

# General Comments

Tangential components of  $\mathbf{E}$  are always equal.

Normal components of  $\mathbf{B}$  are always equal.

Normal component of  $\mathbf{E}$  discontinuous implies a **surface charge density**.

Normal components of  $\mathbf{D}$  discontinuous implies a **free surface charge density**

Tangential components of  $\mathbf{B}$  discontinuous implies a **surface current density**.

Tangential components of  $\mathbf{H}$  discontinuous implies a **free surface current density**.

# Boundary Condition Summary

Tangential Components

$$\mathbf{E}_{T2} = \mathbf{E}_{T1} \quad \mathbf{H}_{T2} - \mathbf{H}_{T1} = \mathbf{K}_f \times \hat{\mathbf{n}} \quad \mathbf{B}_{T2} - \mathbf{B}_{T1} = \mu_0 \mathbf{K}_t \times \hat{\mathbf{n}}$$

Normal Components

$$(\mathbf{D}_{N2} - \mathbf{D}_{N1}) \cdot \hat{\mathbf{n}} \Delta a = Q_f = \sigma_f \Delta a \quad \rightarrow \quad \varepsilon_2 E_{N2} - \varepsilon_1 E_{N1} = \sigma_f$$

$$\varepsilon_0 (\mathbf{E}_{N2} - \mathbf{E}_{N1}) \cdot \hat{\mathbf{n}} \Delta a = Q_t = \sigma_t \Delta a \quad \rightarrow \quad \varepsilon_0 E_{N2} - \varepsilon_0 E_{N1} = \sigma_t$$

$$(\mathbf{B}_{N2} - \mathbf{B}_{N1}) \cdot \hat{\mathbf{n}} \Delta a = 0 \quad \rightarrow \quad \mathbf{B}_{N2} = \mathbf{B}_{N1}$$

$$H_{N2} - H_{N1} = -(M_{N2} - M_{N1})$$

# Let's play the boundary condition game!

No free surface charge or current

Medium #1

$$\epsilon_1 = 2\epsilon_0, \mu_1 = \mu_0, \sigma_1 = 0$$
$$\mathbf{E}_1 = 2\hat{\mathbf{x}} + 4\hat{\mathbf{y}} + 6\hat{\mathbf{z}}$$
$$\mathbf{D}_1 / \epsilon_0 = \hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}$$
$$\mathbf{B}_1 / \mu_0 = 6\hat{\mathbf{x}} + 7\hat{\mathbf{y}} + 8\hat{\mathbf{z}}$$
$$\mathbf{H}_1 = \hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}$$

Medium #2

$$\epsilon_2 = 4\epsilon_0, \mu_2 = 2\mu_0, \sigma_2 = 0$$
$$\mathbf{E}_2 = \hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}$$
$$\mathbf{D}_2 / \epsilon_0 = \hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}$$
$$\mathbf{B}_2 / \mu_0 = \hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}$$
$$\mathbf{H}_2 = \hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}$$

# Let's play the boundary condition game!

Medium #1

$$\epsilon_1 = 2\epsilon_0, \mu_1 = \mu_0, \sigma_1 = 0$$

$$\mathbf{E}_1 = 2\hat{\mathbf{x}} + 4\hat{\mathbf{y}} + 6\hat{\mathbf{z}}$$

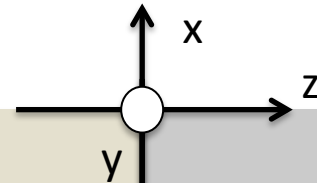
$$\mathbf{D}_1 = \epsilon_1 \mathbf{E}_1 = (2\epsilon_0) \mathbf{E}_1$$

$$\mathbf{D}_1 / \epsilon_0 = 2\mathbf{E}_1 = 4\hat{\mathbf{x}} + 8\hat{\mathbf{y}} + 12\hat{\mathbf{z}}$$

$$\mathbf{B}_1 / \mu_0 = 6\hat{\mathbf{x}} + 7\hat{\mathbf{y}} + 8\hat{\mathbf{z}}$$

$$\mathbf{H}_1 = \mathbf{B}_1 / \mu_1 = \mathbf{B}_1 / \mu_0$$

$$\mathbf{H}_1 = 6\hat{\mathbf{x}} + 7\hat{\mathbf{y}} + 8\hat{\mathbf{z}}$$



No free surface charge or current

Medium #2

$$\epsilon_2 = 4\epsilon_0, \mu_2 = 2\mu_0, \sigma_2 = 0$$

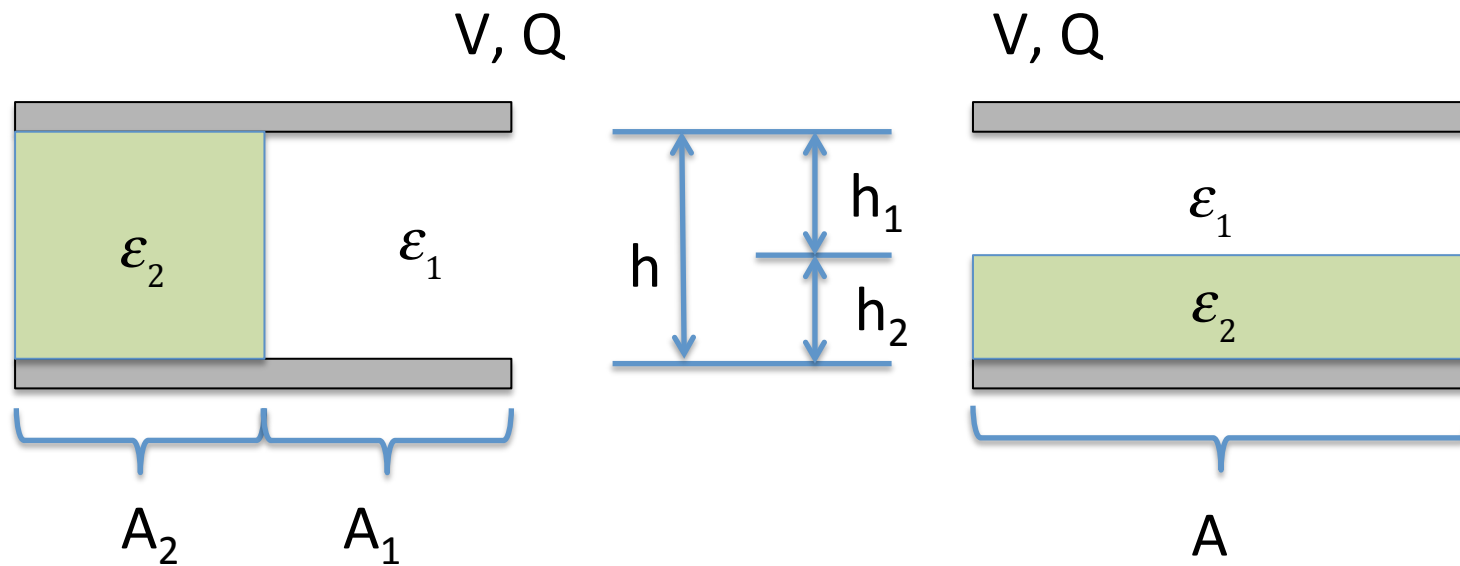
$$\mathbf{E}_2 = \hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}$$

$$\mathbf{D}_2 / \epsilon_0 = \hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}$$

$$\mathbf{B}_2 / \mu_0 = \hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}$$

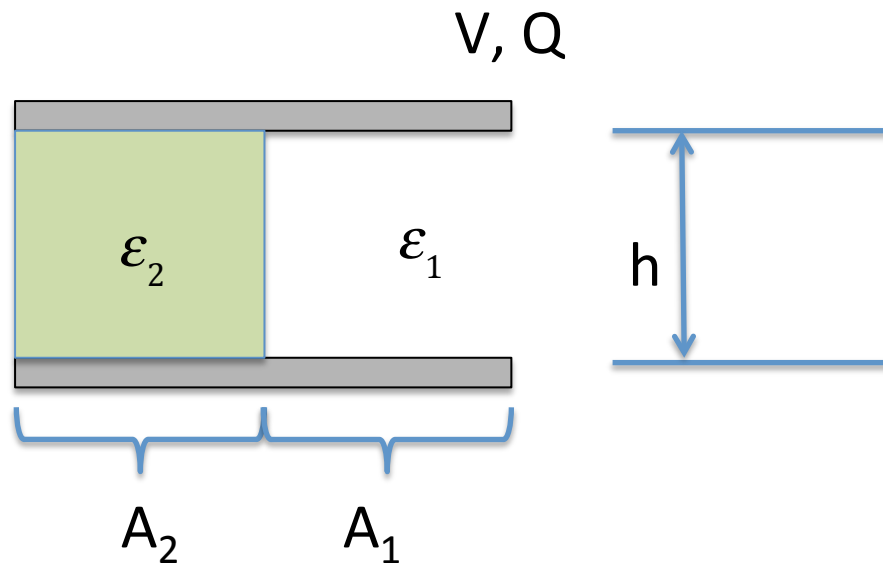
$$\mathbf{H}_2 = \hat{\mathbf{x}} + \hat{\mathbf{y}} + \hat{\mathbf{z}}$$

# Boundary Conditions in a Capacitor



Which boundary Conditions Apply?

# Boundary Conditions in a Capacitor



Case #1

$$E_1 = E_2 = V/h \quad \text{tangential } E$$

$$Q_1 = A_1 D_1 = A_1 \epsilon_1 V/h$$

$$Q_2 = A_2 D_2 = A_2 \epsilon_2 V/h$$

Case #1

$$Q = Q_1 + Q_2 = \left( \frac{A_1 \epsilon_1 + A_2 \epsilon_2}{h} \right) V$$

$$C = \left( \frac{A_1 \epsilon_1 + A_2 \epsilon_2}{h} \right) \text{ Capacitors in parallel}$$

# Boundary Conditions in a Capacitor

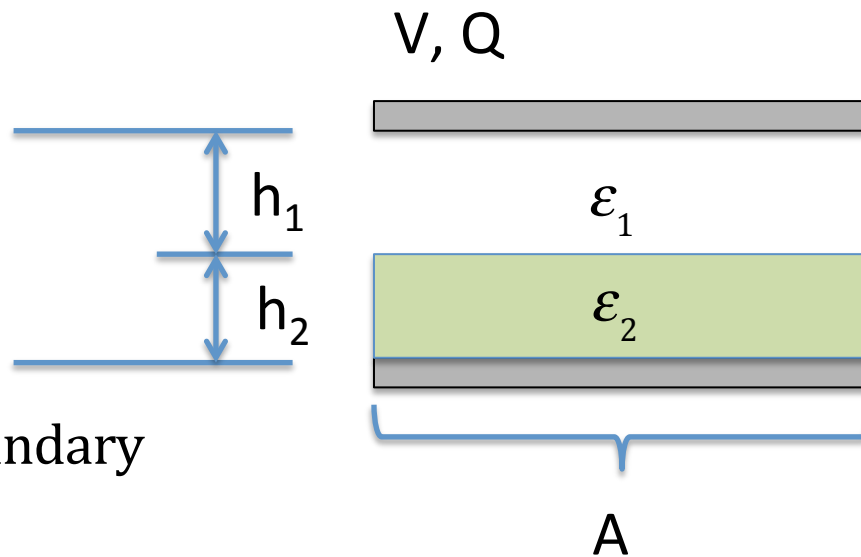
Case #2

No free surface charge on boundary  
between  $\epsilon_1$  and  $\epsilon_2$ .

$$D_1 = D_2 = Q / A$$

$$E_1 = D_1 / \epsilon_1 = Q / (\epsilon_1 A)$$

$$E_2 = D_2 / \epsilon_2 = Q / (\epsilon_2 A)$$

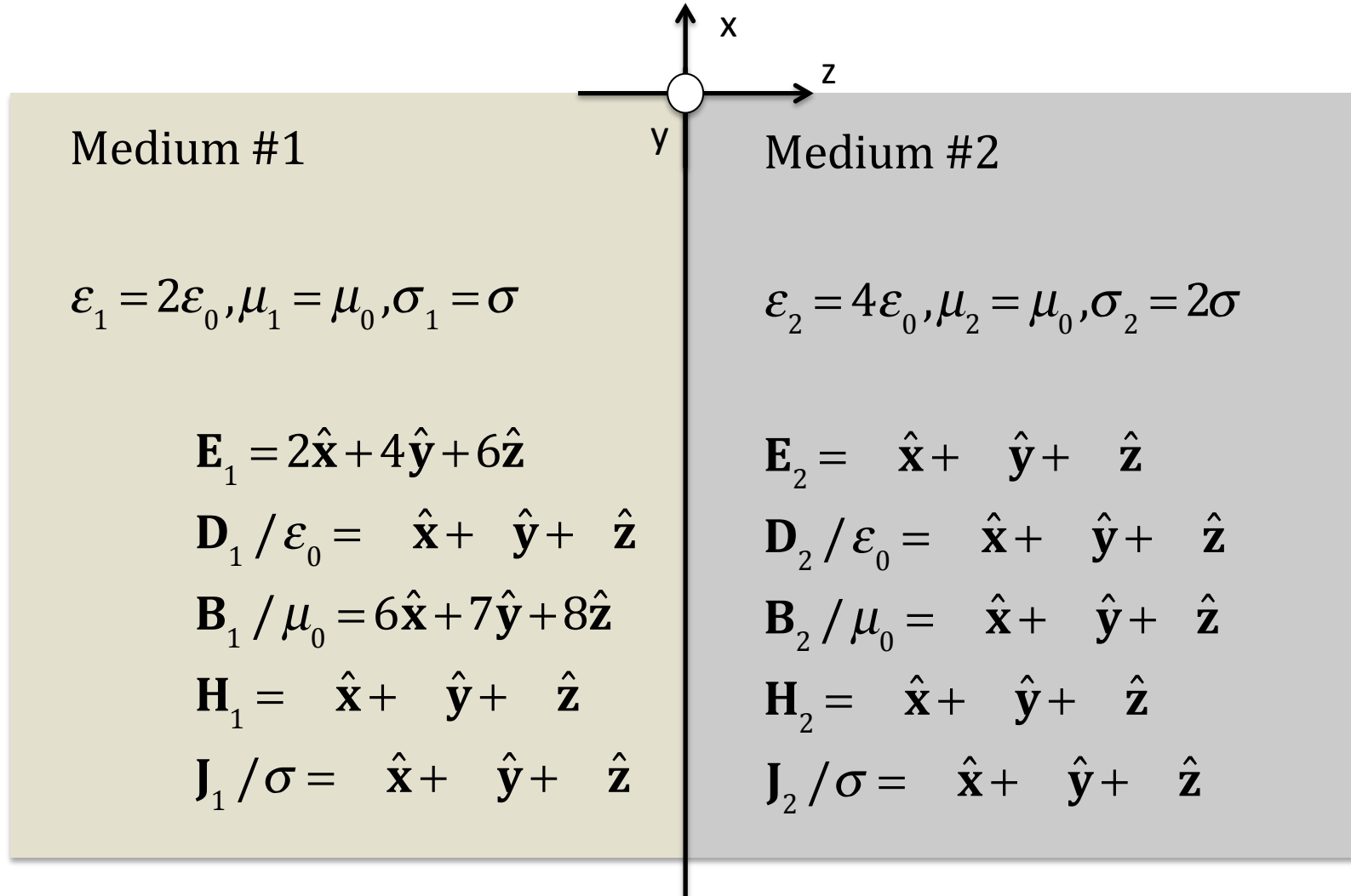


Case #2

$$V = h_1 E_1 + h_2 E_2 = Q \left( \frac{h_1}{A \epsilon_1} + \frac{h_2}{A \epsilon_2} \right)$$

$$C^{-1} = \left( \frac{h_1}{A \epsilon_1} + \frac{h_2}{A \epsilon_2} \right) \text{ Capacitors in series}$$

# Let's play the boundary condition game! With conductivity!!





# ENEE381

Lecture 4

Conservation Laws

Charge, Energy, Momentum

Griffiths Chapter 8

# Introduction

A consequence of the laws of Physics is that certain quantities are conserved once a closed system has been properly defined.

Some of these are:

Charge

Energy (and mass via  $E=mc^2$ )

Linear Momentum

Angular Momentum

# Conservation Laws

## **Noether's Theorem**

**Conservation laws** in physics are a direct consequence of **symmetries** in nature

Conservation of energy(mass)  $\rightarrow$  time invariance

Conservation of linear momentum  $\rightarrow$  translation invariance

Conservation of angular momentum  $\rightarrow$  rotation invariance

Conservation of electric charge  $\rightarrow$  gauge invariance (TBE)

# Emmy Noether (Wikipedia)

|                     |   |
|---------------------|---|
| <b>Born</b>         | Amalie Emmy Noether<br>23 March 1882<br>Erlangen, Bavaria, German Empire      |
| <b>Died</b>         | 14 April 1935 (aged 53)<br>Bryn Mawr, Pennsylvania, United States             |
| <b>Nationality</b>  | German  |
| <b>Alma mater</b>   | University of Erlangen  |
| <b>Known for</b>    | Abstract algebra<br>Theoretical physics<br>Noether's theorem                  |
| <b>Awards</b>       | Ackermann–Teubner Memorial Award (1932)                                       |
|                     | <b>Scientific career</b>  |
| <b>Fields</b>       | Mathematics and physics   |
| <b>Institutions</b> | University of Göttingen<br>Bryn Mawr College                                  |
| <b>Thesis</b>       | <i>On Complete Systems of Invariants for Ternary Biquadratic Forms</i> (1907) |



# Example: conservation of kinetic + potential energy

$$\frac{d}{dt} m\mathbf{v} = q[\mathbf{E} + \mathbf{v} \times \mathbf{B}] \quad \text{Newton's law of motion (F=ma)}$$

Quasi-Static Fields:  $\mathbf{E} = -\nabla\Phi(\mathbf{x},t)$

$$\mathbf{v} \cdot \frac{d}{dt} m\mathbf{v} = \frac{d}{dt} \frac{m|\mathbf{v}|^2}{2} = q\mathbf{v} \cdot [\mathbf{E} + \mathbf{v} \times \mathbf{B}] = -q\mathbf{v} \cdot \nabla\Phi$$

Rate of change of potential following a trajectory

$$\frac{d}{dt} q\Phi(t, \mathbf{x}(t)) = \frac{\partial}{\partial t} q\Phi + q\mathbf{v} \cdot \nabla\Phi$$

$$\frac{d}{dt} \left( \frac{m|\mathbf{v}|^2}{2} + q\Phi \right) = \frac{\partial}{\partial t} q\Phi \quad \text{Kinetic + Potential Energy is conserved only if potential is time independent}$$

# Conservation of Linear Momentum

$$\frac{d}{dt} m_i \mathbf{v}_i = q_i \mathbf{E}(\mathbf{x}_i, t) \quad \mathbf{E}(\mathbf{x}_i, t) = \sum_{j \neq i} \frac{q_j (\mathbf{x}_i - \mathbf{x}_j)}{4\pi\epsilon_0 |\mathbf{x}_i - \mathbf{x}_j|^3}$$

$$\frac{d}{dt} \sum_i m_i \mathbf{v}_i = \frac{d}{dt} \mathbf{P} = \sum_{i,j \neq i} \frac{q_i q_j (\mathbf{x}_i - \mathbf{x}_j)}{4\pi\epsilon_0 |\mathbf{x}_i - \mathbf{x}_j|^3} = 0$$

Momentum  $\mathbf{P}$  is constant,  
velocity of center of mass is constant

$$\frac{d}{dt} \mathbf{x}_{cm} = \frac{d}{dt} \frac{\sum_i m_i \mathbf{x}_i}{\sum_i m_i} = \frac{\mathbf{P}}{M} = \text{constant}$$

If  $\mathbf{P} = 0$ ,  $\mathbf{x}_{cm}$  can not change

System is symmetric wrt translation in 3 directions. Three constants of motion: 3 components of  $\mathbf{P}$ .

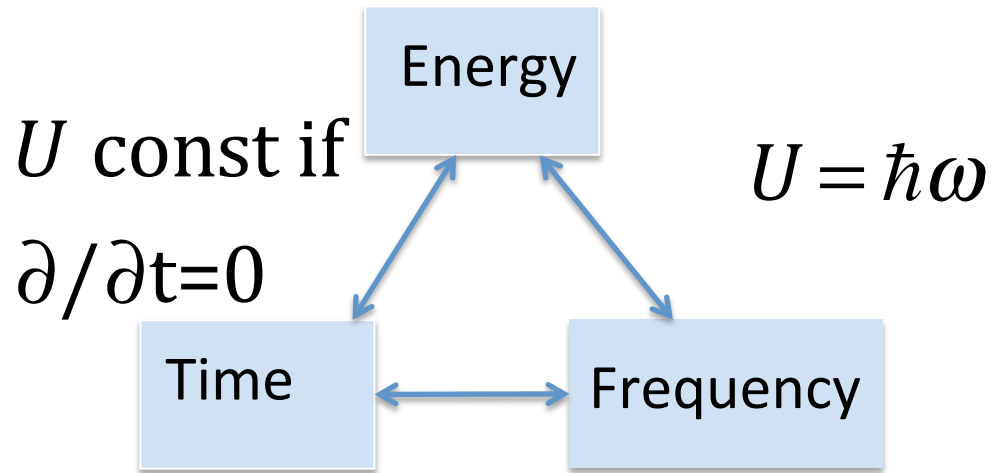
# Conservation of Angular Momentum

$$\frac{d}{dt} m_i \mathbf{v}_i = q_i \mathbf{E}(\mathbf{x}_i, t) \quad \mathbf{E}(\mathbf{x}_i, t) = \sum_{j \neq i} \frac{q_j (\mathbf{x}_i - \mathbf{x}_j)}{4\pi\epsilon_0 |\mathbf{x}_i - \mathbf{x}_j|^3}$$

$$\begin{aligned} \frac{d}{dt} \mathbf{L} &= \frac{d}{dt} \sum_i \mathbf{x}_i \times m_i \mathbf{v}_i = \sum_i \left( \frac{d\mathbf{x}_i}{dt} \times m_i \mathbf{v}_i + \mathbf{x}_i \times \frac{d}{dt} m_i \mathbf{v}_i \right) \\ &= \sum_{i, j \neq i} \mathbf{x}_i \times \frac{q_i q_j (\mathbf{x}_i - \mathbf{x}_j)}{4\pi\epsilon_0 |\mathbf{x}_i - \mathbf{x}_j|^3} = 0 \end{aligned}$$

System is symmetric wrt rotation in 3 directions. Three constants of motion: 3 components of  $\mathbf{L}$ .

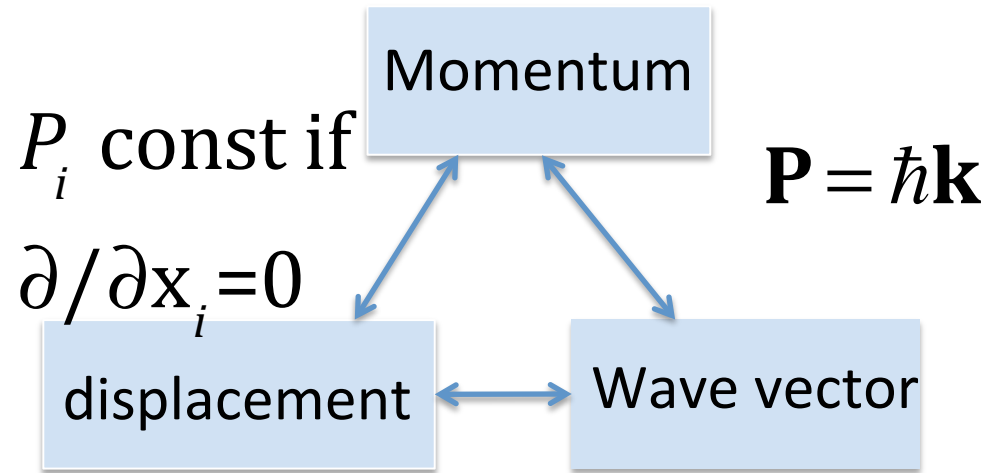
# Linked Quantities



$$1 = \Delta t \Delta \omega$$

Sinusoidal waves

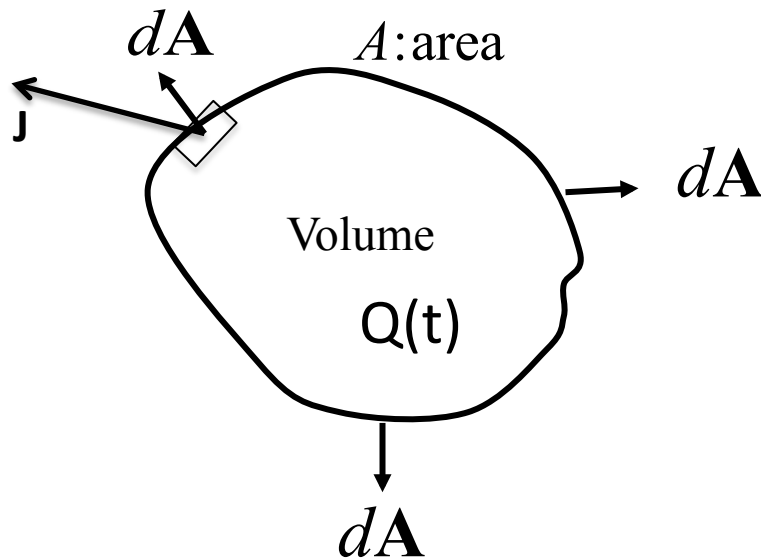
$$\exp(i\mathbf{k} \cdot \mathbf{x} - i\omega t)$$



$$1 = \Delta x \Delta k$$



# What does a conservation law for continuous systems look like?



Conservation of charge

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \vec{J} = 0$$

$$\frac{dQ}{dt} + \int_S d\vec{A} \cdot \vec{J} = 0$$

$$Q = \int_V d^3r \rho(\mathbf{r}, t)$$

$$\int_S d\vec{A} \cdot \vec{J} = \int_V d^3r \nabla \cdot \vec{J}$$

# Conservation of Energy

$$\frac{\partial}{\partial t} [u_E + u_M] + \nabla \cdot \vec{S} = -\vec{E} \cdot \vec{J}$$

Rate at which energy is transferred to current  $\mathbf{J}$

$$u_E + u_M = \frac{\epsilon_0}{2} \mathbf{E} \cdot \mathbf{E} + \frac{1}{2\mu_0} \mathbf{B} \cdot \mathbf{B}$$

Energy density in fields

$\mathbf{S} = \mathbf{E} \times \mathbf{H}$  : Poynting vector

Flow of local energy density

# Conservation of energy

$$\nabla \times \vec{\mathbf{E}} = -\frac{\partial \vec{\mathbf{B}}}{\partial t} \qquad \nabla \times \vec{\mathbf{B}} = \mu_0 \left[ \vec{\mathbf{J}} + \epsilon_0 \frac{\partial \vec{\mathbf{E}}}{\partial t} \right]$$

$$\frac{\vec{\mathbf{B}}}{\mu_0} \cdot \nabla \times \vec{\mathbf{E}} = -\frac{\vec{\mathbf{B}}}{\mu_0} \cdot \frac{\partial \vec{\mathbf{B}}}{\partial t} \qquad \vec{\mathbf{E}} \cdot \nabla \times \frac{\vec{\mathbf{B}}}{\mu_0} = \left[ \vec{\mathbf{E}} \cdot \vec{\mathbf{J}} + \epsilon_0 \vec{\mathbf{E}} \cdot \frac{\partial \vec{\mathbf{E}}}{\partial t} \right]$$

$$\epsilon_0 \vec{\mathbf{E}} \cdot \frac{\partial \vec{\mathbf{E}}}{\partial t} + \frac{\vec{\mathbf{B}}}{\mu_0} \cdot \frac{\partial \vec{\mathbf{B}}}{\partial t} + \frac{\vec{\mathbf{B}}}{\mu_0} \cdot \nabla \times \vec{\mathbf{E}} - \vec{\mathbf{E}} \cdot \nabla \times \frac{\vec{\mathbf{B}}}{\mu_0} = -\vec{\mathbf{E}} \cdot \vec{\mathbf{J}}$$

$$\frac{\partial}{\partial t} \left( \frac{\epsilon_0 |\vec{\mathbf{E}}|^2}{2} + \frac{|\vec{\mathbf{B}}|^2}{2\mu_0} \right) + \nabla \cdot \left( \vec{\mathbf{E}} \times \frac{\vec{\mathbf{B}}}{\mu_0} \right) = -\vec{\mathbf{E}} \cdot \vec{\mathbf{J}}$$

# Poynting's Theorem

$$\frac{\partial}{\partial t} \left( \frac{\epsilon_0 |\mathbf{E}|^2}{2} + \frac{\mu_0 |\mathbf{H}|^2}{2} \right) + \nabla \cdot (\mathbf{E} \times \mathbf{H}) = -\mathbf{E} \cdot \mathbf{J}$$

Energy density

$$\left( \frac{\epsilon_0 |\mathbf{E}|^2}{2} + \frac{\mu_0 |\mathbf{H}|^2}{2} \right)$$

Units:      Joules/m<sup>3</sup>

Power Flux

$$\mathbf{S} = (\mathbf{E} \times \mathbf{H})$$

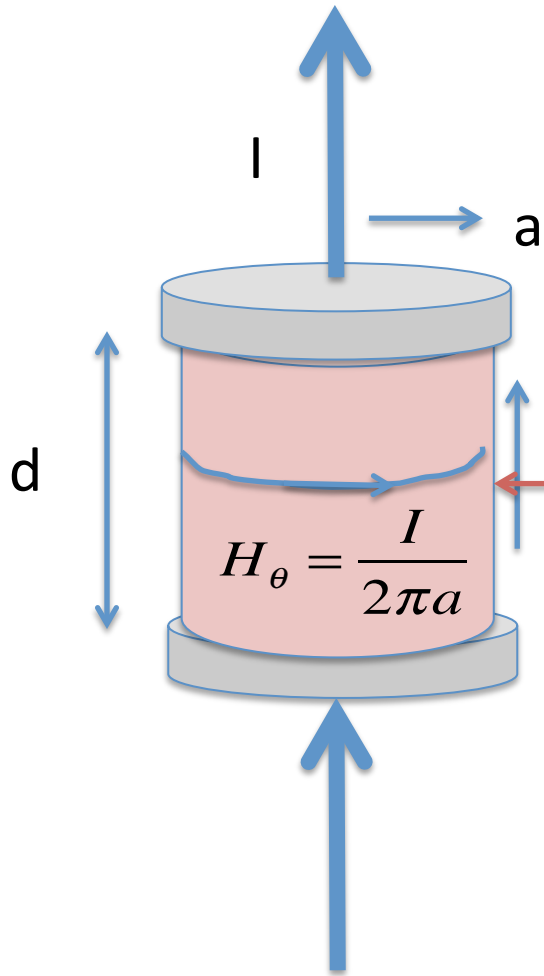
Watts/m<sup>2</sup>

Rate of work done  
by E on J

$$\mathbf{E} \cdot \mathbf{J}$$

Watts/m<sup>3</sup>

# Poynting Example



$$E_z = J_z / \sigma = I / (\pi a^2 \sigma)$$

$$\vec{S} = (\vec{E} \times \vec{H})$$

$$H_\theta = \frac{I}{2\pi a}$$

$$S_r = -E_z H_\theta = -I^2 / (2\pi^2 a^3 \sigma)$$

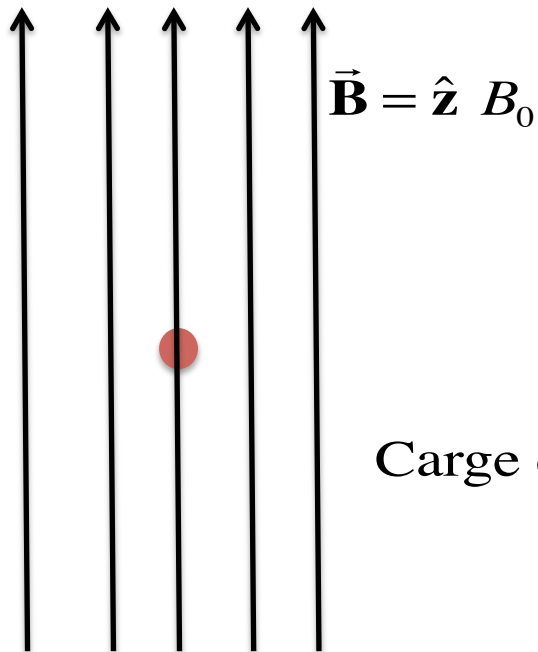
Power in:

$$P = 2\pi a d |S_r| = I^2 / (\pi a^2 \sigma) = RI^2$$

Area of side

Resistance

# Only divergence of Poynting flux matters



Charge  $q$  at  $\mathbf{r} = 0$

Find  $S$ :

What direction?

What does it mean?

# Poynting's theorem addresses EM energy, what about mechanical energy?

$$\frac{\partial}{\partial t} \left( \frac{\epsilon_0 |\mathbf{E}|^2}{2} + \frac{\mu_0 |\mathbf{H}|^2}{2} \right) + \nabla \cdot (\mathbf{E} \times \mathbf{H}) = -\mathbf{E} \cdot \mathbf{J}$$

Rate of work done by E on J

Newton's Law  $m\mathbf{a}=\mathbf{F}$

$$m \frac{d}{dt} \mathbf{v}_i = q [\mathbf{E} + \mathbf{v}_i \times \mathbf{B}]$$

$$m \sum_i \mathbf{v}_i \cdot \frac{d}{dt} \mathbf{v}_i = \sum_i \mathbf{v}_i \cdot q [\mathbf{E} + \mathbf{v}_i \times \mathbf{B}] = \sum_i \mathbf{v}_i \cdot q \mathbf{E} = \int_V d^3r \mathbf{v}_i \cdot q \mathbf{E}$$

$$\sum_i \frac{d}{dt} \frac{m |\mathbf{v}_i|^2}{2} = \int_V d^3r \mathbf{v}_i \cdot q \mathbf{E} = \int_V d^3r \mathbf{J} \cdot \mathbf{E}$$

# Combining EM and Mechanical Energy

$$\frac{d}{dt} \left\{ \int_V d^3r \left( \frac{\epsilon_0 |\mathbf{E}|^2}{2} + \frac{\mu_0 |\mathbf{H}|^2}{2} \right) + \sum_i \frac{m |\mathbf{v}_i|^2}{2} \right\} + \int_S d\mathbf{A} \cdot (\mathbf{E} \times \mathbf{H}) = 0$$

EM + Mechanical Energy

EM power flow



## Conservation of EM Momentum

The total EM force on charges in a volume can be written as

$$\frac{d\mathbf{P}_{mech}}{dt} = \sum_i q(\mathbf{E}(\mathbf{x}_i) + \mathbf{v}_i \times \mathbf{B}(\mathbf{x}_i)) = \int_V (\rho\mathbf{E} + \mathbf{J} \times \mathbf{B}) d^3r$$

|                 |  |
|-----------------|--|
| After some Math | $\frac{d\mathbf{P}_{mech}}{dt} + \frac{d\mathbf{P}_{EM}}{dt} = \oint_A \bar{\bar{\mathbf{T}}} \cdot \hat{\mathbf{n}} da$ |
|-----------------|--|

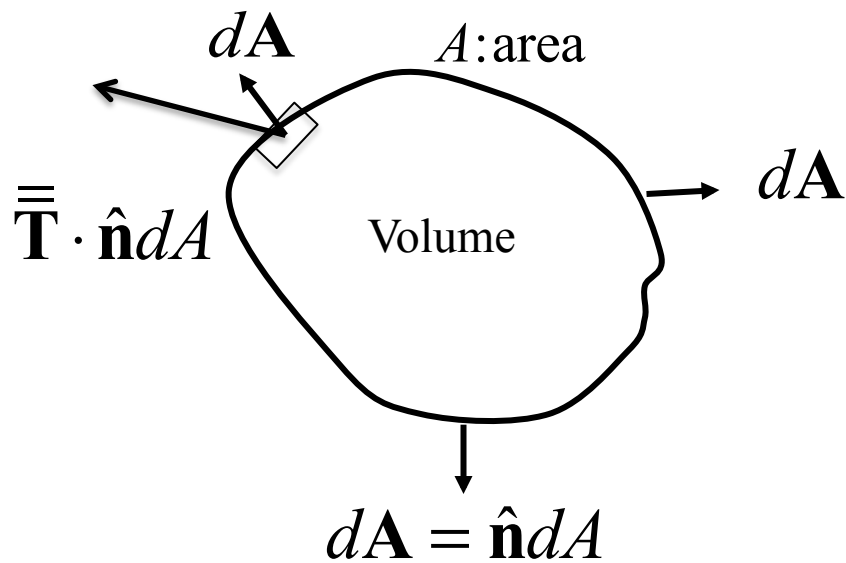
Total EM linear momentum:  $\mathbf{P}_{EM} = \epsilon_0 \mu_0 \int_V \mathbf{E} \times \mathbf{H} d^3r$

EM linear momentum density:  $\epsilon_0 \mu_0 \mathbf{E} \times \mathbf{H} = \mathbf{S} / c^2$

Poynting vector:  $\mathbf{S} = \mathbf{E} \times \mathbf{H}$ ,  $\mu_0 \epsilon_0 = 1 / c^2$

Maxwell Stress Tensor:  $\bar{\bar{\mathbf{T}}} = \epsilon_0 \mathbf{E}\mathbf{E} + \frac{1}{\mu_0} \mathbf{B}\mathbf{B} - \frac{1}{2} (\epsilon_0 \mathbf{E} \cdot \mathbf{E} + \frac{1}{\mu_0} \mathbf{B} \cdot \mathbf{B}) \bar{\bar{\mathbf{I}}}$

# Force on what's inside



$$\frac{d\mathbf{P}_{mech}}{dt} + \frac{d\mathbf{P}_{EM}}{dt} = \mathbf{F}$$

$$\mathbf{F} = \oint_A \bar{\bar{\mathbf{T}}} \cdot \hat{\mathbf{n}}dA$$

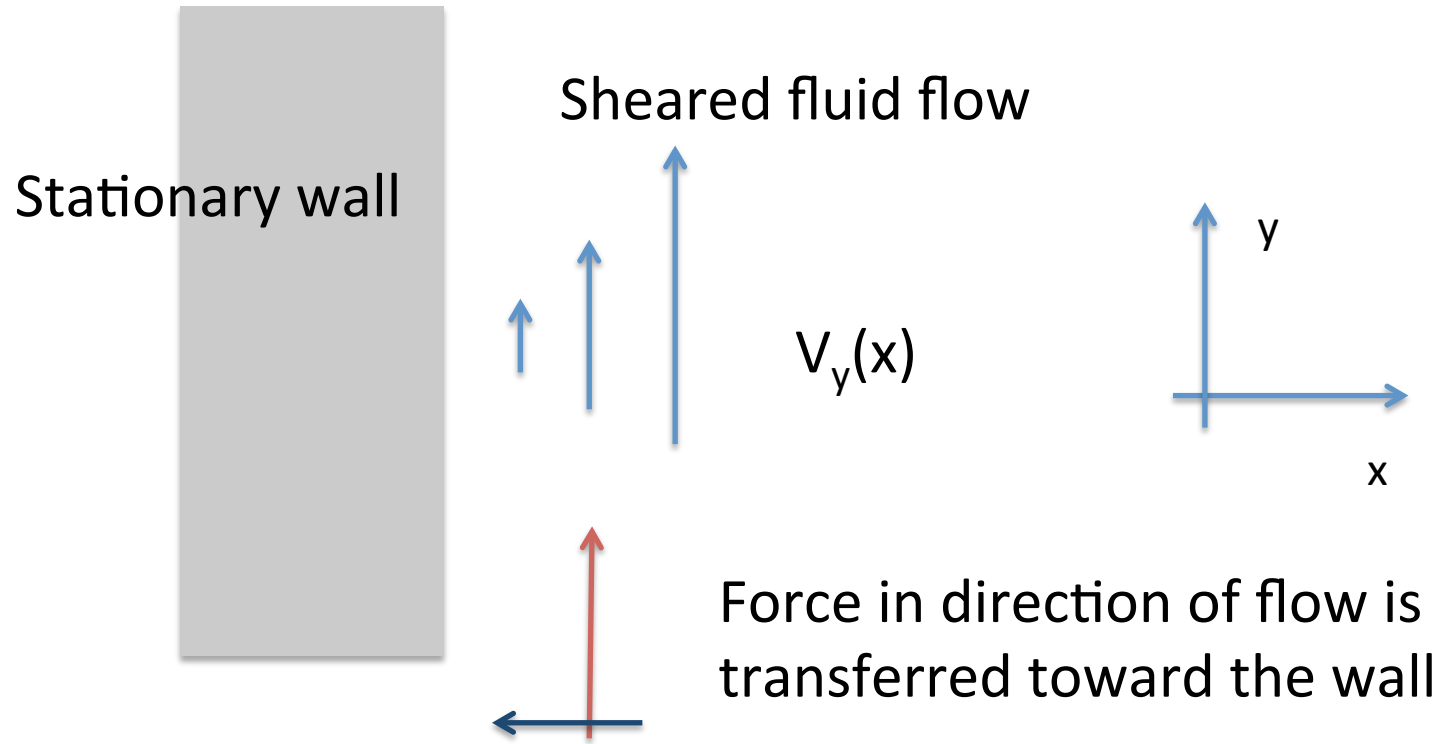
Analogy: pressure

$$\bar{\bar{\mathbf{T}}} = -p\bar{\bar{\mathbf{I}}}$$

$$\bar{\bar{\mathbf{T}}} \cdot \hat{\mathbf{n}} = -p\hat{\mathbf{n}}$$

$$\text{Maxwell Stress Tensor: } \bar{\bar{\mathbf{T}}} = \epsilon_0 \mathbf{E}\mathbf{E} + \frac{1}{\mu_0} \mathbf{B}\mathbf{B} - \frac{1}{2} (\epsilon_0 \mathbf{E} \cdot \mathbf{E} + \frac{1}{\mu_0} \mathbf{B} \cdot \mathbf{B}) \bar{\bar{\mathbf{I}}}$$

# Viscous Fluid Stress



Force in direction of flow is transferred toward the wall

$$T_{xy} \propto \nu \frac{\partial v_y(x)}{\partial x}$$

# Energy and Momentum of Light

$$\left( \frac{\epsilon_0 |\mathbf{E}|^2}{2} + \frac{\mu_0 |\mathbf{H}|^2}{2} \right)$$

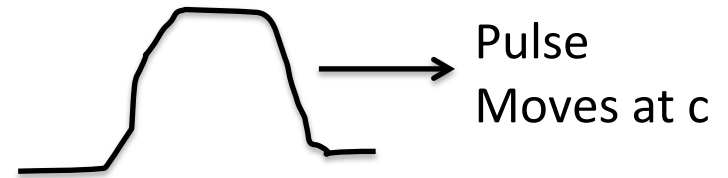
Energy density

Units: Joules/m<sup>3</sup>

$$\vec{\mathbf{S}} = (\vec{\mathbf{E}} \times \vec{\mathbf{H}})$$

Power Flux

Watts/m<sup>2</sup>



Power Flux = c Energy Density

Pulse also contains momentum

EM linear momentum density:  $\epsilon_0 \mu_0 \mathbf{E} \times \mathbf{H} = \mathbf{S} / c^2$

$$\frac{\text{Energy Density}}{\text{Momentum Density}} = \frac{S / c}{S / c^2} = c$$

A pulse of light carries energy and momentum: ratio = c

## Mass Energy Equivalence $E = mc^2$

Isolated box of mass  $M$  and length  $L$  in space.  
 A light on the wall on one side sends out a pulse of energy  $E$  toward the right.  
 The pulse has momentum  $p = E/c$ .  
 The box recoils with velocity  $v = p/M$  to the left.  
 The pulse is absorbed on the other side after a time  $T = L/c$ .  
 The box absorbs the momentum and stops moving.

Displacement of the box  $\Delta x = vT = \frac{EL}{Mc^2}$

Has the center of mass moved?

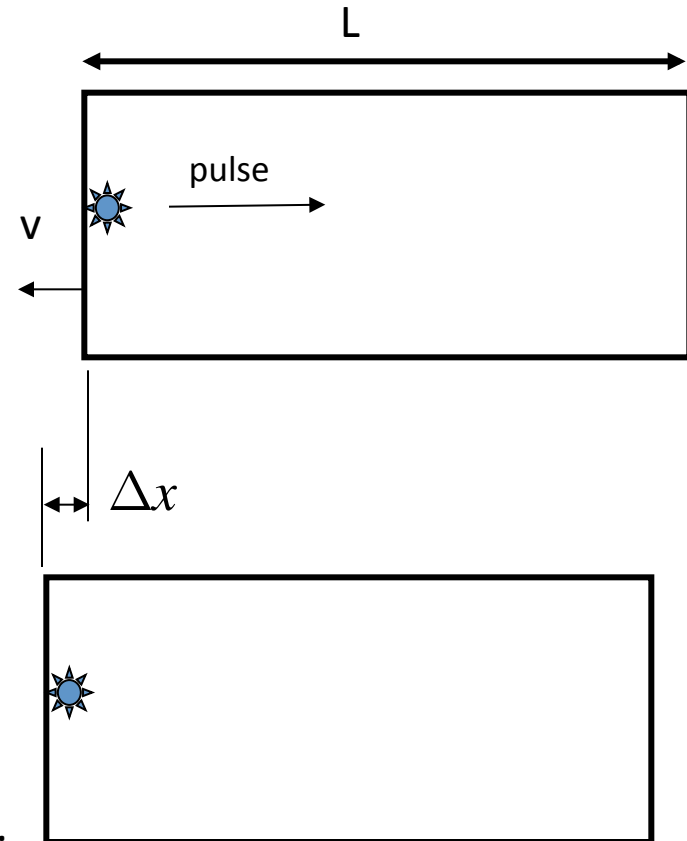
We would like to say no.

The box should not be able to move its center of mass.

$$\Delta x M = L \left( E / c^2 \right) = Lm$$

We can say that the CM has not moved if the pulse reduced the mass of the left side by  $m = E/c^2$  and increased the right side by the same amount.

$$E = mc^2$$



# Stress Tensor

$$\bar{\bar{\mathbf{T}}} = \epsilon_0 \mathbf{E}\mathbf{E} + \frac{1}{\mu_0} \mathbf{B}\mathbf{B} - \frac{1}{2} \left( \epsilon_0 \mathbf{E} \cdot \mathbf{E} + \frac{1}{\mu_0} \mathbf{B} \cdot \mathbf{B} \right) \bar{\bar{\mathbf{I}}}$$

Force transmitted through surface  $\mathbf{F} = \oint_A \bar{\bar{\mathbf{T}}} \cdot \hat{\mathbf{n}} da$

The component normal to the surface is like a pressure force  $\mathbf{n} \cdot \bar{\bar{\mathbf{T}}} \cdot \mathbf{n} = -p$

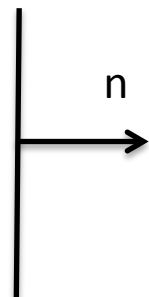
$$\mathbf{n} \cdot \bar{\bar{\mathbf{T}}} \cdot \mathbf{n} = \epsilon_0 \left[ \frac{1}{2} (\mathbf{n} \cdot \mathbf{E})^2 - \frac{1}{2} |\mathbf{E}_t|^2 \right] + \frac{1}{\mu_0} \left[ \frac{1}{2} (\mathbf{n} \cdot \mathbf{B})^2 - \frac{1}{2} |\mathbf{B}_t|^2 \right]$$

Remember BC's

$E_t$  and  $B_n$  are continuous

Normal E pulls on surface

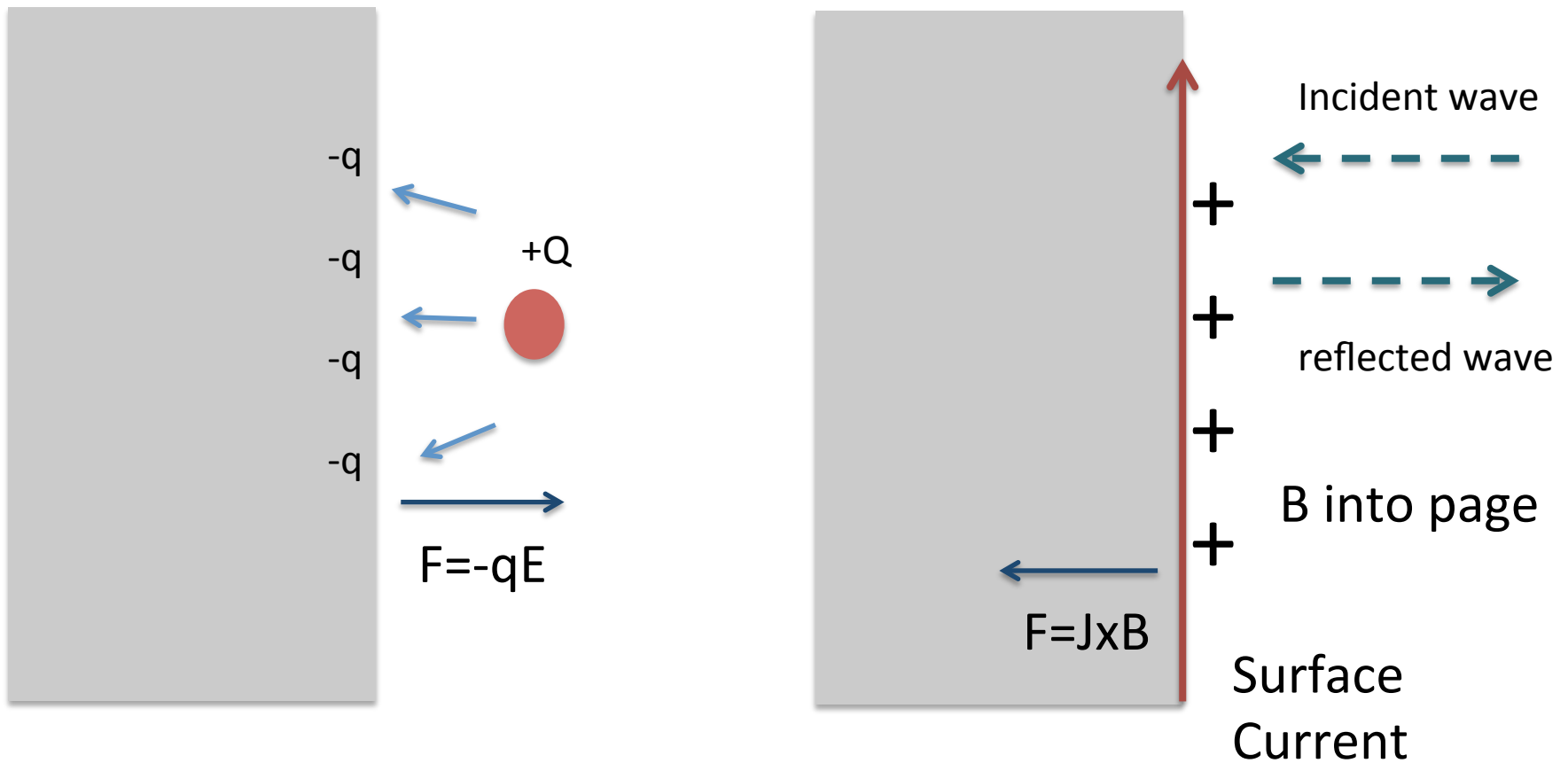
Tangential B pushes



Surface of conductor

$$\mathbf{n} \cdot \bar{\bar{\mathbf{T}}} \cdot \mathbf{n} = \epsilon_0 \left[ \frac{1}{2} (\mathbf{n} \cdot \mathbf{E})^2 \right] + \frac{1}{\mu_0} \left[ -\frac{1}{2} |\mathbf{B}_t|^2 \right]$$

# Forces on Conductor



Electric field force on surface charge pulls

# Force of attraction between capacitor plates

Diagram illustrating the force of attraction between capacitor plates. The left plate is labeled  $-Q$  and the right plate is labeled  $+Q$ . Blue arrows represent the electric field  $\mathbf{E}$  pointing from the positive plate to the negative plate. A red arrow labeled  $\mathbf{F}$  points from the positive plate towards the negative plate, representing the force of attraction. The area of the plates is labeled  $\text{Area} = A$ .

Surface charge density  
 $\sigma = Q/A$   
 $E_n = \sigma / \epsilon_0$

$$\mathbf{F} = \oint_A \bar{\mathbf{T}} \cdot \hat{\mathbf{n}} da$$

$$\mathbf{n} \cdot \bar{\mathbf{T}} \cdot \mathbf{n} = \epsilon_0 \left[ \frac{1}{2} (\mathbf{n} \cdot \mathbf{E})^2 \right] = \frac{1}{2} \frac{Q^2}{A^2 \epsilon_0}$$

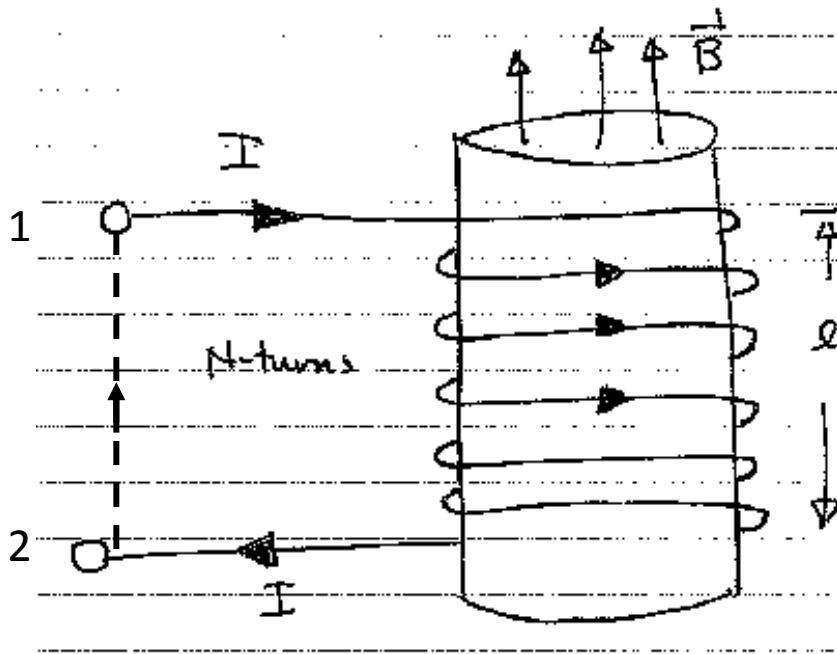
$$F = \frac{1}{2} \frac{Q^2}{A \epsilon_0}$$

How much work must be done to separate plates a distance  $h$ ?

$$\text{Work} = hF = \frac{h}{2} \frac{Q^2}{A \epsilon_0} = \frac{1}{2} \frac{Q^2}{C} \quad \text{capacitance}$$



# What is the force on the windings of a coil?



$$\mathbf{n} \cdot \vec{\mathbb{T}} \cdot \mathbf{n} = \epsilon_0 \left[ \frac{1}{2} (\mathbf{n} \cdot \mathbf{E})^2 - \frac{1}{2} |\mathbf{E}_t|^2 \right] + \frac{1}{\mu_0} \left[ \frac{1}{2} (\mathbf{n} \cdot \mathbf{B})^2 - \frac{1}{2} |\mathbf{B}_t|^2 \right]$$

# Energy Density in a Linear Medium

Field Energy

|  |   |   |
|--|---|---|
| Energy density   | Power Flux  | Rate of work done<br>by E on J            |
| $\left( \frac{\epsilon_0  \vec{\mathbf{E}} ^2}{2} + \frac{ \vec{\mathbf{B}} ^2}{2\mu_0} \right)$ | $\vec{\mathbf{S}} = (\vec{\mathbf{E}} \times \vec{\mathbf{H}})$ | $\vec{\mathbf{E}} \cdot \vec{\mathbf{J}}$ |

$$\vec{\mathbf{B}} = \mu \vec{\mathbf{H}} \quad \vec{\mathbf{D}} = \epsilon \vec{\mathbf{E}}$$

|   |   |   |
|---|---|---|
| Energy density  | Power Flux  | Rate of work done<br>by E on J            |
| $\left( \frac{\epsilon  \vec{\mathbf{E}} ^2}{2} + \frac{\mu  \vec{\mathbf{H}} ^2}{2} \right)$ | $\vec{\mathbf{S}} = (\vec{\mathbf{E}} \times \vec{\mathbf{H}})$ | $\vec{\mathbf{E}} \cdot \vec{\mathbf{J}}$ |

Almost always wrong

$$\frac{\partial}{\partial \omega} \left( \frac{\omega \epsilon |\vec{\mathbf{E}}|^2}{2} + \frac{\omega \mu |\vec{\mathbf{H}}|^2}{2} \right)$$