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ENEE 350 Homework Set No. 4
(Due: Class 13, Mon., Feb. 25, 2008)

1. Read textbook Chapt. 3 and work the following problems:
 - a. Problem 3-23.
 - b. Problem 3-24.
 - c. Problem 3-25.
 - d. Problem 3-28.
 - e. Problem 3-30.
 - f. Problem 3-31.
 - g. Problem 3-32.
 - h. Problem 3-42.
2. Print out and read the notes on an example microprogrammed microarchitecture. These notes are entitled "Microarch.ps" or "Microarch.pdf" in the Notes subdirectory of the course webpage, and they describe a microarchitecture called the Mic-1 that by way of microprogramming implements an instruction set architecture (or macroarchitecture) called the Mac-1. Then do the following.

- (1) Log into a Glue workstation.
- (2) Type "tap ee350" (without the quotes, of course)
- (3) Copy the two files halt and halt.pascal to your working directory:

```
‘‘cp $EE350/halt .’’  
‘‘cp $EE350/halt.pascal .’’
```

- (4) Then print out these two files:

```
‘‘qpr -q <your favorite printer> halt’’  
‘‘qpr -q <your favorite printer> halt.pascal’’
```

- (5) Keep the listings themselves for your reference.

In problems 3 through 8 below assume that new OP Codes have been assigned for some new MAC-1 machine instructions and that these instructions have been fetched into the IR during an instruction fetch cycle, that they have been completely decoded, and that a microprogram jump has occurred to the control store starting address for their execution sequences. Write the MAL routines that accomplish execution of each of these new MAC-1 instructions. Execution is complete when an unconditional transfer of control back to the start of the instruction fetch sequence occurs.

3. Implement execution of the machine instruction:

CALNZ x

which calls subroutine (procedure) x if the content of the accumulator (ac) is NOT equal to zero. Assume that this microinstruction sequence starts at control memory address 100 and that locations above 100 are available for your use.

4. Implement execution of the machine instruction:

Mnemonic	Meaning
JSR x	$m[x] := pc; pc := x+1$

where JSR stands for “Jump to subroutine” (with entry point at main memory address x specified in the address field of the instruction). It differs from the subroutine call instruction in that it stores the return address (the content of the program counter) in location x (the first location in the subroutine) and jumps to location $x+1$ rather than storing the return address on the stack. Assume that this microinstruction sequence starts at control memory address 120 and that locations above 120 are available for your use.

5. Implement execution of the machine instruction:

RAR

Assume that the sequence of microinstructions to execute a new Mac-1 conventional machine language instruction “RAR” starts in address 150 of control store and that all control store locations > 150 are free and available for your use. RAR stands for “rotate accumulator right” which does a one bit position right circular shift of the bits in the 16-bit ac register specified by the following, where the bit positions in the ac register are numbered right to left in their natural powers of two order from 0 to 15: For $i = 0, 1, \dots, 14$, bit $ac_i := ac_{i+1}$; and $ac_{15} := ac_0$.

6. Implement execution of the machine instruction:

ASHR

Assume that the sequence of microinstructions to execute a new Mac-1 conventional machine language instruction “ASHR” starts in address 160 of control store and that all control store locations > 160 are free and available for your use. ASHR stands for “arithmetic shift right the accumulator” which does a one bit position arithmetic (i.e., algebraic) right shift of the bits in the 16-bit ac register specified by the following, where again the bit positions in the ac register are numbered right to left in their natural powers of two order from 0 to 15: For $i = 0, 1, \dots, 14$, bit $ac_i := ac_{i+1}$; and $ac_{15} := ac_{15}$.

7. Implement execution of the machine instruction:

ACTOE

which transfers (i.e., copies) the contents of the AC register into the E register. Assume control store locations 170 and above 170 are available for this.

8. Implement execution of the looping control instruction:

JGDE x

which first checks the contents of register E, and if the content of E is strictly greater than zero, then jumps to memory address “x”; if the content of E is not strictly greater than zero, then no jump is taken (i.e., the execution cycle terminates by going directly to the instruction fetch cycle); in either case the content of register E is decremented by one (i.e., 1 is subtracted from the contents of register E).