

1. Obtain a reachability condition analogous to those given in Theorem (page 4, Lecture (3b)) for the matrix system

$$\dot{X}(t) = A(t)X(t) + X(t)B(t) + C(t)U(t)D(t)$$

where X is a square matrix of size $n \times n$, A, B are square matrices and the remaining matrices are of compatible sizes.

2. Let $Q = Q^T$ be a positive definite matrix. When is the linear time-invariant system

$$\begin{bmatrix} \dot{x}_1(t) \\ \dot{x}_2(t) \end{bmatrix} = \begin{bmatrix} 0 & Q \\ -Q & 0 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} 0 \\ B \end{bmatrix} u(t)$$

controllable?

3. Given the time-invariant system

$$\dot{x} = Ax + bu \quad x(0) = 0,$$

and the constraint $u(t + \frac{1}{2}) = u(t)$

show that it is possible to select a control u such that $x(1) = x_1$ if and only if there exists a vector η such that

$$\left(e^{\frac{A}{2}} + I \right) (b, Ab, \dots, A^{n-1}b) \eta = x_1$$

2. Show that the inverse of the Gramian $W(t, t_1)$, if it exists, satisfies the nonlinear differential equation

$$\begin{aligned} \frac{d}{dt} P(t) = & -A^T(t) P(t) - P(t) A(t) \\ & + P(t) B(t) B^T(t) P(t) \end{aligned}$$

on the interval $[t_0, t_1]$ with terminal condition

$$\begin{aligned} P(t_1) &= W(t, t_1) \Big|_{t=t_1} \\ &= 0 \end{aligned}$$