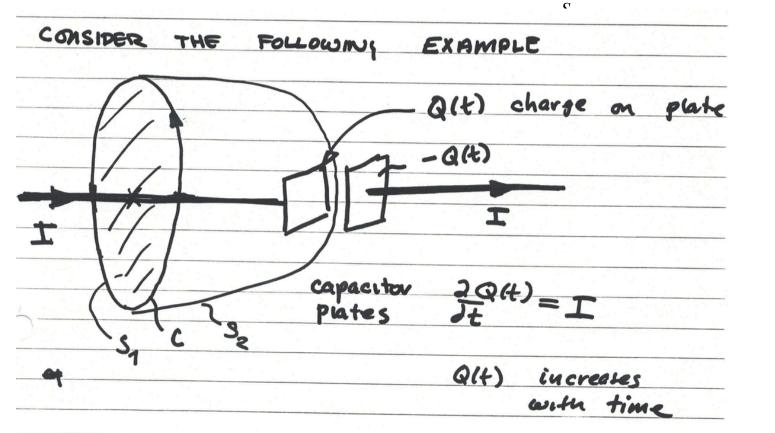
It is not really a current. It just acts like one.

Maxwell determined the static Ampere's Law could not be correct. Inconsistent with charge conservation

$$\oint_{Loop} \vec{\mathbf{B}}(\vec{\mathbf{r}}) \cdot d\vec{\mathbf{l}} = \mu_0 \int d\vec{\mathbf{A}} \cdot \vec{\mathbf{J}} = \mu_0 \vec{\mathbf{A}}$$

 $\int d\vec{\mathbf{A}} \cdot \vec{\mathbf{J}} = I$ 

 $\int d\vec{\mathbf{A}} \cdot \vec{\mathbf{J}} = 0$ 



Remember for Faraday's Law Any surface with the same perimeter gave the correct answer.

$$\oint_{loop} \vec{\mathbf{E}} \cdot d\vec{\mathbf{l}} = -\int_{S} d\vec{\mathbf{A}} \cdot \frac{\partial \vec{\mathbf{B}}}{\partial t}$$

 $\vec{\mathbf{B}}$  .

 $S_1+S_2$ 

From Gauss' Law  
$$\int_{S_1+S_2} \vec{\mathbf{B}} \cdot d\vec{\mathbf{A}} = 0$$

Sz

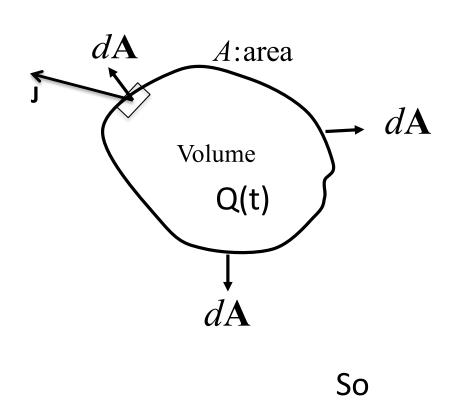
de

$$d\vec{\mathbf{S}}_{1} = d\vec{\mathbf{S}}$$
  

$$d\vec{\mathbf{S}}_{2} = -d\vec{\mathbf{S}}$$
  

$$\int_{S_{1}+S_{2}} \vec{\mathbf{B}} \cdot d\vec{\mathbf{S}} = 0 \Rightarrow \int_{S_{1}} \vec{\mathbf{B}} \cdot d\vec{\mathbf{S}}_{1} = \int_{S_{2}} \vec{\mathbf{B}} \cdot d\vec{\mathbf{S}}_{2}$$

#### **Conservation of Charge**

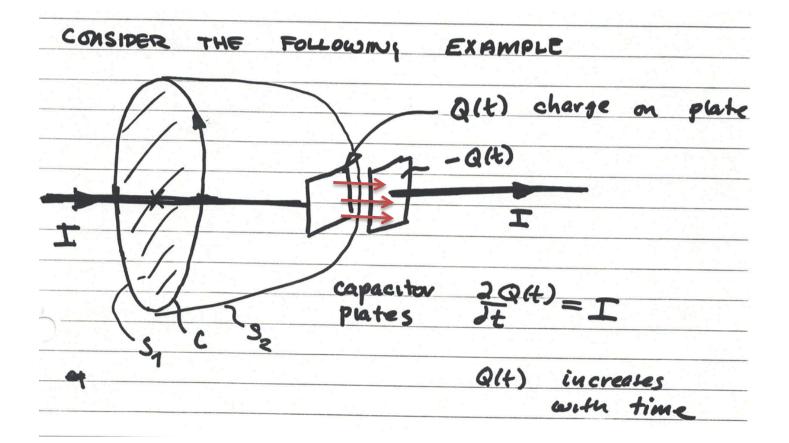


$$\int_{S} d\vec{\mathbf{A}} \cdot \vec{\mathbf{J}} + \frac{dQ}{dt} = 0$$

But

$$\oint_{S} \varepsilon_{0} \vec{\mathbf{E}} \cdot d\vec{\mathbf{A}} = Q$$

 $\int_{S} d\vec{\mathbf{A}} \cdot \left(\vec{\mathbf{J}} + \varepsilon_0 \frac{\partial}{\partial t} \vec{\mathbf{E}}\right) = 0$ 



$$\int_{S} d\vec{\mathbf{A}} \cdot \left(\vec{\mathbf{J}} + \boldsymbol{\varepsilon}_{0} \frac{\partial}{\partial t} \vec{\mathbf{E}}\right) = 0$$

Faraday: time varying B makes an E

$$\oint_{loop} \vec{\mathbf{E}} \cdot d\vec{\mathbf{l}} == -\frac{d}{dt} \int_{\mathbf{S}} \vec{\mathbf{B}} \cdot d\vec{\mathbf{A}}$$

example  
$$E_{\theta}(r) = -\frac{r}{2} \frac{\partial B_z}{\partial t}$$

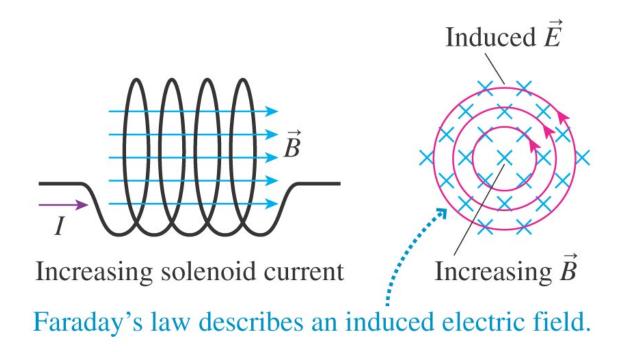
Ampere-Maxwell: time varying E makes a B

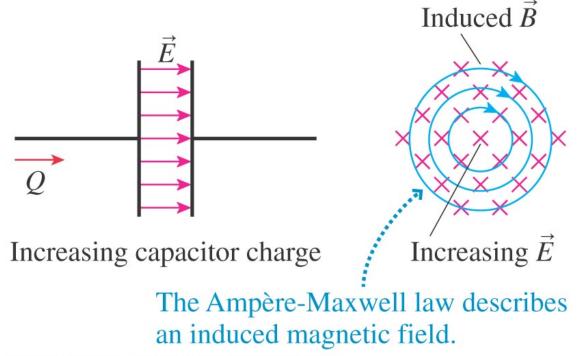
$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{l}} = \mu_0 \varepsilon_0 \frac{d}{dt} \int_{S} \vec{\mathbf{E}} \cdot d\vec{\mathbf{A}}$$

example  

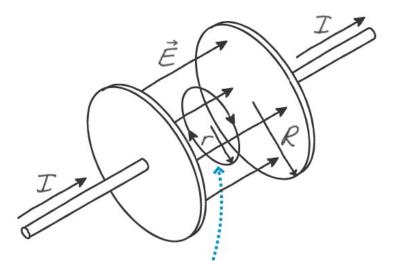
$$B_{\theta}(r) = \frac{\mu_0 \varepsilon_0 r}{2} \frac{\partial E_z}{\partial t}$$

Put together, fields can sustain themselves - Electromagnetic Waves





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$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{l}} = B_{\theta}(r) 2\pi r$$
$$\Phi_{e} = \int_{S} \vec{\mathbf{E}} \cdot d\vec{\mathbf{A}} = \pi r^{2} E_{z}$$

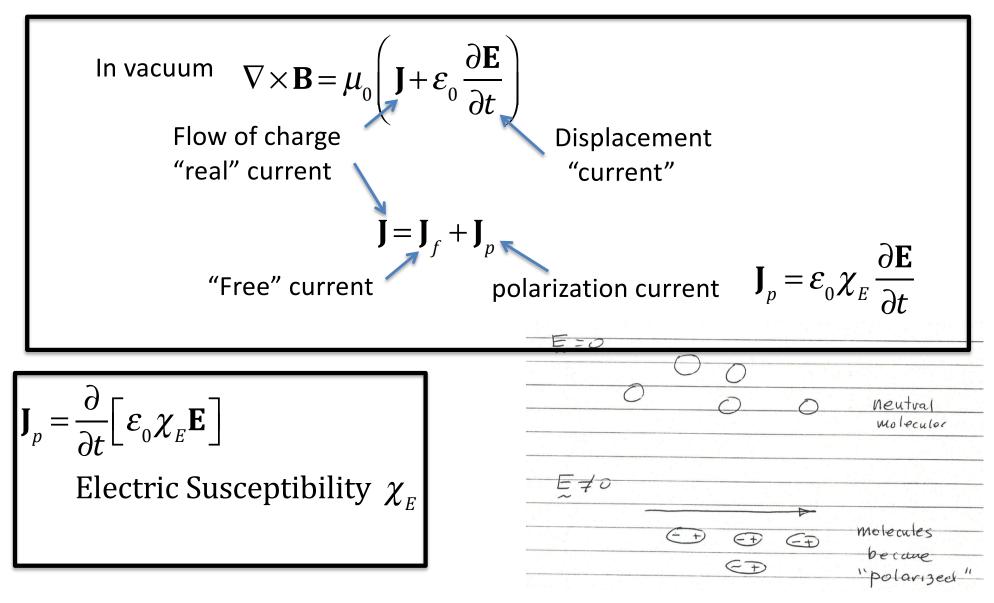
$$\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{l}} = \mu_0 (I + \varepsilon_0 \frac{d\Phi_e}{dt})$$

The magnetic field line is a circle concentric with the capacitor. The electric flux through this circle is  $\pi r^2 E$ .

$$B_{\theta}(r) = \frac{\mu_0 \varepsilon_0 r}{2} \frac{\partial E_z}{\partial t}$$

Recall from Faraday: 
$$E_{\theta}(r) = -\frac{r}{2} \frac{\partial B_z}{\partial t}$$

# Conduction current, Displacement current, Polarization current



#### **Dielectric Terminology**

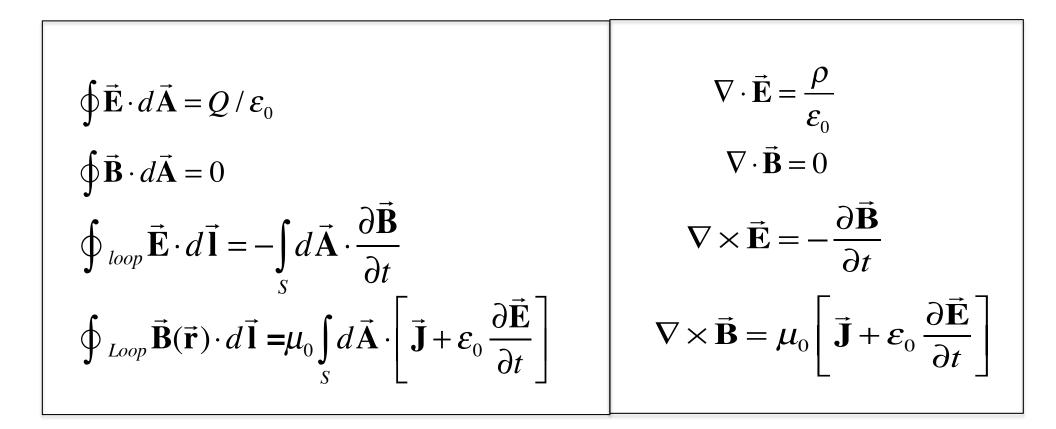
$$\nabla \times \frac{\mathbf{B}}{\mu_0} = \mathbf{J}_f + \frac{\partial}{\partial t} \Big[ \varepsilon_0 \Big( 1 + \chi_E \Big) \mathbf{E} \Big]$$
$$\nabla \times \frac{\mathbf{B}}{\mu_0} = \mathbf{J}_f + \frac{\partial}{\partial t} \mathbf{D}$$
$$\mathbf{D} = \varepsilon_0 \Big( 1 + \chi_E \Big) \mathbf{E} = \varepsilon \mathbf{E}$$

**D** Electric flux density

$$\varepsilon = \varepsilon_0 (1 + \chi_E)$$
 Dielectric contant

 $(1 + \chi_E)$  Relative Dielectric constant

#### Maxwell's Equations in Vacuum

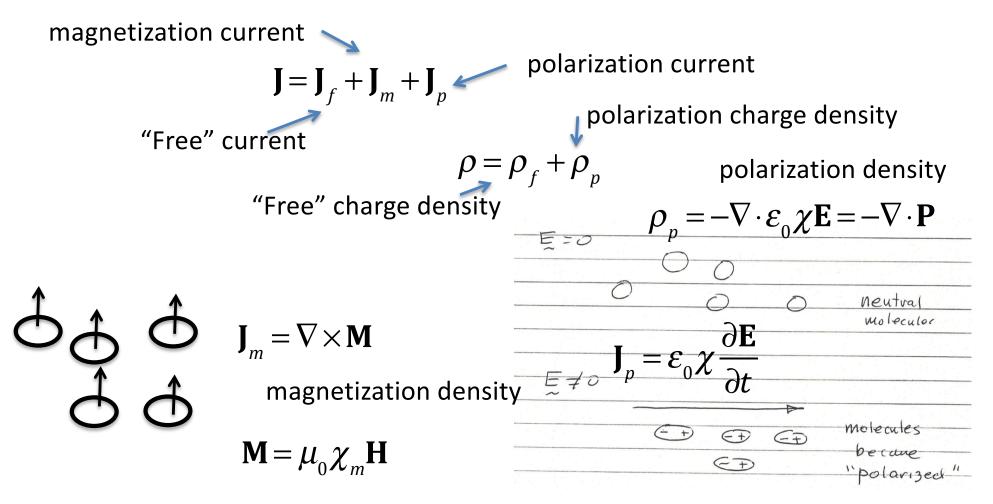


Here ho and J are the <u>total charge and current densities</u>

Includes charge and current densities induced in dielectric and magnetic materials

Separate charge and current densities into "free" and "induced" components

#### Somewhat arbitrary but very useful



#### Maxwell's Equations in Matter

Equations in linear media

 $\mathbf{D} = \varepsilon_0 \mathbf{E} + \mathbf{P} = \varepsilon \mathbf{E}$  $\mathbf{B} = \boldsymbol{\mu}_0 \mathbf{H} + \mathbf{M} = \boldsymbol{\mu} \mathbf{H}$  $\mathbf{P} = \varepsilon_0 \chi_E \mathbf{E}$  $\mathbf{M} = \boldsymbol{\mu}_{0} \boldsymbol{\chi}_{M} \mathbf{H}$  $\oint \vec{\mathbf{D}} \cdot d\vec{\mathbf{A}} = Q_{free}$  $\oint \vec{\mathbf{B}} \cdot d\vec{\mathbf{A}} = 0$  $\nabla \cdot \vec{\mathbf{D}} = \rho_{free}$  $\nabla \cdot \vec{\mathbf{B}} = 0$  $\oint_{loop} \vec{\mathbf{E}} \cdot d\vec{\mathbf{l}} = -\int_{S} d\vec{\mathbf{A}} \cdot \frac{\partial \vec{\mathbf{B}}}{\partial t}$  $\oint_{Loop} \vec{\mathbf{H}}(\vec{\mathbf{r}}) \cdot d\vec{\mathbf{l}} = \int_{S} d\vec{\mathbf{A}} \cdot \left[\vec{\mathbf{J}}_{free} + \frac{\partial \vec{\mathbf{D}}}{\partial t}\right]$  $\nabla \times \vec{\mathbf{E}} = -\frac{\partial \vec{\mathbf{B}}}{\partial \vec{\mathbf{B}}}$  $\nabla \times \vec{\mathbf{H}} = \vec{\mathbf{J}}_{free} + \frac{\partial \vec{\mathbf{D}}}{\partial t}$ 

#### Maxwell's Equations in Matter

$$\nabla \cdot \mathbf{D} = \rho_{f} \qquad \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \qquad \nabla \cdot \mathbf{B} = 0 \qquad \nabla \times \mathbf{H} = \mathbf{J}_{f} + \frac{\partial \mathbf{D}}{\partial t}$$
(linear and isotropic matter)  

$$\mathbf{H} = \frac{1}{\mu_{0}} \mathbf{B} - \mathbf{M} = \frac{1}{\mu} \mathbf{B}, \quad \mathbf{J}_{b} = \nabla \times \mathbf{M}$$

$$\mathbf{D} = \varepsilon_{0} \mathbf{E} + \mathbf{P} = \varepsilon \mathbf{E}, \quad \rho_{b} = -\nabla \cdot \mathbf{P}$$

$$\mathbf{M} = \chi_{m} \mathbf{H}: \text{ Magnetization field} \qquad \mathbf{P} = \varepsilon_{0} \chi_{e} \mathbf{E}: \text{ Polarzation field}$$

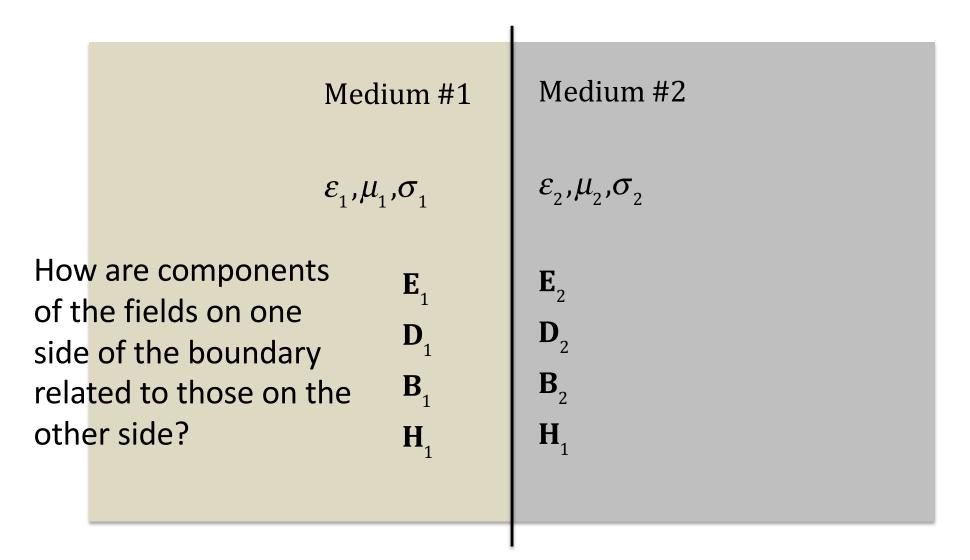
$$\mu = \mu_{0}(1 + \chi_{m}): \text{ permeability} \qquad \varepsilon_{r} = 1 + \chi_{e} \quad :\text{ relative permittivity}$$

$$\chi_{m}: \text{ magnetic susceptibility} \qquad \chi_{e}: \text{ electric suscepibility}$$

In a good conductor – Ohms' Law (point version)

$$\mathbf{J}_{f} = \mathbf{\sigma} \Big( \mathbf{E} + \mathbf{v} \times \mathbf{B} \Big)$$

# **Boundary Conditions**



# **General Comments**

Tangential components of **E** are always equal.

Normal components of **B** are always equal.

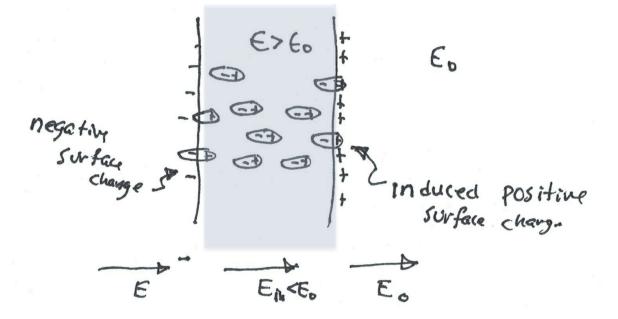
Normal component of **E** discontinuous implies a **surface charge density.** 

Normal components of **D** discontinuous implies a **free** surface charge density

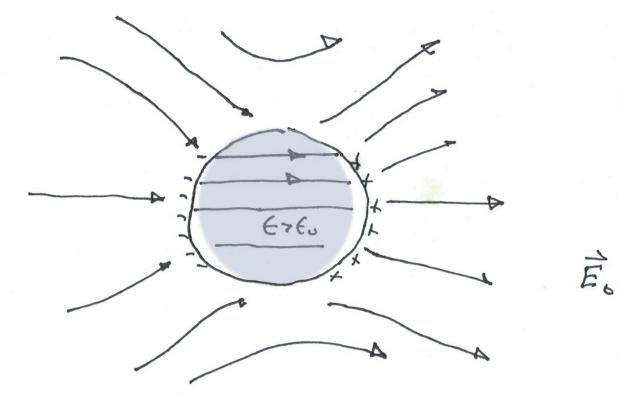
Tangential components of **B** discontinuous implies a **surface current density.** 

Tangential components of **H** discontinuous implies a **free** surface current density.

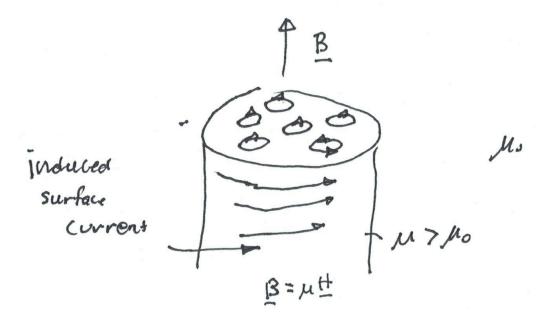
#### Induced surface charge density



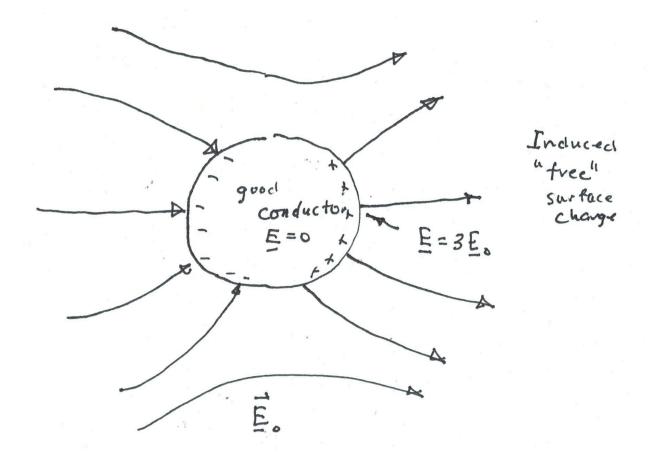
### **Dielectric Sphere**



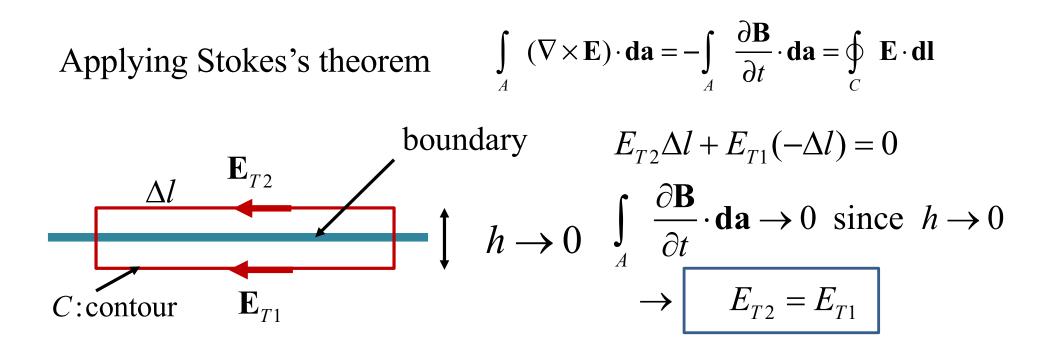
#### Magnetized Rod



#### **Conducting Sphere**



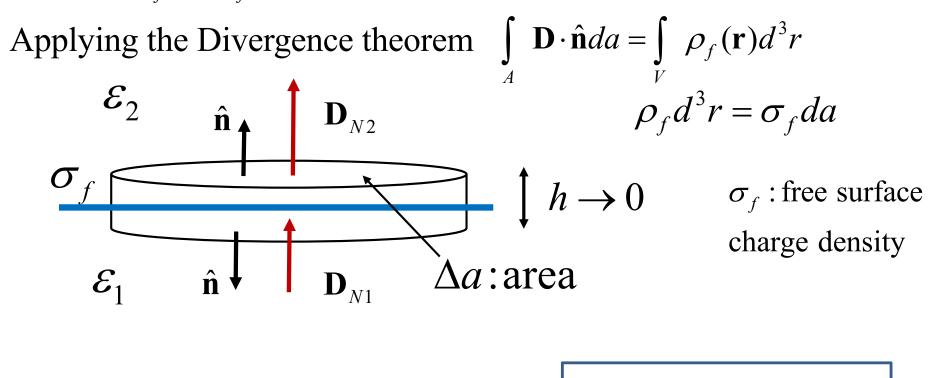
#### Tangential Component of E Boundary Conditions



 The tangential component of electric field E is continuous across a boundary

#### Normal Component of **D**

Consider the electric flux field:  $\mathbf{D} = \varepsilon \mathbf{E} = \varepsilon_0 (1 + \chi_e) \mathbf{E}$  (linear/isotropic matter)  $\nabla \cdot \mathbf{D} = \rho_f \qquad \rho_f$  = free charge density



$$(\mathbf{D}_{N2} - \mathbf{D}_{N1}) \cdot \hat{\mathbf{n}} \Delta a = Q_f = \sigma_f \Delta a \quad \rightarrow \quad \varepsilon_2 E_{N2} - \varepsilon_1 E_{N1} = \sigma_f$$

• The normal component of the electric flux field D is discontinuous by the free surface charge density

## Normal E?

 $\nabla \cdot \varepsilon_0 \mathbf{E} = \rho_t$ ,  $\rho_t$  = total charge density Applying the Divergence theorem  $\int_{A} \varepsilon_0 \mathbf{E} \cdot \hat{\mathbf{n}} da = \int_{V} \rho_t(\mathbf{r}) d^3 r$  $\varepsilon_2 \qquad \hat{\mathbf{n}} \quad \mathbf{E}_{N2} \qquad \rho_t d^3 r = \sigma_t da$  $\mathbf{E}_{N2}$  $[h \to 0 \quad \sigma_t: \text{total surface}$ charge density  $\Delta a$ :area ĥ  $\mathbf{E}_{N^{\dagger}}$  $\varepsilon_0(\mathbf{E}_{N2} - \mathbf{E}_{N1}) \cdot \hat{\mathbf{n}} \Delta a = Q_t = \sigma_t \Delta a \quad \rightarrow \left| \begin{array}{c} \varepsilon_0 E_{N2} - \varepsilon_0 E_{N1} = \sigma_t \end{array} \right|$ 

The normal component of the electric field E is discontinuous by the total surface charge density/ E<sub>0</sub>

#### Tangential Component of H

Magnetic field:  $\nabla \times \mathbf{H} = \mathbf{J}_f + \frac{\partial \mathbf{D}}{\partial t} \quad \mathbf{D} = \varepsilon \mathbf{E}$  (linear/isotropic matter)  $\mathbf{H} = \mathbf{B}/\mu$  (linear/isotropic matter and nonferromagnetic)  $\oint_{C} \mathbf{H} \cdot \mathbf{dl} = \int_{A} \mathbf{J}_{f} \cdot \mathbf{da} + \int_{A} \frac{\partial \mathbf{D}}{\partial t} \cdot \mathbf{da}$ Applying Stokes's theorem  $\int_{A} \mathbf{J}_{f} \cdot \mathbf{d} \mathbf{a} \rightarrow \mathbf{J}_{f} \Delta l h \rightarrow \mathbf{K}_{f} \Delta l$ boundary *C*:contour ĥ as  $h \to 0$   $h \to 0$   $\int \frac{\partial \mathbf{D}}{\partial t} \cdot \mathbf{da} \to 0$  since  $h \to 0$  $\mathbf{H}_{T2}$  $\mathbf{H}_{T1}$  $\mathbf{K}_{f}$  $\mathbf{H}_{T2}\Delta l + \mathbf{H}_{T1}(-\Delta l) = \Delta l \mathbf{K}_{f} \times \hat{\mathbf{n}}$ free surface  $\mathbf{H}_{T2} - \mathbf{H}_{T1} = \mathbf{K}_{f} \times \hat{\mathbf{n}}$ current density **n** : outward normal to the surface boundary

• The tangential component of magnetic field H is discontinuous by the free surface current

## **Tangential B**

$$\mathbf{H}_{T2} - \mathbf{H}_{T1} = \mathbf{K}_f \times \hat{\mathbf{n}}$$
$$\mathbf{B}_{T2} - \mathbf{B}_{T1} = \mu_0 \mathbf{K}_t \times \hat{\mathbf{n}}$$

• The tangential component of magnetic flux density B is discontinuous by the total surface current  $\times \mu_0$ 

#### Normal Component of **B**

 $\nabla \cdot \mathbf{B} = 0$  Magnetic flux density : **B** 

$$\hat{\mathbf{n}} + \mathbf{B}_{N2} \quad \Delta a : \text{area} \qquad \oint_{A} \mathbf{B} \cdot \hat{\mathbf{n}} da = 0$$

$$\hat{\mathbf{n}} + \mathbf{B}_{N1} \quad h \to 0$$

$$(\mathbf{B}_{N2} - \mathbf{B}_{N1}) \cdot \hat{\mathbf{n}} \Delta a = 0 \quad \to \quad \mathbf{B}_{N2} = \mathbf{B}_{N1}$$

Normal compontent of  $\mathbf{H}$   $\nabla \cdot \mathbf{H} = -\nabla \cdot \mathbf{M}$ 

$$\rightarrow \qquad H_{N2} - H_{N1} = -(M_{N2} - M_{N1})$$

• The normal component of the magnetic flux field B is continuous across boundary

#### **Boundary Condition Summary**

**Tangential Components** 

$$\mathbf{E}_{T2} = \mathbf{E}_{T1} \qquad \mathbf{H}_{T2} - \mathbf{H}_{T1} = \mathbf{K}_{f} \times \hat{\mathbf{n}} \qquad \mathbf{B}_{T2} - \mathbf{B}_{T1} = \boldsymbol{\mu}_{0} \mathbf{K}_{t} \times \hat{\mathbf{n}}$$

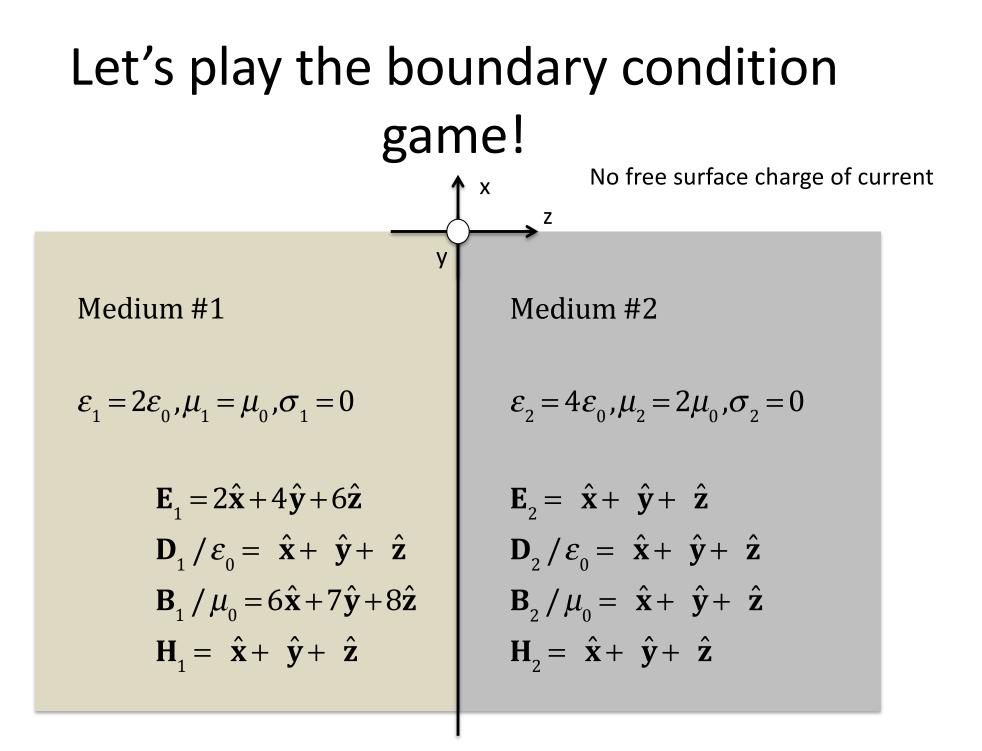
Normal Components

$$(\mathbf{D}_{N2} - \mathbf{D}_{N1}) \cdot \hat{\mathbf{n}} \Delta a = Q_f = \sigma_f \Delta a \quad \rightarrow \qquad \varepsilon_2 E_{N2} - \varepsilon_1 E_{N1} = \sigma_f$$

$$\varepsilon_0 (\mathbf{E}_{N2} - \mathbf{E}_{N1}) \cdot \hat{\mathbf{n}} \Delta a = Q_t = \sigma_t \Delta a \quad \rightarrow \qquad \varepsilon_0 E_{N2} - \varepsilon_0 E_{N1} = \sigma_t$$

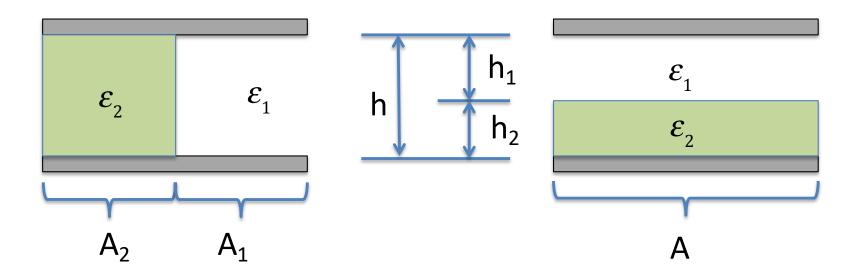
$$(\mathbf{B}_{N2} - \mathbf{B}_{N1}) \cdot \hat{\mathbf{n}} \Delta a = 0 \quad \rightarrow \qquad \mathbf{B}_{N2} = \mathbf{B}_{N1}$$

$$H_{N2} - H_{N1} = -(M_{N2} - M_{N1})$$



## Boundary Conditions in a Capacitor

V, Q

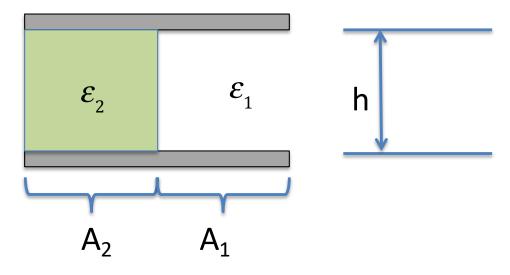


V, Q

Which boundary Conditions Apply?

# Boundary Conditions in a Capacitor

V, Q



Case #1  $E_1 = E_2 = V/h$  tangential E  $Q_1 = A_1 D_1 = A_1 \varepsilon_1 V/h$   $Q_2 = A_2 D_2 = A_2 \varepsilon_2 V/h$ Case #1  $Q = Q_1 + Q_2 = \left(\frac{A_1 \varepsilon_1 + A_2 \varepsilon_2}{h}\right) V$  $C = \left(\frac{A_1 \varepsilon_1 + A_2 \varepsilon_2}{h}\right)$  Capacitors in parallel

# **Boundary Conditions in a Capacitor**

 $h_1$ 

 $h_2$ 

V, Q

Case #2

No free surface charge on boundary

between  $\varepsilon_1$  and  $\varepsilon_2$ .

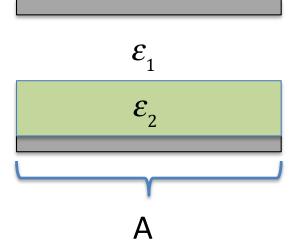
$$D_{1} = D_{2} = Q / A$$
  

$$E_{1} = D_{1} / \varepsilon_{1} = Q / (\varepsilon_{1}A)$$
  

$$E_{2} = D_{2} / \varepsilon_{2} = Q / (\varepsilon_{2}A)$$

Case #2

$$V = h_1 E_1 + h_2 E_2 = Q \left( \frac{h_1}{A\varepsilon_1} + \frac{h_2}{A\varepsilon_2} \right)$$
$$C^{-1} = \left( \frac{h_1}{A\varepsilon_1} + \frac{h_2}{A\varepsilon_2} \right)$$
Capacitors in series



# Let's play the boundary condition game! With conductivity!!

