

## Classification of controllable pairs $[A, B]$ .

Let  $n \geq 1, m \geq 1$  be fixed. Let

$\Sigma_{n,m}$  denote all possible pairs of matrices  $[A, B]$ . Clearly this is a vector space of dimension  $n^2 + nm$ .

A pair  $[A, B]$  is uncontrollable iff

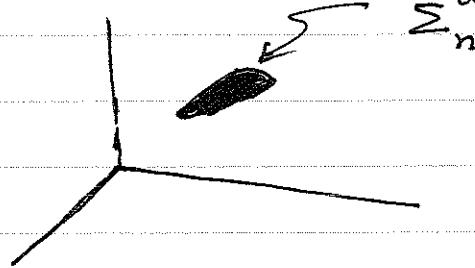
$$\det \left( \sum_{k=0}^{n-1} A^k B B^T A^T{}^k \right) = 0.$$

A pair  $[A, B]$  is controllable iff

$$\det \left( \sum_{k=0}^{n-1} A^k B B^T A^T{}^k \right) > 0.$$

Thus  $\Sigma_{n,m}$  breaks up into two disjoint pieces  $\Sigma_{n,m}^{uc}$  the uncontrollable systems and  $\Sigma_{n,m}^c$  of the controllable systems.

The piece  $\Sigma_{n,m}^{uc}$  is a "thin set" since it satisfies an algebraic condition of a vanishing determinant.



This picture illustrates that what is outside

the dark, thin blob  $\sum_{n,m}^{uc}$ , makes up  
the controllable systems.

We are interested in showing  
that  $\sum_{n,m}^c$  falls into a finite number  
of disjoint regions (also called  
equivalence classes, orbits etc.)  
such that if  $[A, B]$  and  $[\tilde{A}, \tilde{B}]$   
belong to the same region, then  
there is a combination of transformation  
of the form

$$(i) [A, B] \mapsto [PAP^{-1}, PB]$$

P  $n \times n$  invertible

change  
of basis  
in state space

$$(ii) [A, B] \mapsto [A + BK, B]$$

K  $m \times n$

state  
feedback

$$(iii) [A, B] \mapsto [A, BQ]$$

Q  $m \times m$  invertible

change  
of basis  
in input  
space

that take  $[A, B]$  into  $[\tilde{A}, \tilde{B}]$ .

They constitute the feedback group.

An example of such a combination is

$$[A, B] \mapsto [PAP^{-1} + PBK, PBQ].$$

Each of the transformations can be undone (relevant inverses exist). Hence,  $[A, B]$  and  $[\tilde{A}, \tilde{B}]$  are equivalent if they each can be transformed into a standard or canonical form.

For instance, when  $m=1$ ,

any two controllable pairs in  $\Sigma_{n,1}^c$ ,

$[A, b]$  and  $[\tilde{A}, \tilde{b}]$ , can be transformed under the feedback group into the canonical form

$$A_c = \begin{bmatrix} 0 & 1 & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad b_c = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

We saw this earlier under the setting

(4)

of single-input system eigenvalue placement theorem.

Note : We did not make use of change basis in input space for  $m=1$ , since in that case it is subsumed by the special case of change of basis in state space with

$$P = q \mathbb{I} \quad q \neq 0$$

Since,

$$[(q \mathbb{I}) A (q \mathbb{I})^{-1}, (q \mathbb{I}) b]$$

$$= [A, bq]$$

In the multi-input setting the change of basis in input space really makes a difference.

Finding invariants under feedback group

$$\text{Let } L_j = \text{im } [B \ AB \ \dots \ A^j B]$$

= linear subspace of  $\mathbb{R}^n$  spanned by columns of  $[B \ AB \ \dots \ A^j B]$ .

(5)

By hypothesis  $L_{n-1} = \mathbb{R}^n$  (controllability)

Clearly

$$\text{im}(B) = L_0 \subseteq L_1 \subseteq L_2 \dots \subseteq L_{n-1} = \mathbb{R}^n$$

Let  $\mathbb{R}^n$  be given an inner product,  
say Euclidean inner product.

Let  $\Lambda_j$  = orthogonal complement  
of  $L_{j-1}$  in  $L_j$

$$= \{v \in L_j : \langle v, w \rangle = 0 \quad \forall w \in L_{j-1}\}$$

Here  $\langle v, w \rangle$  = inner product of  $v$  and  $w$ .

Then

$$L_j = L_{j-1} \oplus \Lambda_j$$

↑  
direct sum of orthogonal  
vectors

$$\mathbb{R}^n = L_0 \oplus \Lambda_1 \oplus \Lambda_2 \oplus \Lambda_3 \dots \oplus \Lambda_{n-1}$$

~~scribble~~

$$\begin{aligned} \text{Let } r_0 &= \dim L_0 = \text{rank}(B) \\ r_j &= \dim(L_j) - \dim(L_{j-1}) \\ &= \dim(\Lambda_j) \quad j=1, 2, \dots, n-1 \end{aligned}$$

Clearly  $r_0 + r_1 + r_2 + \dots + r_{n-1} = n$ .

(6)

Clearly  $r_0 > 0$  and  $r_0 \leq m$ .

Clearly  $r_j \leq m$  for  $j \leq n-1$

By re-ordering the columns of  $B$ , equivalently, right multiplying  $B$  by a suitable nonsingular  $\alpha$ , we can be sure that columns 1 through  $r_0$  of  $B$  are linearly independent. They constitute a basis for  $L_0$ .

Create the following Young diagram

	1	2		$r_0$	
$b_j$	x	x	x	x	x
$Ab_j$	x	x	x		
	x		x		
	x				
$n-1$					

with  $r_0$  columns and  $n$  rows.

Fill first row with crosses,  $r_0$  in number to mark selection of columns 1 through  $r_0$  of  $B$  as basis of  $L_0$ .

Mark a cross in second row in  $j^{\text{th}}$  place only if  $Ab_j$  is linearly independent of all vectors  $b_1, b_2, \dots, b_{r_0}, Ab_1, \dots, Ab_{r_0-1}$ . Total # crosses in second row

$$= r_1 = \dim(L_1) = \dim L_1 - \dim L_0.$$

In  $i^{\text{th}}$  row mark a cross in  $j^{\text{th}}$  place only if  $A^i b_j$  is linearly independent of all vectors  $b_1, b_2, \dots, b_{r_0}, Ab_1, \dots, Ab_{r_0}, \dots, A^i b_1, \dots, A^i b_{j-1}$ .

(7)

It follows that

$$r_0 \geq r_1 \geq r_2 \cdots \geq r_{n-1}$$

We have picked basis  $S$  (by marking crosses) of vectors  $A^i b_i$  with the property that if  $A^i b_i \notin S$  then  $A^{i+l} b_i \notin S$  for  $l > 0$ .

We now associate with every  $b_i$  a number  $\kappa_i$  such that  $A^i b_i \in S$  for  $0 \leq j \leq \kappa_i - 1$  but  $A^{\kappa_i} b_i \notin S$ . Again by re-ordering the  $\frac{r_0}{\text{first } r_0}$  columns of  $B$ , we can achieve

$$\kappa_1 \geq \kappa_2 \geq \cdots \geq \kappa_{r_0}.$$

But  $\kappa_i$ 's are simply column sums

of the number of crosses. Hence

$$\sum_{i=1}^{r_0} \kappa_i = \sum_{j=0}^{n-1} r_j = n.$$

Sequence  $\kappa_1, \kappa_2, \dots, \kappa_{r_0}$  defines a partition of the integer  $n$ .

Remark (i)  $\kappa_i$ 's determine  $r_j$ 's and vice-versa

X	X	X	X
X	XX		
X			

(ii)

After reordering in  $B$ ,  
 $\{A^j b_i : 1 \leq i \leq r_0, 0 \leq j \leq \kappa_i - 1\}$

Young diagram

is a basis for  $\mathbb{R}^n$ .

(iii) under  $[A, B] \rightarrow [PAP^{-1}, PB]$

$$L_j \rightarrow PL_j \text{ so}$$

list  $r_0, \dots, r_{n-1}$  is invariant,  
and hence  $x_0, \dots, x_{r_0}$  ordered  
list of  $x$ 's is also invariant.

(iv) under  $[A, B] \rightarrow [A, BQ]$

$L_i \rightarrow L_i$  so remarks  
as in (iii) apply regarding  
invariance -

(v)  $[A, B] \rightarrow [A+BK, B]$

$$(A+BK)^j = A^j B + G^j$$

where  $G$  is a matrix whose  
columns are contained in  $L_{j-1}$

Hence  $L_j$  invariant under  $A \mapsto A+BK$

...  $r_g, x_i$  invariant.

## Canonical form

1. Write down pyramidal basis

$$S = \{ b_i, \dots, A^{K_j-1} b_i, \dots \mid i \in M' \} \text{ for } \mathbb{R}^n.$$

$M' = \{1, 2, \dots, m\}$  containing exactly  $r_s = \text{rank}(B)$  elements

Linear dependence relations:

$$A^{K_j} b_i = - \sum_{j \in M'} \sum_{k=1}^{K_j-1} \alpha_{ijk} A^k b_j \quad * \quad i \in M'$$

determine unique coefficients  $\alpha_{ijk}$

2. New basis

$$e_{j1} = b_j$$

$$e_{j2} = A b_j + \alpha_{j1j} b_j$$

$$\vdots \quad e_{jK_j} = A^{K_j-1} b_j + \alpha_{j1j} A^{K_j-2} b_j + \dots + \alpha_{j, K_j-1} b_j \quad j \in M'$$

Direct calculation shows that in this new basis A and B take canonical forms

$$A = \left[ \begin{array}{cccc|cc|cc} 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ \hline x & x & x & x & x & x & x & x \\ \hline 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ \hline x & x & x & x & x & x & x & x \end{array} \right] \quad \begin{matrix} \overbrace{\hspace{1cm}}^{K_1 \text{ col}} & \overbrace{\hspace{1cm}}^{K_2 \text{ row}} \\ \end{matrix} \quad \begin{matrix} \} K_1 \text{ rows} \\ \} K_2 \text{ rows} \end{matrix}$$

$$B = \left[ \begin{array}{c|cc} 0 & 0 & 0 & x & x \\ \vdots & 0 & 0 & x & x \\ 0 & 0 & \vdots & x & x \\ \hline 1 & 0 & \vdots & x & x \\ 1 & 0 & \vdots & x & x \\ \hline 0 & 0 & x & x & x \\ \vdots & 1 & x & x & x \\ 0 & 0 & \vdots & x & x \\ \hline 1 & 1 & 1 & x & x \end{array} \right] \quad \begin{matrix} \overbrace{\hspace{1cm}}^{r_0 \text{ columns}} \\ \end{matrix} \quad \begin{matrix} \} K_1 \text{ rows} \\ \} K_2 \text{ rows} \end{matrix}$$

The elements marked  $x$  in  $A$  are given by  $d_{ijk}$ . The last  $(m - r_0)$  columns of  $B$  are linearly dependent on the first  $r_0$  columns.

By applying another  $B \rightarrow BQ$  we can make last  $(m - r_0)$  columns equal to 0.

By now applying feedback  $A \mapsto A + BK$  with appropriate rows of  $K$  containing  $-d_{ijk}$  we can kill off all crosses in  $A$ . We have,

Theorem [Brouwer]

$[A, B] \in \sum_{n,m}^c$ . Then there exist positive integers  $k_1, k_2, \dots, k_{r_0}$  uniquely determined by  $[A, B]$  such that  $[A, B]$  is equivalent under the feedback group to  $[A_0, B_0]$  where

$$A_0 = \text{diag}(E_{k_1}, E_{k_2}, \dots, E_{k_{r_0}})$$

$$B_0 = \begin{bmatrix} e_{k_1} & e_{k_2+x_1} & \cdots & e_{k_j+k_{j-1}+\cdots+k_1} & \cdots & e_n & | & 0 \\ \uparrow & \uparrow & & & & & & \uparrow \\ \text{column } 1 & 2 & & & & & & \text{column } r_0 \end{bmatrix}$$

$$E_x = \begin{pmatrix} 0 & 1 & 0 \\ \vdots & \ddots & \vdots \\ 0 & 0 & 1 \end{pmatrix}_{r_0 \times r_0}$$

Since there are finitely partitions, there are finitely many classes