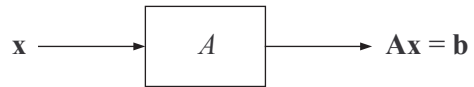
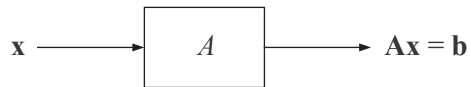


Invertible Matrices

Invertible Matrices

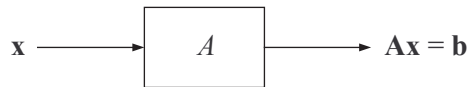


Invertible Matrices



$$a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1$$

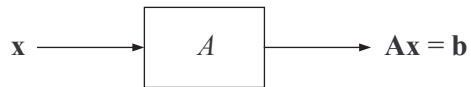
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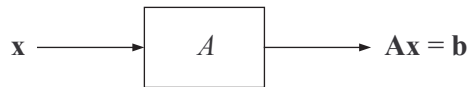


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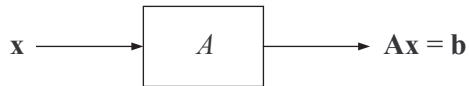
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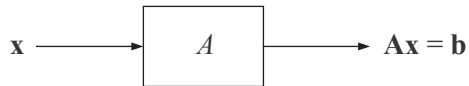
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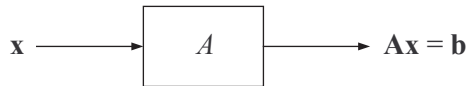
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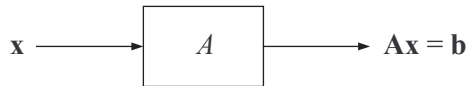
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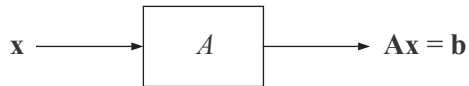
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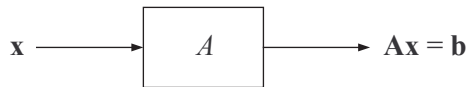
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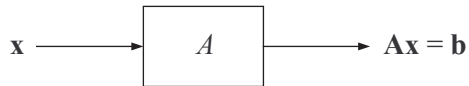
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Only **square** matrices ($m = n$) can be invertible.

1. Which (one or more) of the following statements about the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & -2 \\ 3 & -6 \end{bmatrix}$$

are correct?

- (i) The equation $\mathbf{Ax} = \mathbf{b}$, where $\mathbf{b} = [1 \ 0]^T$, has a unique solution.
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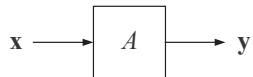
Key Identities on Matrix Inverse

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Assuming \mathbf{A} is invertible:

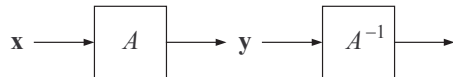
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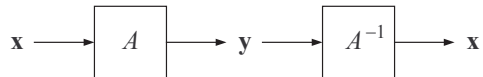
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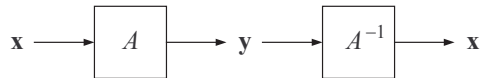
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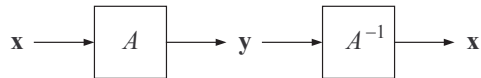
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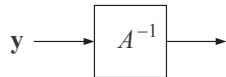
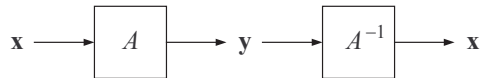
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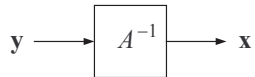
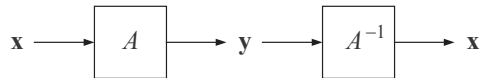
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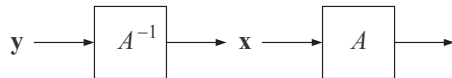
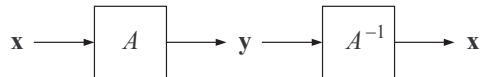
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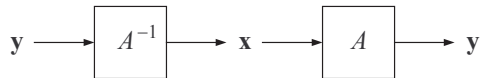
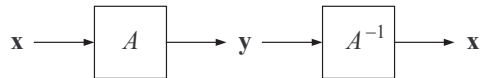
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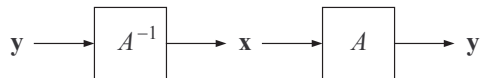
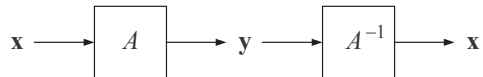
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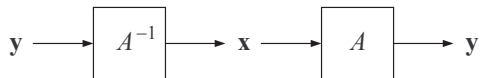
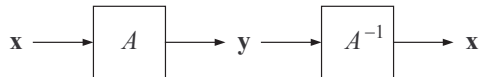


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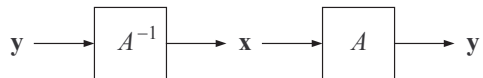
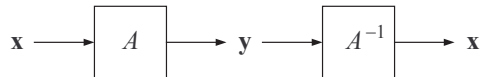


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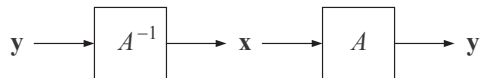
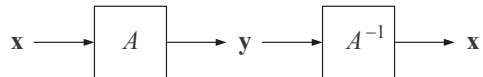


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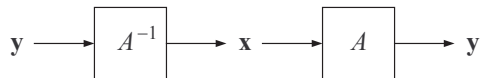
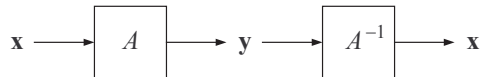


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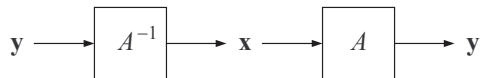
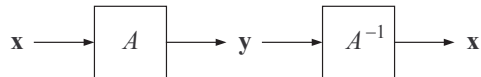


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- $\mathbf{A}\mathbf{B} = \mathbf{I} \Leftrightarrow \mathbf{A}$ and \mathbf{B} are inverses of each other

2. The matrix

$$\mathbf{A} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

represents counterclockwise rotation by angle θ on the Cartesian plane.

Determine \mathbf{A}^{-1} .

3. If

$$\mathbf{A} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{and} \quad \mathbf{A} \begin{bmatrix} -1 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix},$$

then $\mathbf{A}^{-1} =$

4. Given

$$\mathbf{L} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ -1 & -1 & 1 & 0 \\ -1 & -1 & -1 & 1 \end{bmatrix} \quad \text{and} \quad \mathbf{L}^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 2 & 1 & 1 & 0 \\ c & 2 & 1 & 1 \end{bmatrix},$$

what is the value of c ?

(i) 0

(ii) 3

(iii) 4

(iv) -3

Product and Transpose

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From L8.2 4 :

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- $(\mathbf{AB})^T = \mathbf{B}^T \mathbf{A}^T$

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Product and Transpose

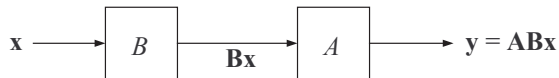
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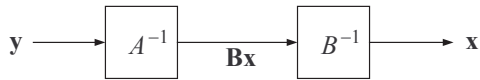
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5.

$$\text{If } \begin{bmatrix} a & 0 & 0 \\ b & d & 0 \\ c & e & f \end{bmatrix}^{-1} = \begin{bmatrix} p & 0 & 0 \\ q & s & 0 \\ r & t & u \end{bmatrix}, \text{ then}$$

$$\begin{bmatrix} f & 0 & 0 \\ c & b & a \\ e & d & 0 \end{bmatrix}^{-1} =$$

Triangular Matrices

Triangular Matrices

$$\mathbf{L} = \begin{bmatrix} \text{shaded triangle} & 0 \\ & \ddots \\ & & \text{shaded triangle} \end{bmatrix}$$

$$\mathbf{U} = \begin{bmatrix} \text{shaded triangle} & & \\ & \ddots & \\ & & \text{shaded triangle} \\ 0 & & & \text{shaded triangle} \end{bmatrix}$$

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$$\mathbf{Lx} = \mathbf{b} \quad \Leftrightarrow$$

Triangular Matrices

$$\mathbf{L} = \begin{bmatrix} \text{shaded} & & & & \\ \text{shaded} & \text{shaded} & & & \\ \text{shaded} & \text{shaded} & \text{shaded} & & \\ \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \\ \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} \\ & & & & & & 0 \end{bmatrix}$$

$$\mathbf{U} = \begin{bmatrix} \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} \\ \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} \\ \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} \\ \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} \\ \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} \\ \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} \\ \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} \\ & & & & & & & & 0 \end{bmatrix}$$

$$\mathbf{L}\mathbf{x} = \mathbf{b} \quad \Leftrightarrow \quad \begin{cases} \ell_{11}x_1 & & & = & b_1 \\ \ell_{21}x_1 + \ell_{22}x_2 & & & = & b_2 \\ \vdots & \vdots & \ddots & & \vdots \\ \ell_{m1}x_1 + \ell_{m2}x_2 + \cdots + \ell_{mm}x_m & & & = & b_m \end{cases}$$

Triangular Matrices

$$\mathbf{L} = \begin{bmatrix} \color{gray} & & & & \\ \color{gray} & \color{gray} & & & \\ \color{gray} & \color{gray} & \color{gray} & & \\ \color{gray} & \color{gray} & \color{gray} & \color{gray} & \\ \color{gray} & \color{gray} & \color{gray} & \color{gray} & \color{gray} \\ & & & & 0 \end{bmatrix}$$

$$\mathbf{U} = \begin{bmatrix} \color{gray} & \color{gray} & \color{gray} & \color{gray} & \color{gray} \\ \color{gray} & \color{gray} & \color{gray} & \color{gray} & \color{gray} \\ \color{gray} & \color{gray} & \color{gray} & \color{gray} & \color{gray} \\ \color{gray} & \color{gray} & \color{gray} & \color{gray} & \color{gray} \\ \color{gray} & \color{gray} & \color{gray} & \color{gray} & \color{gray} \\ 0 & & & & \color{gray} \end{bmatrix}$$

$$\mathbf{L}\mathbf{x} = \mathbf{b} \quad \Leftrightarrow \quad \begin{cases} \ell_{11}x_1 & & & & = & b_1 \\ \ell_{21}x_1 + \ell_{22}x_2 & & & & = & b_2 \\ \vdots & \vdots & \ddots & & & \vdots \\ \ell_{m1}x_1 + \ell_{m2}x_2 + \cdots + \ell_{mm}x_m & & & & = & b_m \end{cases}$$

Solved by [forward substitution](#):

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Solution exists and is unique (i.e., \mathbf{L} is invertible) if and only if $\ell_{ii} \neq 0$ for all i .

Solution of $\mathbf{Ax} = \mathbf{b}$ by Gaussian Elimination

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Invertibility (or not) of \mathbf{A} is established during forward elimination.

6 and 7. Forward phase of Gaussian elimination:

m	x_1	x_2	x_3	b
	4	5	2	12
-1	4	7	-2	4
c	3	3	2	9
	4	5	2	12
	0	2	-4	-8
$3/8$	0	$-3/4$	$1/2$	0

Determine the value of c and the solution (x_1, x_2, x_3) .