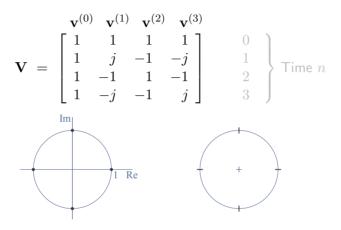
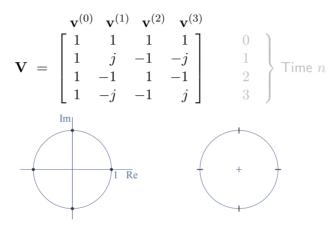
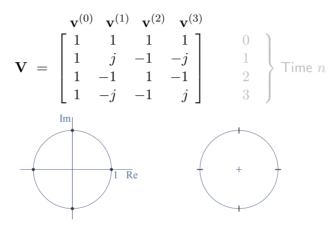
$v^{(0)} v^{(1)} v^{(2)} v^{(3)}$

$$\mathbf{V} = \begin{bmatrix} \mathbf{v}^{(0)} & \mathbf{v}^{(1)} & \mathbf{v}^{(2)} & \mathbf{v}^{(3)} \\ 1 & 1 & 1 & 1 \\ 1 & j & -1 & -j \\ 1 & -1 & 1 & -1 \\ 1 & -j & -1 & j \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix}$$
 Time *n*

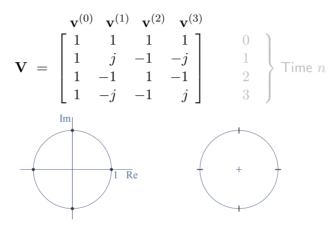




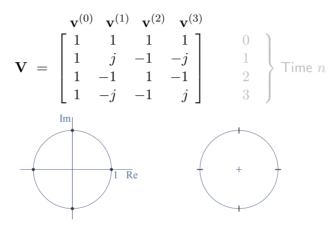
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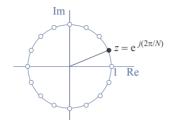
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$$\omega_k = k \cdot \pi/2$$

The $N \times N$ Matrix \mathbf{V}

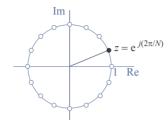


1. What is the smallest vector length N for which both

$$\omega = \frac{7\pi}{12}$$
 and $\omega' = \frac{11\pi}{28}$

are Fourier (DFT) frequencies?

- **A**. 77
- **B**. 84
- **C**. 168
- **D**. 336

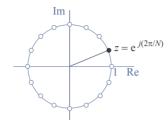


$$V_{nk} = v^{(k)}[n] = z^{kn}$$

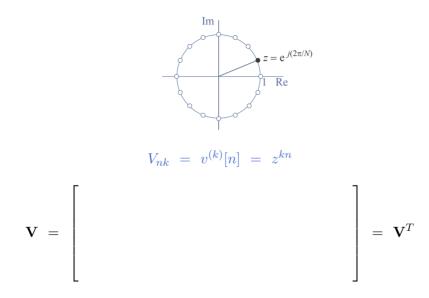
2. What is the smallest vector length N such that the $N \times N$ matrix V of Fourier sinusoids contains the entry

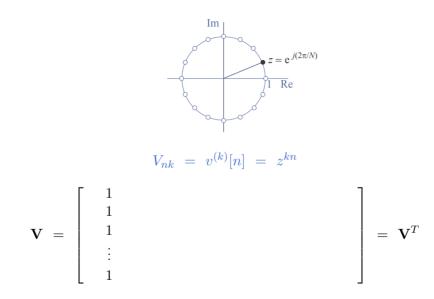
$$-\frac{\sqrt{3}}{2}+\frac{j}{2}$$
 ?

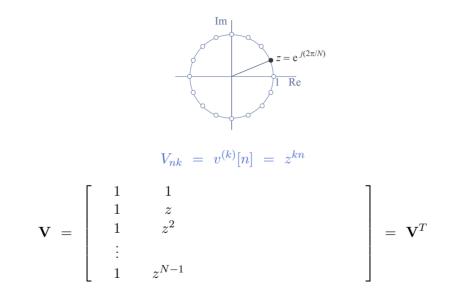


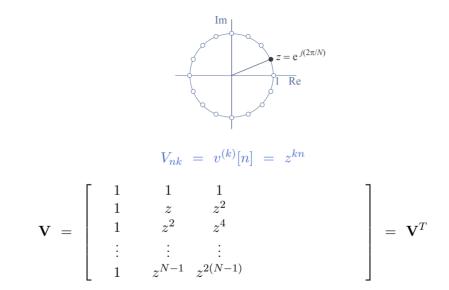


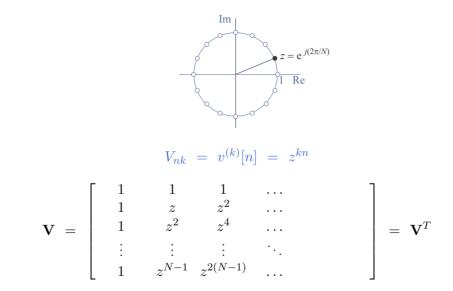
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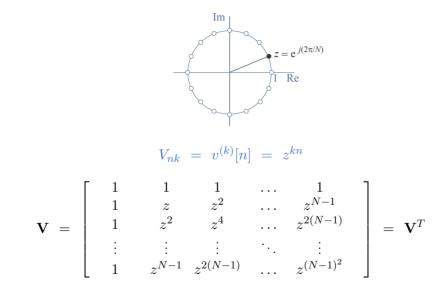


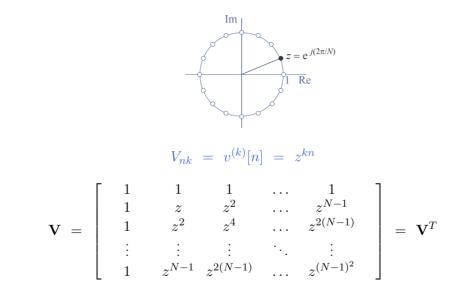




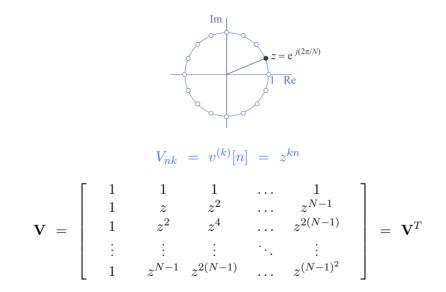




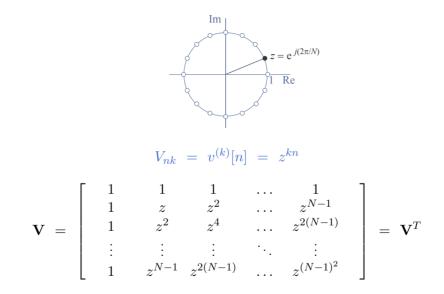




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$$\mathbf{V}^H \mathbf{V} = N \mathbf{I}$$



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, where $c_k = \frac{\langle \mathbf{v}^{(k)}, \mathbf{s} \rangle}{N}$

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3. If $s = \begin{bmatrix} 7 & -2 & 3 & -1 & 4 & 5 \end{bmatrix}^T$ has DFT S[0:5], then S[3] equals A. 12 B. 16 C. $1 + j(3\sqrt{3})$ D. $1 - j(3\sqrt{3})$ 4. Let $\mathbf{x} = x_{0:7}$. Which of the following entries in the DFT X is given by

$$x_0 + jx_1 - x_2 - jx_3 + x_4 + jx_5 - x_6 - jx_7$$
?

- A. X[1]
- **B**. *X*[2]
- $\mathsf{C}. \quad X[6]$
- $\mathsf{D}. \quad X[7]$

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5. The signal vector $\mathbf{x} = x[0:15]$ is given by the formula

$$x[n] = \cos(5\pi n/8), \qquad n = 0, \dots, 15$$

How many zeros does the DFT vector $\mathbf X$ contain?

- A. None
- B. One
- C. Fourteeen
- D. Fifteen

- B. X contains information about the amplitude and phase of standard sinusoidal vectors which, when summed together, produce the signal vector \mathbf{x} .
- C. If one of the entries of the DFT ${\bf X}$ is zero, then ${\bf x}$ must also contain (at least) one zero entry.
- D. If \mathbf{x} is real-valued, then so is \mathbf{X} .

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