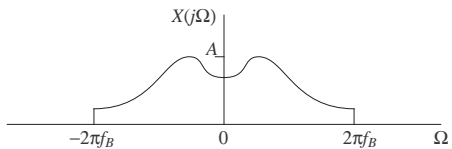
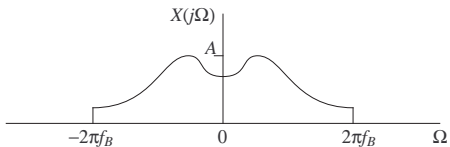


Bandlimited Case: Sampling

Bandlimited Case: Sampling

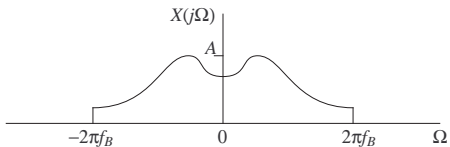


Bandlimited Case: Sampling



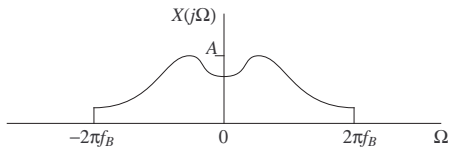
$$x[n] = x(n\Delta)$$

Bandlimited Case: Sampling



$$x[n] = x(n\Delta) = x(n/f_s)$$

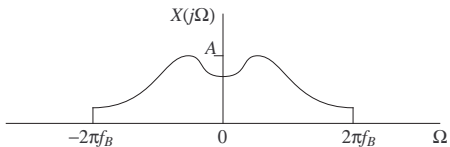
Bandlimited Case: Sampling



$$x[n] = x(n\Delta) = x(n/f_s)$$

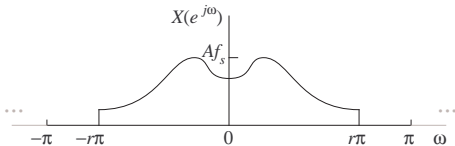
- $r = 2f_B/f_s < 1$:

Bandlimited Case: Sampling

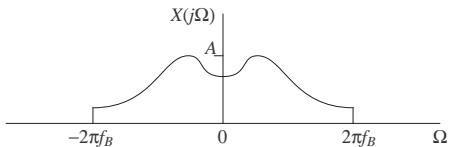


$$x[n] = x(n\Delta) = x(n/f_s)$$

- $r = 2f_B/f_s < 1$:

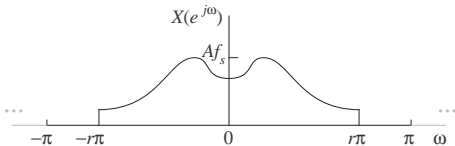


Bandlimited Case: Sampling



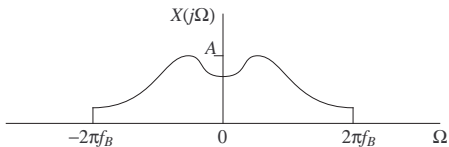
$$x[n] = x(n\Delta) = x(n/f_s)$$

- $r = 2f_B/f_s < 1$:



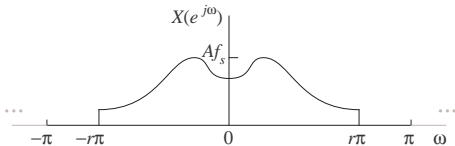
$$x(t) = \sum_{n=-\infty}^{\infty} x[n] \cdot \text{sinc}((t/\Delta) - n)$$

Bandlimited Case: Sampling



$$x[n] = x(n\Delta) = x(n/f_s)$$

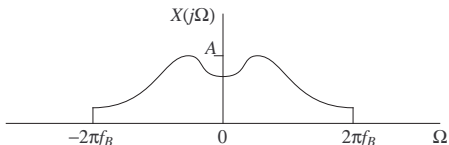
- $r = 2f_B/f_s < 1$:



$$x(t) = \sum_{n=-\infty}^{\infty} x[n] \cdot \text{sinc}((t/\Delta) - n)$$

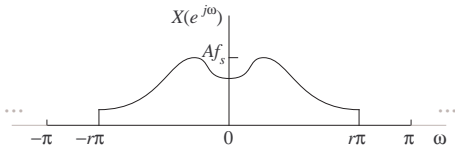
- $r = 2f_B/f_s > 1$:

Bandlimited Case: Sampling



$$x[n] = x(n\Delta) = x(n/f_s)$$

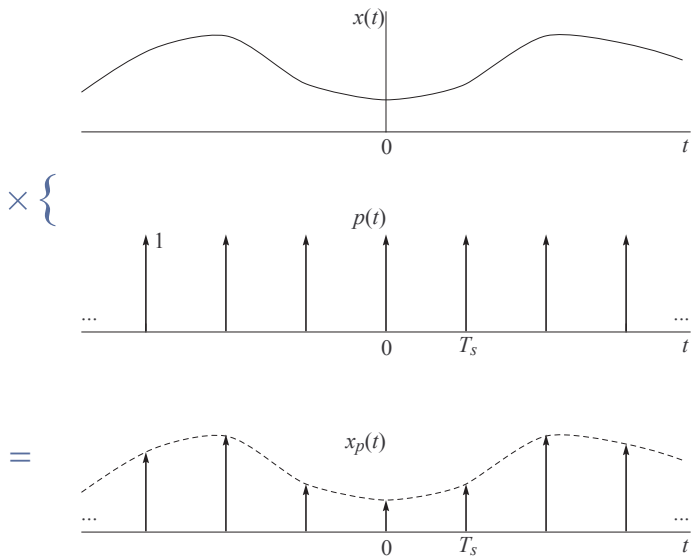
- $r = 2f_B/f_s < 1$:



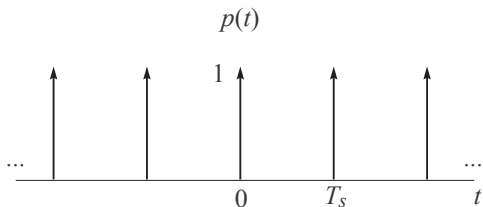
$$x(t) = \sum_{n=-\infty}^{\infty} x[n] \cdot \text{sinc}((t/\Delta) - n)$$

- $r = 2f_B/f_s > 1$: Interpolation impossible due to **aliasing**

Impulse Sampling in Time Domain



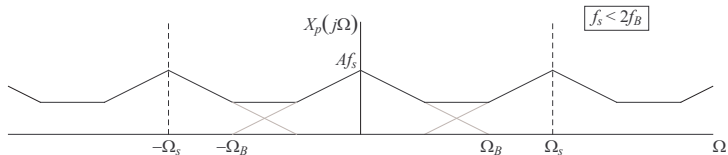
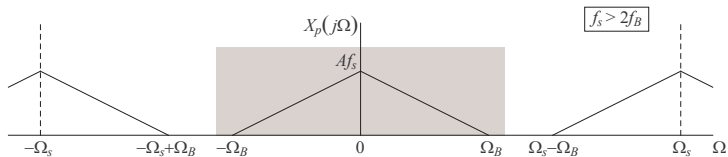
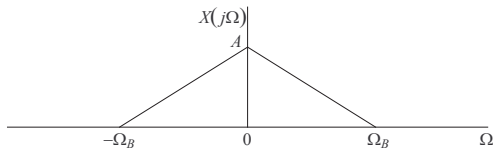
Periodic Impulse Train



$$p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s) = f_s \cdot \sum_{k=-\infty}^{\infty} e^{jk\Omega_s t}$$

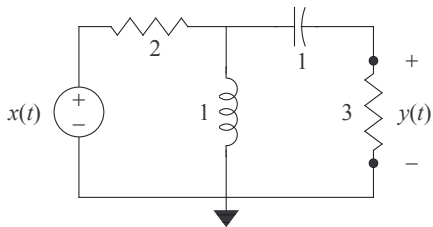
Fourier series: heuristic (does not converge)

Impulse Sampling in Frequency Domain

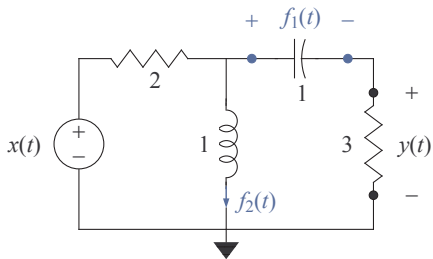


Passive Circuit: State-Space Model

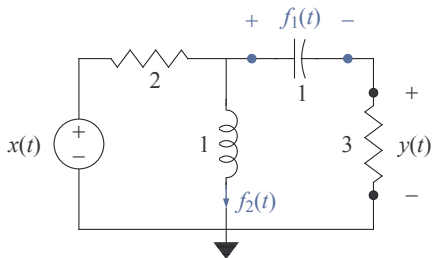
Passive Circuit: State-Space Model



Passive Circuit: State-Space Model

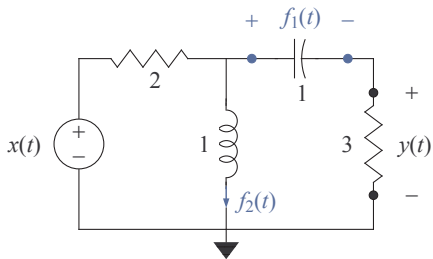


Passive Circuit: State-Space Model



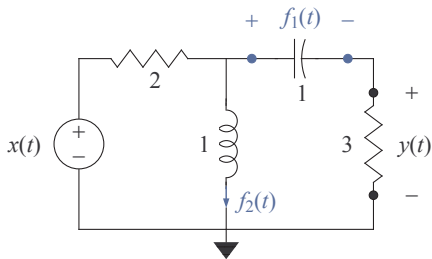
State variables:

Passive Circuit: State-Space Model



State variables: $f_1(t)$ and $f_2(t)$

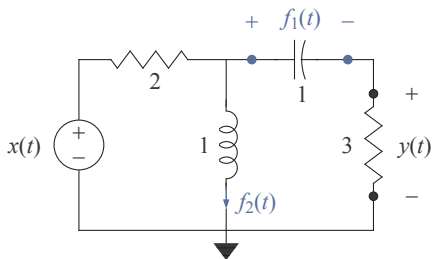
Passive Circuit: State-Space Model



State variables: $f_1(t)$ and $f_2(t)$

State equation:

Passive Circuit: State-Space Model

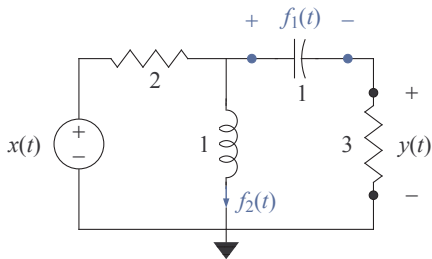


State variables: $f_1(t)$ and $f_2(t)$

State equation:

$$\begin{bmatrix} \dot{f}_1(t) \\ \dot{f}_2(t) \end{bmatrix} =$$

Passive Circuit: State-Space Model

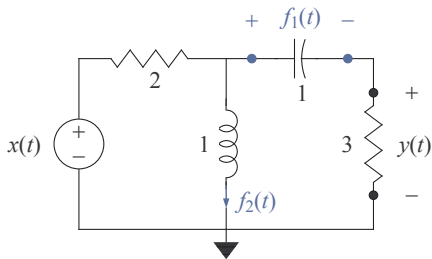


State variables: $f_1(t)$ and $f_2(t)$

State equation:

$$\begin{bmatrix} \dot{f}_1(t) \\ \dot{f}_2(t) \end{bmatrix} = \frac{1}{5} \begin{bmatrix} -1 & -2 \\ 2 & -6 \end{bmatrix} \begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix}$$

Passive Circuit: State-Space Model

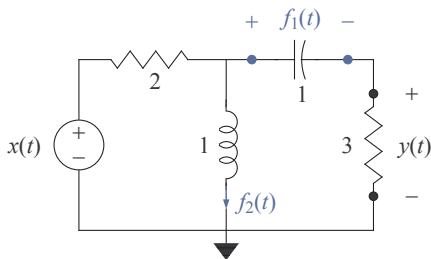


State variables: $f_1(t)$ and $f_2(t)$

State equation:

$$\begin{bmatrix} \dot{f}_1(t) \\ \dot{f}_2(t) \end{bmatrix} = \frac{1}{5} \begin{bmatrix} -1 & -2 \\ 2 & -6 \end{bmatrix} \begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix} + \frac{1}{5} \begin{bmatrix} 1 \\ 3 \end{bmatrix} x(t)$$

Passive Circuit: State-Space Model



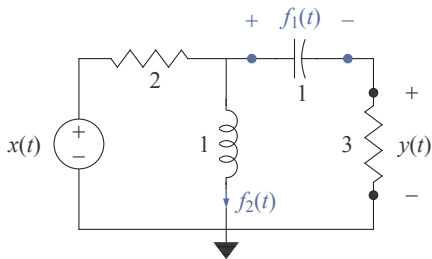
State variables: $f_1(t)$ and $f_2(t)$

State equation:

$$\begin{bmatrix} \dot{f}_1(t) \\ \dot{f}_2(t) \end{bmatrix} = \frac{1}{5} \begin{bmatrix} -1 & -2 \\ 2 & -6 \end{bmatrix} \begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix} + \frac{1}{5} \begin{bmatrix} 1 \\ 3 \end{bmatrix} x(t)$$

Output equation:

Passive Circuit: State-Space Model



State variables: $f_1(t)$ and $f_2(t)$

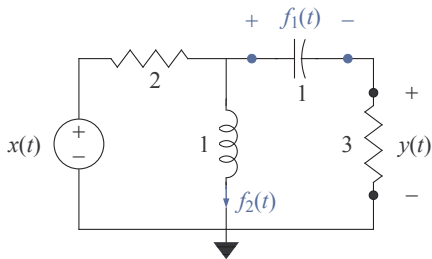
State equation:

$$\begin{bmatrix} \dot{f}_1(t) \\ \dot{f}_2(t) \end{bmatrix} = \frac{1}{5} \begin{bmatrix} -1 & -2 \\ 2 & -6 \end{bmatrix} \begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix} + \frac{1}{5} \begin{bmatrix} 1 \\ 3 \end{bmatrix} x(t)$$

Output equation:

$$y(t) =$$

Passive Circuit: State-Space Model



State variables: $f_1(t)$ and $f_2(t)$

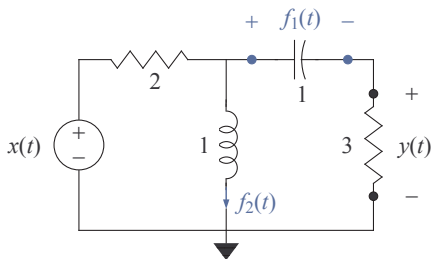
State equation:

$$\begin{bmatrix} \dot{f}_1(t) \\ \dot{f}_2(t) \end{bmatrix} = \frac{1}{5} \begin{bmatrix} -1 & -2 \\ 2 & -6 \end{bmatrix} \begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix} + \frac{1}{5} \begin{bmatrix} 1 \\ 3 \end{bmatrix} x(t)$$

Output equation:

$$y(t) = \frac{3}{5} \begin{bmatrix} -1 & -2 \end{bmatrix} \begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix}$$

Passive Circuit: State-Space Model



State variables: $f_1(t)$ and $f_2(t)$

State equation:

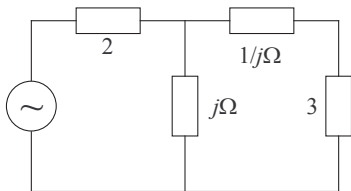
$$\begin{bmatrix} \dot{f}_1(t) \\ \dot{f}_2(t) \end{bmatrix} = \frac{1}{5} \begin{bmatrix} -1 & -2 \\ 2 & -6 \end{bmatrix} \begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix} + \frac{1}{5} \begin{bmatrix} 1 \\ 3 \end{bmatrix} x(t)$$

Output equation:

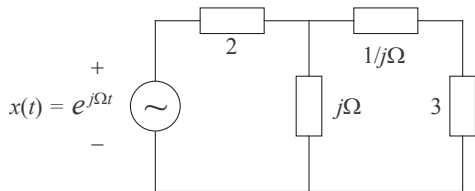
$$y(t) = \frac{3}{5} \begin{bmatrix} -1 & -2 \end{bmatrix} \begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix} + \frac{3}{5} x(t)$$

Passive Circuit: Frequency Response

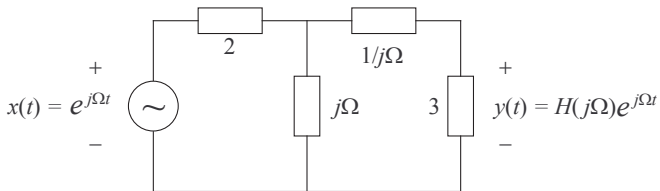
Passive Circuit: Frequency Response



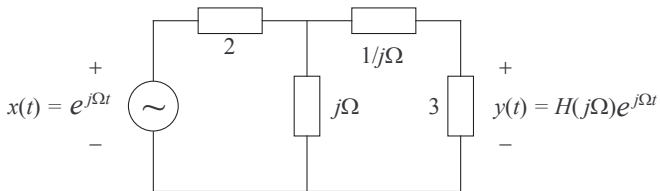
Passive Circuit: Frequency Response



Passive Circuit: Frequency Response

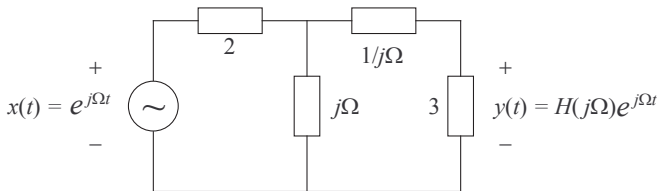


Passive Circuit: Frequency Response



- By AC steady-state analysis:

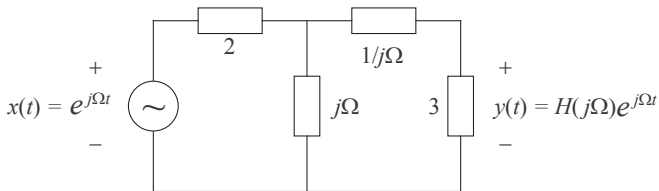
Passive Circuit: Frequency Response



- By AC steady-state analysis:

$$H(j\Omega) = \frac{3(j\Omega)^2}{5(j\Omega)^2 + 7(j\Omega) + 2}$$

Passive Circuit: Frequency Response

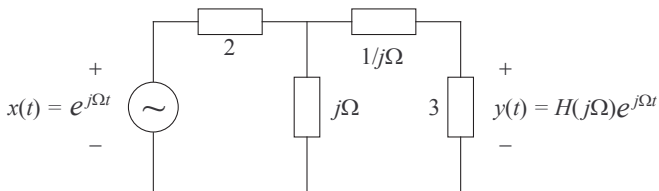


- By AC steady-state analysis:

$$H(j\Omega) = \frac{3(j\Omega)^2}{5(j\Omega)^2 + 7(j\Omega) + 2}$$

▶ $(5(j\Omega)^2 + 7(j\Omega) + 2) \cdot Y(j\Omega) = 3(j\Omega)^2 \cdot X(j\Omega)$

Passive Circuit: Frequency Response



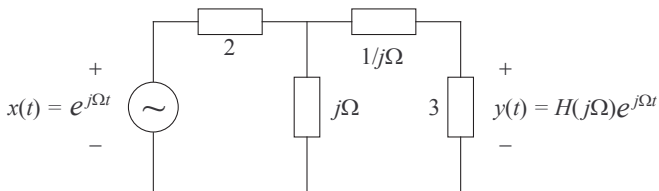
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- By FT time-domain differentiation property:

Passive Circuit: Frequency Response



- By AC steady-state analysis:

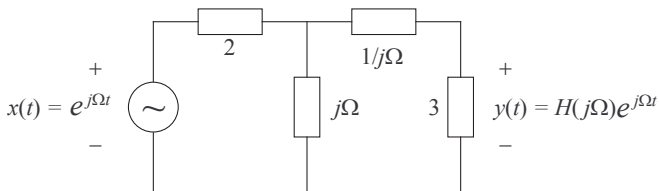
$$H(j\Omega) = \frac{3(j\Omega)^2}{5(j\Omega)^2 + 7(j\Omega) + 2}$$

▶ $(5(j\Omega)^2 + 7(j\Omega) + 2) \cdot Y(j\Omega) = 3(j\Omega)^2 \cdot X(j\Omega)$

- By FT time-domain differentiation property:

$$5\ddot{y}(t) + 7\dot{y}(t) + 2y(t) = 3\ddot{x}(t)$$

Passive Circuit: Frequency Response



- By AC steady-state analysis:

$$H(j\Omega) = \frac{3(j\Omega)^2}{5(j\Omega)^2 + 7(j\Omega) + 2}$$

▶ $(5(j\Omega)^2 + 7(j\Omega) + 2) \cdot Y(j\Omega) = 3(j\Omega)^2 \cdot X(j\Omega)$

- By FT time-domain differentiation property:

$$5\ddot{y}(t) + 7\dot{y}(t) + 2y(t) = 3\ddot{x}(t)$$

▶ $h(t) = \frac{3}{5}\delta(t) - e^{-t} + \frac{4}{25}e^{-2t/5}$