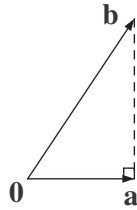


ENEE 222: 3/07 Class

Material: Lecture videos 10.1, 10.2

1. If vectors \mathbf{a} and \mathbf{b} are as shown in the figure below, which (one or more) of the following statements are true?



- A. Vectors \mathbf{a} and \mathbf{b} are orthogonal.
B. Vectors \mathbf{a} and $\mathbf{b} - \mathbf{a}$ are orthogonal.
C. $\langle \mathbf{a}, \mathbf{b} \rangle = \|\mathbf{a}\| \cdot \|\mathbf{b}\|$
D. $\langle \mathbf{a}, \mathbf{b} \rangle = \|\mathbf{a}\|^2$
2. The angle between $\mathbf{a} = [3 \ 1 \ 1 \ 5]^T$ and $\mathbf{b} = [1 \ -5 \ -1 \ -3]^T$ equals
- A. $\pi/3$
B. $\cos^{-1}(-1/8)$
C. $\cos^{-1}(-1/72)$
D. $2\pi/3$
3. Vectors \mathbf{u} , \mathbf{v} and \mathbf{w} are mutually orthogonal and such that $\|\mathbf{u}\| = 1$, $\|\mathbf{v}\| = 2$ and $\|\mathbf{w}\| = 3$. Let

$$\mathbf{s} = 5\mathbf{u} + 7\mathbf{v} - 2\mathbf{w}$$

If $\hat{\mathbf{s}}$ is the projection of \mathbf{s} onto the subspace defined by \mathbf{u} and \mathbf{v} , then $\|\mathbf{s} - \hat{\mathbf{s}}\|$ equals

- A. 6
B. 12
C. 18
D. -6

4. (HW 11 i) Show that

$$\mathbf{v}^{(1)} = [3 \ 1 \ 1 \ -1]^T, \quad \mathbf{v}^{(2)} = [1 \ -2 \ 0 \ 1]^T \quad \text{and} \quad \mathbf{v}^{(3)} = [-1 \ 1 \ 5 \ 3]^T$$

are mutually orthogonal, and compute their norms.

5. (HW 11 ii) If $\mathbf{s} = [1 \ 6 \ 2 \ 7]^T$, determine the projection $\mathbf{f}^{(i)}$ of \mathbf{s} onto each $\mathbf{v}^{(i)}$.

6. (HW 11 iv) Determine the angle between \mathbf{s} and the plane defined by $\mathbf{v}^{(2)}$ and $\mathbf{v}^{(3)}$.

7. (HW 11 v, vi) If \mathbf{g} is the projection of \mathbf{s} onto the three-dimensional subspace defined by $\mathbf{v}^{(1)}$, $\mathbf{v}^{(2)}$ and $\mathbf{v}^{(3)}$, determine the error vector $\mathbf{s} - \mathbf{g}$. What special property does $\mathbf{s} - \mathbf{g}$ have?

8. (HW 11 v, vii) Solve the system

$$\begin{bmatrix} 3 & 1 & -1 & 1 \\ 1 & -2 & 1 & 2 \\ 1 & 0 & 5 & -2 \\ -1 & 1 & 3 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$$

without using Gaussian elimination.